

Field uncertainties estimation through (hyper)parameters sampling using Bayesian inference

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Context

Detection and analysis of seismic events

Global scale

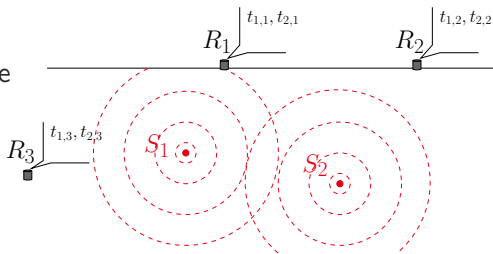
- International treaties (CTBT, NTP)
- Environment monitoring (IMS)

Local scale

- Knowledge of subsurface
- Exploitation

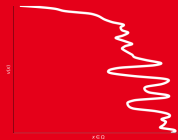
Regional scale

- Tsunami and seism alerts
- Risk prevention



Context: seismic tomography

Quantity of interest



Velocity field f

Forward problem

Forward model^(a)
 \mathcal{M}

Indirect observations



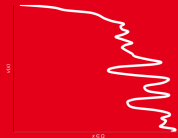
Arrival time

$$\mathbf{d}^{\text{obs}} = \mathcal{M}(f) + \varepsilon$$

^(a) Eikonal solver [Noble and Gesret, 2011]

Context: seismic tomography

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? Inverse problem ?

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Arrival time

$$\mathbf{d}^{\text{obs}} = \mathcal{M}(f) + \varepsilon$$

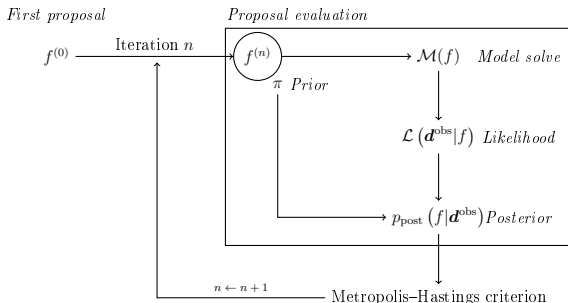
(^a) Eikonal solver [Noble and Gesret, 2011]

Objective: Estimation of a field (i) accurate,
(ii) with uncertainties,
(iii) fast

Bayes formulation

Bayes rule: $p_{\text{post}}(f|\mathbf{d}^{\text{obs}}) \propto \mathcal{L}(\mathbf{d}^{\text{obs}}|f)\pi_{\mathcal{F}}(f)$

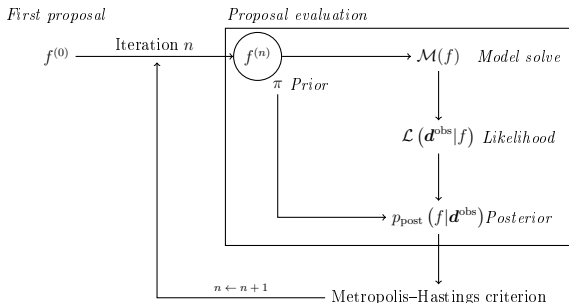
Markov Chain Monte–Carlo algorithm:



Bayes formulation

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Markov Chain Monte–Carlo algorithm:



⇒ Representation of f ?

Evaluation of \mathcal{M} ?

→ Polynomial chaos surrogate [Marzouk and Najm, 2009]

Field representation

$f(\mathbf{x})$ is seen as a particular *realization of a random (Gaussian) process* $\mathcal{G} \sim \mathcal{N}(0, k)$, where k is the *autocovariance function*

Karhunen–Loève decomposition

$$f(\mathbf{x}) = \mathcal{G}(\mathbf{x}, \theta) \simeq \sum_{i=1}^r \lambda_i^{1/2} u_i(\mathbf{x}) \eta_i(\theta), \text{ with } \eta_i = \lambda_i^{-1/2} \langle u_i, \mathcal{G} \rangle_{\Omega}$$

