

Conformal prediction for surrogate modelling in the UQ framework

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- 1 Problem formulation
- 2 Conformal prediction (CP) paradigm
- 3 Gaussian Process Regression (GPR) surrogates
- 4 Adapting CP to GPR
- 5 Conclusion

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- For a computer code $g : \mathcal{X} \rightarrow \mathcal{Y}$ used in industrial applications, the Uncertainty Quantification (UQ) methodology aims at evaluating how uncertainty on the inputs $X \in \mathcal{X}$ affects our knowledge of the output $g(X) \in \mathcal{Y}$ [De Rocquigny et al., 2008].

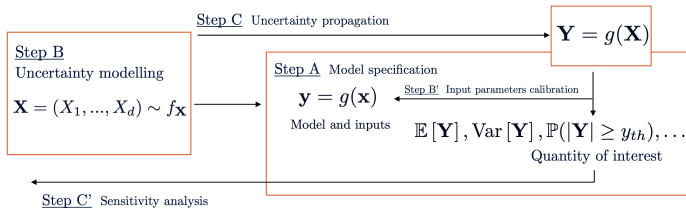


Figure – General UQ methodology.

- Since these codes are time-costly, surrogates \tilde{g} are constructed for performing heavy simulations like Monte-Carlo batch runs for Step C, C'.
- For objective reasons, one needs to assess the *quality* of these surrogates.
- We propose to use the Conformal prediction paradigm [Vovk et al., 2005] which is a generic, model-agnostic theory allowing to build *prediction* sets to these surrogates with frequentist coverage guarantees.

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General CP in regression

The Jackknife+/minmax estimator

CV+/minmax estimator

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[Vovk et al., 2005]. We fix a probability space $(\Omega, \mathcal{F}, \mathbb{P})$.

Definition

Let \mathcal{X}, \mathcal{Y} be metric spaces and $\mathcal{Z} = \mathcal{X} \times \mathcal{Y}$. Let $n \in \mathbb{N}$ and $\mathcal{D} = \{Z_1, \dots, Z_n\} \in 2^{\mathcal{Z}}$ a training sample. For $\alpha \in (0, 1)$ a conformal predictor of coverage α is any measurable function of the form :

$$C_\alpha: 2^{\mathcal{Z}} \times \mathcal{X} \rightarrow 2^{\mathcal{Y}} \quad (1)$$

$$(\mathcal{D}, X) \mapsto C_{n,\alpha}(X),$$

such that for a new point $Z_{n+1} = (X_{n+1}, Y_{n+1}) \in \mathcal{Z}$:

$$\mathbb{P}(Y_{n+1} \in C_{n,\alpha}(X_{n+1})) \geq 1 - \alpha. \quad (2)$$

Three main methods exist to estimate these set-functions : full-conformal, split-conformal and cross-conformal estimators. We focus on the latter.

Full-Conformalized Ridge Regression (CRR)

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[Vovk et al., 2005] A non-conformity score is any measurable function of the form :

$$A: 2^{\mathcal{Z}} \times \mathcal{Z} \rightarrow \overline{\mathbb{R}} \\ (\mathcal{D}, Z) \mapsto A(\mathcal{D}, Z). \quad (3)$$

Assume $\mathcal{X} = \mathcal{Y} = \mathbb{R}$ and $R_{\mathcal{D}}$ a regression rule learned on $\mathcal{D} = \{Z_1, \dots, Z_n\} = \{(X_1, Y_1), \dots, (X_n, Y_n)\}$. A straightforward non-conformity score is given by the difference between prediction and actual value, for all $i = 1, \dots, n$:

$$A(\mathcal{D}, Z_i) = Y_i - R_{\mathcal{D}}(X_i) = Y_i - \hat{Y}_i \quad (4)$$

Full-Conformalized Ridge Regression (CRR)

For a new input $X_{n+1} \in \mathcal{X}$ and output $Y \in \mathcal{Y}$, we denote by $\tilde{\mathcal{D}} := \mathcal{D} \sqcup (X_{n+1}, Y)$. The full conformal predictor is given for all confidence level $0 < \alpha < 1$ by :

$$\hat{C}_{n,\alpha}^{CRR}(X_{n+1}) = \left\{ Y \in \mathcal{Y} : \frac{\#\{i : A(\tilde{\mathcal{D}}, Z_i) \geq A(\tilde{\mathcal{D}}, (X_{n+1}, Y))\}}{n} > \alpha \right\}.$$

- This estimator is based on the "dissimilarity" of the new pair inside the updated dataset. It achieves the required coverage property.
- It is computationally intractable due to the full grid search on the label space \mathcal{Y} .
- To tackle this, more advanced estimators are proposed in the following.
- In the rest of this talk we suppose that $Y = g(X)$ where g is some deterministic function (e.g a numerical simulation code).