- $(u_i, \lambda_i)_{i \in \mathbb{N}^*}$ eigenelements of k :

$$\langle k(\mathbf{x}, \cdot), u_i \rangle_{\Omega} := \int_{\Omega} k(\mathbf{x}, \mathbf{x}') u_i(\mathbf{x}') d\mathbf{x}' = \lambda_i u_i(\mathbf{x})$$

- **Bi-orthonormality** of the decomposition:
 - $\forall i, j \in \mathbb{N}^*$, u_i, u_j orthonormal, $\langle u_i, u_j \rangle_{\Omega} = \delta_{i,j}$,
 - $\boldsymbol{\eta} := (\eta_i)_{1 \leq i \leq r} \sim \mathcal{N}(0, \mathbf{I}_r)$ (if Gaussian process)

$$\Rightarrow p_{\text{post}}(\boldsymbol{\eta} | \mathbf{d}^{\text{obs}}) \propto \mathcal{L}(\mathbf{d}^{\text{obs}} | \boldsymbol{\eta}) \pi(\boldsymbol{\eta})$$

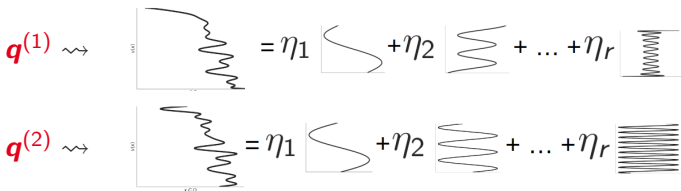
[Karhunen, 1946][Loève, 1977]

Dependency on hyperparameters

In fact, $\mathcal{G} \sim \mathcal{N}(0, k(\mathbf{q}))$,

$$f(\mathbf{x}) \simeq \sum_{i=1}^r \lambda_i^{1/2}(\mathbf{q}) u_i(\mathbf{x}, \mathbf{q}) \eta_i, \text{ with } \eta_i = \lambda_i^{-1/2}(\mathbf{q}) \langle u_i(\cdot, \mathbf{q}), f \rangle_{\Omega}$$

Squared exponential kernel: $k(x, y, \mathbf{q} := \{A, \ell\}) = A \exp\left(-\frac{\|x-y\|^2}{2\ell^2}\right)$



$$\Rightarrow p_{\text{post}}(\boldsymbol{\eta}, \mathbf{q} | \mathbf{d}^{\text{obs}}) \propto \mathcal{L}(\mathbf{d}^{\text{obs}} | \boldsymbol{\eta}, \mathbf{q}) \pi(\boldsymbol{\eta}, \mathbf{q})$$

Change of measure method

Change of measure:

- Reference kernel \bar{k} and associated basis $(\bar{\lambda}_i, \bar{u}_i)_{i \in \mathbb{N}^*}$ [Sraj et al., 2016]
- Sample $(\boldsymbol{\xi}, \mathbf{q})$: *the \mathbf{q} -dependency is transferred to the coordinates law*, [NP/Sochala/Le Maître/Gesret, in prep.]

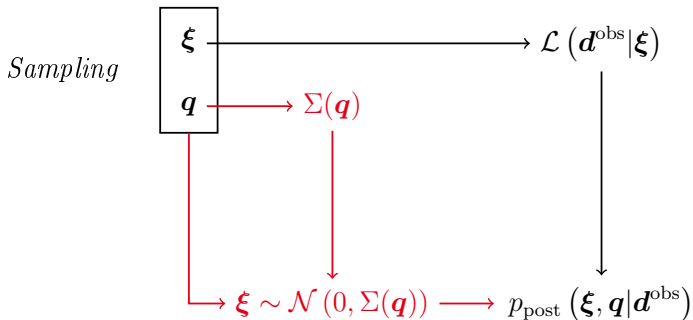
$$f(\mathbf{x}) \simeq \bar{\mathcal{G}}^r(\mathbf{x}, \theta) := \sum_{i=1}^r \bar{\lambda}_i^{1/2} \bar{u}_i(\mathbf{x}) \xi_i(\theta) \text{ with } \boldsymbol{\xi} \sim \mathcal{N}(0, \boldsymbol{\Sigma}(\mathbf{q}))$$

$$\text{and } p_{\text{post}}(\boldsymbol{\xi}, \mathbf{q} | \mathbf{d}^{\text{obs}}) \propto \mathcal{L}(\mathbf{d}^{\text{obs}} | \boldsymbol{\xi}) \pi(\boldsymbol{\xi} | \mathbf{q}) \pi(\mathbf{q})$$

The covariance matrix $\boldsymbol{\Sigma}(\mathbf{q})$ writes

$$\forall 1 \leq i, j \leq r, \forall \mathbf{q} \in \mathbb{H}, \quad \Sigma_{ij}(\mathbf{q}) := (\bar{\lambda}_i \bar{\lambda}_j)^{-1/2} \langle \langle k(\cdot, \cdot, \mathbf{q}), \bar{u}_j \rangle_{\Omega}, \bar{u}_i \rangle_{\Omega}$$

Workflow

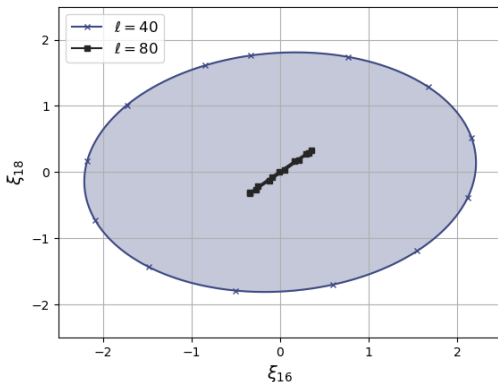


- $\Sigma_{ij}(\mathbf{q}) = (\bar{\lambda}_i \bar{\lambda}_j)^{-1/2} \langle \langle k(\cdot, \cdot, \mathbf{q}), \bar{u}_j \rangle_{\Omega}, \bar{u}_i \rangle_{\Omega}$

Sampling problem

Hierarchical formulation: $p_{\text{post}}(\boldsymbol{\xi}, \mathbf{q} | \mathbf{d}^{\text{obs}}) \propto \mathcal{L}(\mathbf{d}^{\text{obs}} | \boldsymbol{\xi}) \pi(\boldsymbol{\xi} | \mathbf{q}) \pi(\mathbf{q})$,

$\boldsymbol{\xi} \sim \mathcal{N}(0, \Sigma(\mathbf{q}))$: *the prior distribution of $\boldsymbol{\xi}$ is highly sensitive to \mathbf{q}*



Projection of $\boldsymbol{\xi}$ priors for two different \mathbf{q}

Sampling strategy

Introduction of an *auxiliary variable* $\bar{\xi}$ whose prior law does not depend on the hyperparameters (e.g. $\bar{\xi} \sim \mathcal{N}(0, \Sigma_{\bar{\xi}})$)

Algorithm 1 Sampling step for CoM method.

- Input:** $Y^{(n)} = (\bar{\xi}^{(n)}, \xi^{(n)}, \mathbf{q}^{(n)})$ ▷ Current state
- 1: Propose $(\bar{\xi}^*, \mathbf{q}^*) \sim \mathcal{N}((\bar{\xi}^{(n)}, \mathbf{q}^{(n)}), \hat{C}^{(n)})$ ▷ Adaptive random walk
 - 2: Set $\xi^* = \Sigma(\mathbf{q}^{(n)})^{1/2} \Sigma_{\bar{\xi}}^{-1/2} \bar{\xi}^*$ ▷ Change of variable
 - 3: Accept/Reject according to MH criterion on $p_{\text{post}}(\xi^*, \mathbf{q}^*)$.
-