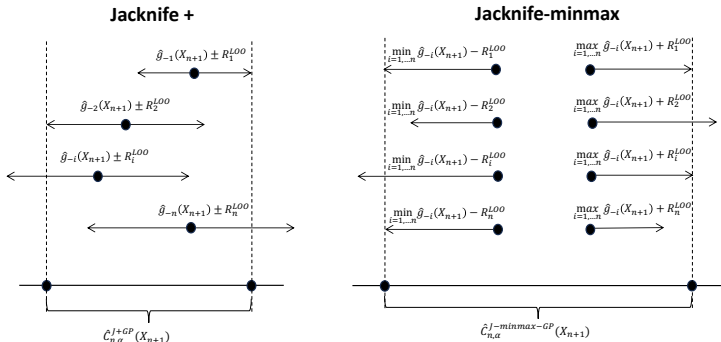
- Let $K \in \{1, \dots, n\}$. We divide $\mathcal{D}^{\text{train}}$ in K -disjoint subsets $S_1 \cup \dots \cup S_K$.
- We fit K metamodels with the k -th fold removed : \hat{g}_{-S_k} .
- We compute the conformity scores :

$$R_i^{\text{CV}} := |g(X_i) - \hat{g}_{-S_{k(i)}}(X_i)|, \quad \forall i \in \{1, \dots, n\}, \quad (7)$$

where $S_{k(i)}$ is the fold containing X_i .

- We estimate our prediction intervals :

$$\hat{C}_{n,\alpha}^{\text{CV}+}(X_{n+1}) = \left[\hat{q}_{n,\alpha}^{\pm} \left\{ \hat{g}_{-S_{k(i)}}(X_{n+1}) \pm R_i^{\text{CV}} \right\} \right] \quad (8)$$



Additionally, we can add minmax on both the J+ and the CV+ methods by replacing the metamodel prediction with :

$$\widehat{g}_{-i}(X_{n+1}) \longleftrightarrow \min_i \widehat{g}_{-i}(X_{n+1}), \max_i \widehat{g}_{-i}(X_{n+1}). \quad (9)$$

$$\widehat{g}_{-S_k(i)}(X_{n+1}) \longleftrightarrow \min_i \widehat{g}_{-S_k(i)}(X_{n+1}), \max_i \widehat{g}_{-S_k(i)}(X_{n+1}). \quad (10)$$

The intervals will not be centered anymore and we have the coverage guarantee [Barber et al., 2021] :

$$\mathbb{P} \left(g(X_{n+1}) \in \widehat{C}_{n,\alpha}^{*+mm}(X_{n+1}) \right) \geq 1 - \alpha. \quad (11)$$

Moreover, the resulting intervals will be more conservative.

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Gaussian Process Regression (GPR)

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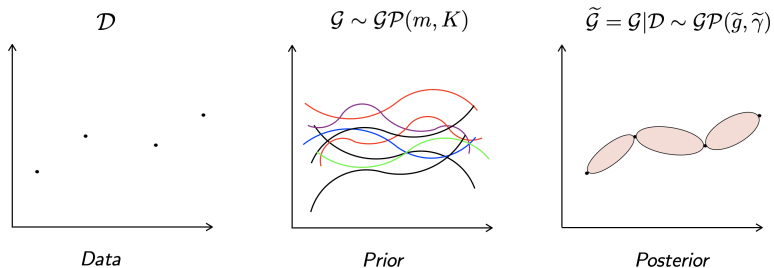
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In practice we don't have access to the true distribution $\mathbb{P}_{(X, g(X))}$. If we dispose of a test dataset :

$$\mathcal{D}^{test} = \{(X_1, g(X_1)), \dots, (X_m, g(X_m))\}, \quad (14)$$

different from \mathcal{D} , then in all generality we cannot expect to have :

$$\frac{1}{m} \sum_{i=1}^m \mathbb{1}\{g(X_i) \in \mathcal{CR}_\alpha(X_i)\} \geq 1 - \alpha, \quad \text{a.s.} \quad (15)$$