- the ratio of the transition probabilities becomes

$$\frac{p(\xi^{(n)}, \mathbf{q}^{(n)} | \xi^*, \mathbf{q}^*)}{p(\xi^*, \mathbf{q}^* | \xi^{(n)}, \mathbf{q}^{(n)})} = \left(\frac{\det \Sigma(\mathbf{q}^*)}{\det \Sigma(\mathbf{q}^{(n)})} \right)^{1/2}$$

Surrogate quantities

Evaluating forward model \mathcal{M} and derived quantities of $\Sigma(\mathbf{q})$ at each step is expensive \Rightarrow use of *Polynomial Chaos (PC) expansions* [Wiener, 1938][Ghanem and Spanos, 1991][Xiu and Karniadakis, 2002]

$$m(\zeta) \simeq \tilde{m}(\zeta) = \sum_{a \in \mathcal{A}} m_a \Psi_a(\zeta),$$

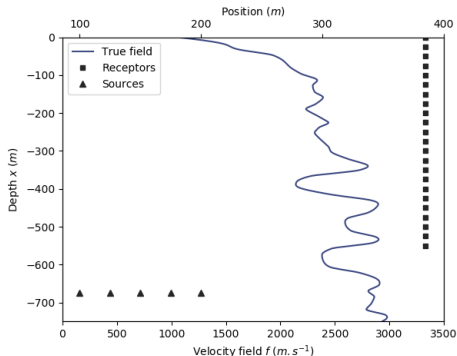
- Forward model: $\mathcal{M} \circ f(\boldsymbol{\xi}) = \tilde{\mathcal{M}}(\boldsymbol{\xi})$
- $\Sigma(\mathbf{q})^{-1} = \widetilde{\Sigma^{-1/2}}(\mathbf{q}) \widetilde{\Sigma^{-1/2}}(\mathbf{q})$
- $\log \det [\Sigma(\mathbf{q})] = \widetilde{(\log \det \Sigma)}(\mathbf{q})$
- $\Sigma(\mathbf{q})^{1/2} = \widetilde{\Sigma^{1/2}}(\mathbf{q})$

$\Sigma^{\pm 1/2}$ is obtained by eigendecomposition of Σ

$$\Sigma^{\pm 1/2} = U \Lambda^{\pm 1/2} U^T,$$

where (U, Λ) are the eigenelements of Σ

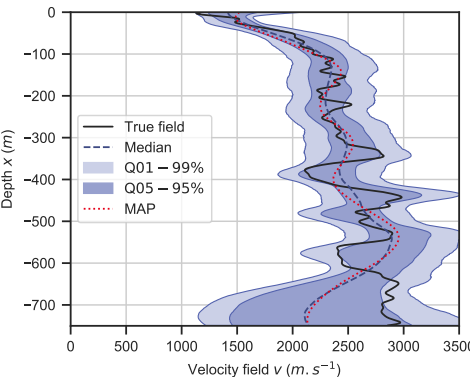
Application to seismic tomography



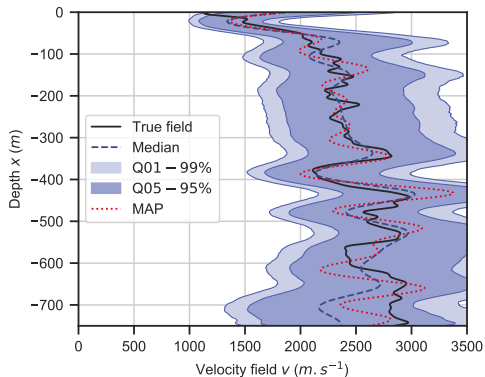
Application case: 1D section of Amoco model [O'Brien and Regone, 1994] and location of stations

\mathbf{d}^{obs} : time of arrival, with noise level $\alpha = 0.002s$
 $r = 20$, $\mathbf{q} = \{A, \ell\}$

Inference of a field (SW)



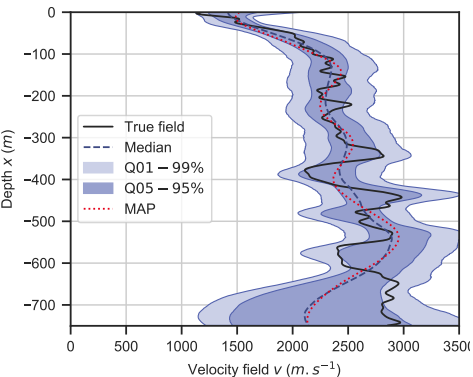
(a) Proposed method



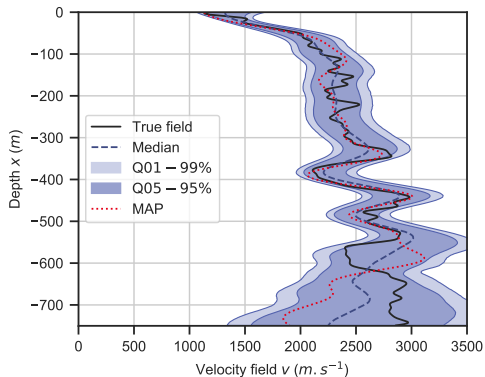
(b) $\ell = 10$

Comparison of inference results for different bases - small wavelength field

Inference of a field (SW)



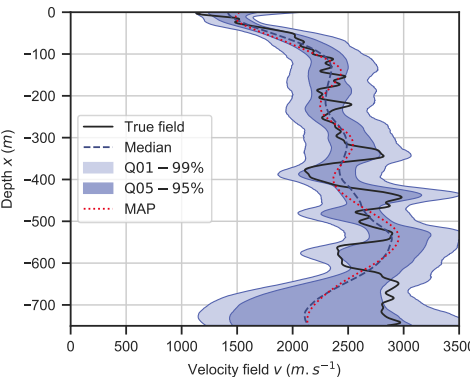
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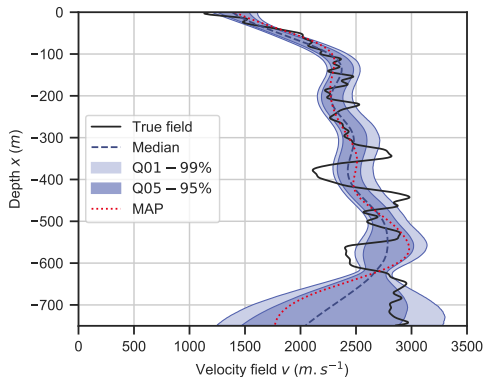
(b) $\ell = 34$

Comparison of inference results for different bases - small wavelength field

Inference of a field (SW)



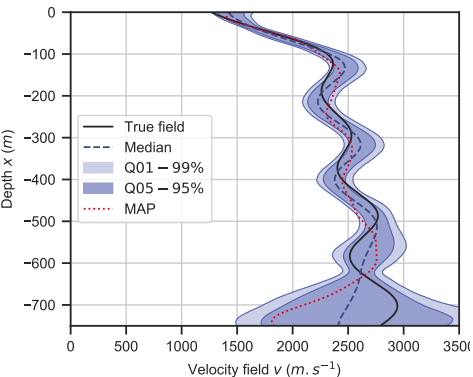
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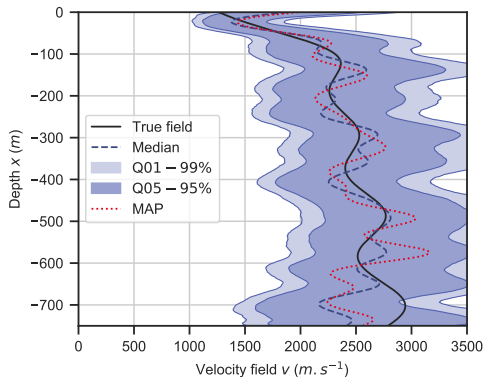
(b) $\ell = 80$

Comparison of inference results for different bases - small wavelength field

Inference of a field (LW)