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The Burnaev-Wasserman program

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[Burnaev and Vovk, 2014] Assume that $\mathcal{X} \subset \mathbb{R}^d$, for all i , $X_i \in L^2(\Omega)$ and the model g is truly gaussian. The credibility sets have exact coverage and output an interval of the form :

$$\mathcal{C}\mathcal{R}_\alpha(X_{n+1}) = [B_*, B^*] \quad (16)$$

The CRR method with the GPR rule outputs a prediction interval of the form :

$$\widehat{C}_{n,\alpha}^{CRR}(X_{n+1}) = [C_*, C^*]. \quad (17)$$

A natural question is to compare the differences of the bounds of these two intervals and their asymptotic behaviour

See [Burnaev and Vovk, 2014] for a proof of the following.

Theorem

Under the above assumptions we get

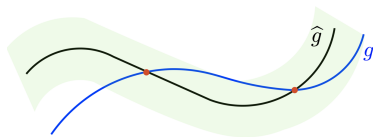
$$\sqrt{n}(B^* - C^*) \xrightarrow[n \rightarrow \infty]{\text{Law}} \mathcal{N}(0, h(\alpha)), \quad (18)$$

and similarly for the lower-bound.

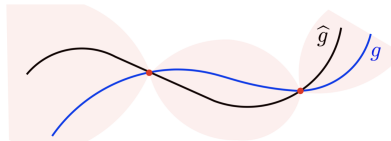
Here h is a function of the $1 - \alpha/2$ -quantile of the standard normal distribution and of the mean and variance of the input distribution.

Problem formulation

Conformal Prediction



Gaussian Processes



Adaptive Conformal Prediction for better
Uncertainty Quantification

$$\mathbb{P}(g(X) \in C_{\hat{g}, \alpha}(X)) \geq 1 - \alpha. \quad (19)$$

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The idea is to adapt the Jackknife+ method presented earlier to GPR metamodels to have adaptive prediction intervals. We denote these predictors as $\widehat{C}_{n,\alpha}^{J+GP}$ and can prove the following theorem :

Theorem

Assume $\mathcal{D} = (\mathbf{X}, g(\mathbf{X}))$ is exchangeable. For a new point $X_{n+1} \in \mathcal{X} \setminus \mathbf{X}$ and a coverage level $\alpha \in (0, 1)$:

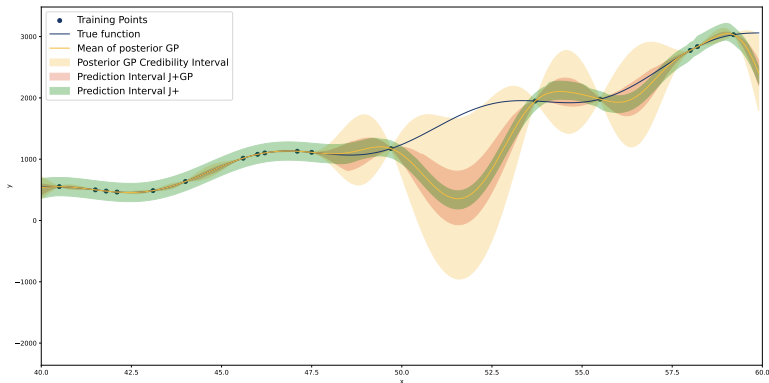
$$\mathbb{P} \left(g(X_{n+1}) \in \widehat{C}_{n,\alpha}^{J+GP}(X_{n+1}) \right) \geq 1 - 2\alpha. \quad (20)$$

Example on a toy function

- The Vincent Blot[©] highly original g_{VB} :

$$g_{VB}(x) = 3x \sin(x) - 2x \cos(x) + \frac{x^3}{40} - \frac{1}{2}x^2 - 10x, \quad (21)$$

which we sample at ease.



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- Conformal prediction is a method for performing distribution-free uncertainty quantification of machine learning algorithms.
- It can be used in a Bayesian regression setting for testing the soft-assumption on the original model.
- Prediction intervals for Gaussian Processes using an adaptation of the CP algorithms can be built (upcoming paper [Jaber and Blot, 2023] - in progress).
- A more robust uncertainty quantification of this type of surrogates can be achieved and can thus serve in assessing their quality for the purpose of performing industrial UQ.

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