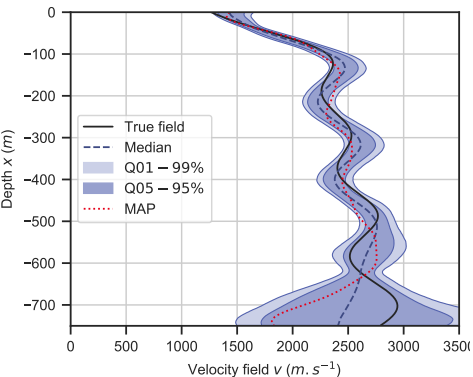
(a) Proposed method



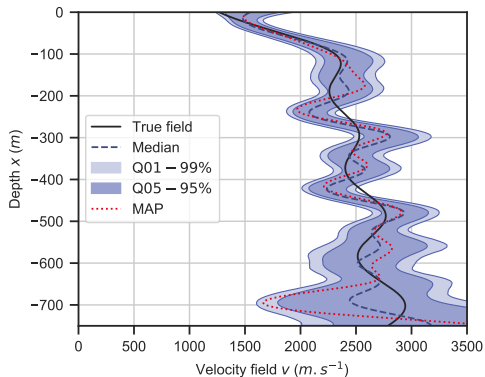
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Comparison of inference results for different bases - large wavelength field

Inference of a field (LW)



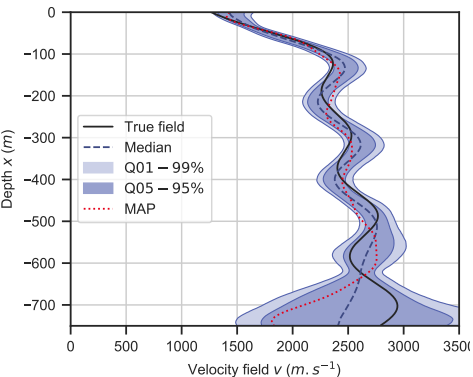
(a) Proposed method



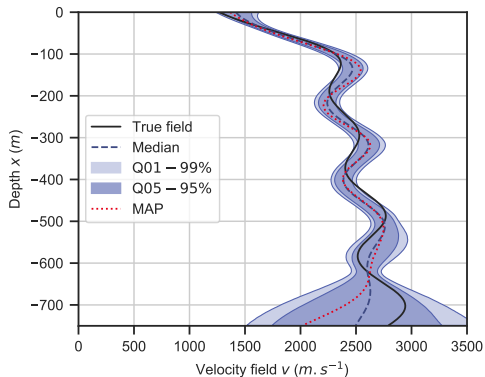
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Comparison of inference results for different bases - large wavelength field

Inference of a field (LW)



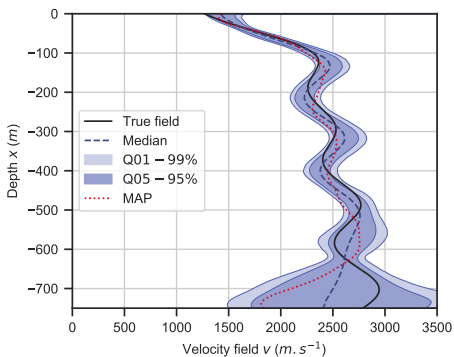
(a) Proposed method



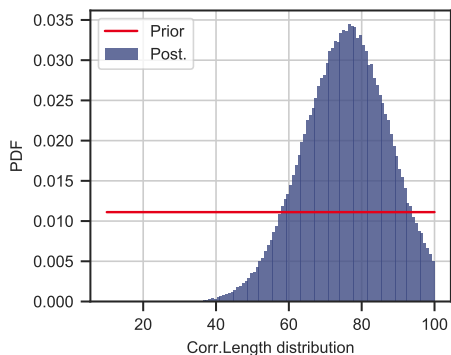
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Comparison of inference results for different bases - large wavelength field

Hyperparameters distribution (LW)



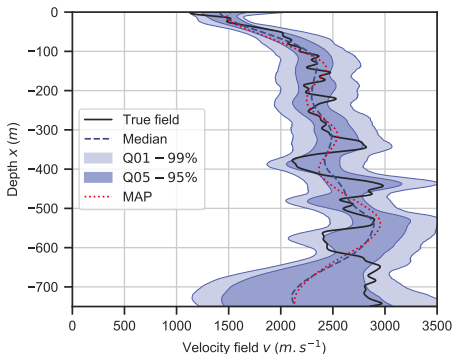
(a) Field posterior distribution



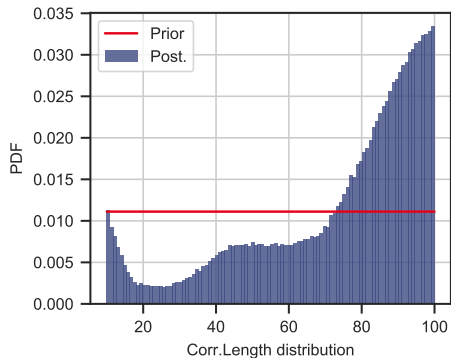
(b) Correlation length posterior distribution

Posterior distributions - large wavelength field

Hyperparameters distribution (SW)



(a) Field posterior distribution

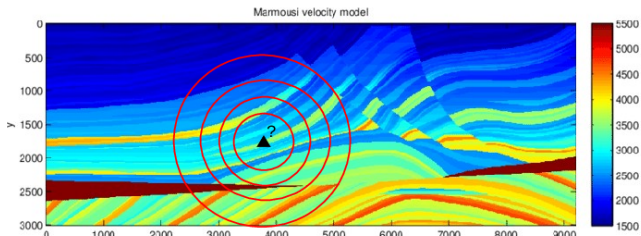


(b) Correlation length posterior distribution

Posterior distributions - small wavelength field

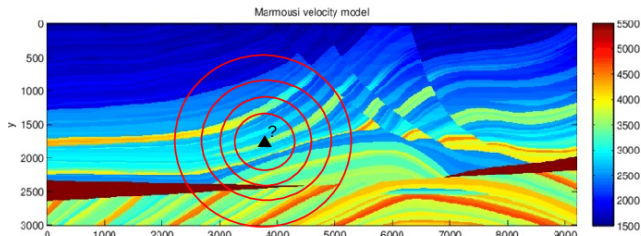
Conclusion and perspectives

- Change of measure
 - Dimension reduction of the field
 - Enlarge *a priori* parametrization \rightsquigarrow uncertainties are less ruled by the model selection
 - Without large computational cost increase



Conclusion and perspectives

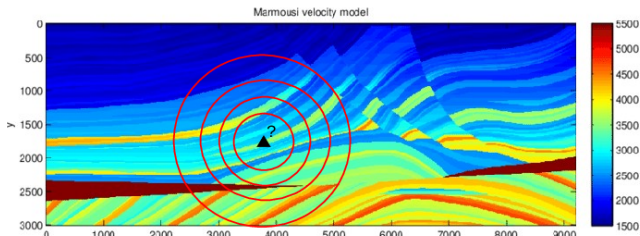
- Change of measure
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 - Enlarge *a priori* parametrization \rightsquigarrow uncertainties are less ruled by the model selection
 - Without large computational cost increase
- Development of adaptive methods
- Use of the posterior quantity to propagate uncertainty to other parameters (e.g. seismic location)
- *How to quantify the relevance of the uncertainties ?*








Conclusion and perspectives

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 - Dimension reduction of the field
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Thank you !



References I

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Polynomial Chaos expansions

Evaluating forward model and derived quantities of $\Sigma(\mathbf{q})$ at each step is expensive \Rightarrow use of *Polynomial Chaos (PC) expansions*

[Wiener, 1938][Ghanem and Spanos, 1991][Xiu and Karniadakis, 2002]

$$m(\zeta) \simeq \tilde{m}(\zeta) = \sum_{a \in \mathcal{A}} m_a \Psi_a(\zeta),$$

- $\{\Psi_a(\zeta)\}_{a \in \mathcal{A}}$: orthogonal polynomials in $L^2(\zeta)$
- $\{m_a\}_{a \in \mathcal{A}}$: PC coefficients
- \mathcal{A} : set of multi-indexes

Building framework:

- Exact evaluations at quadrature points (Gauss–Legendre or sparse grids)
- Computations of PC coefficients by matrix-vector product

Surrogate quantities

Evaluating forward model and derived quantities of $\Sigma(\mathbf{q})$ at each step is expensive \Rightarrow use of *Polynomial Chaos (PC) expansions*
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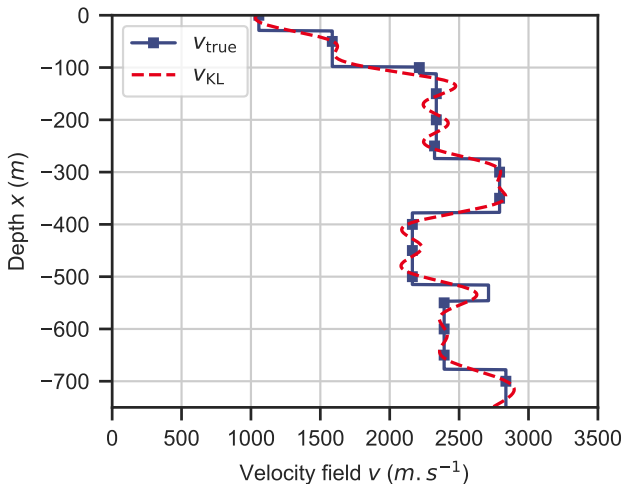
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$\Sigma^{\pm 1/2}$ is obtained by eigendecomposition of Σ

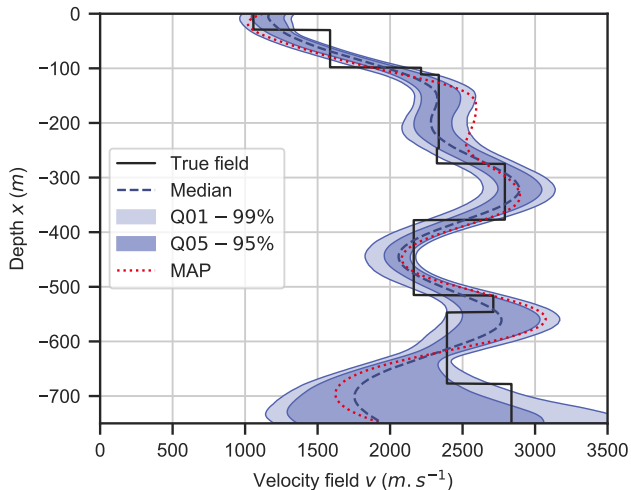
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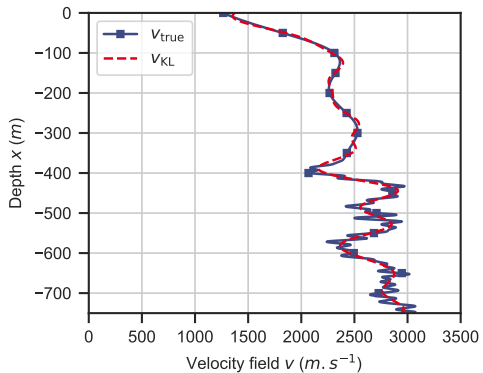
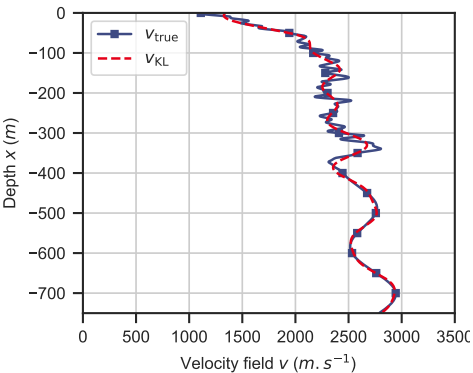
Projection of a discrete field



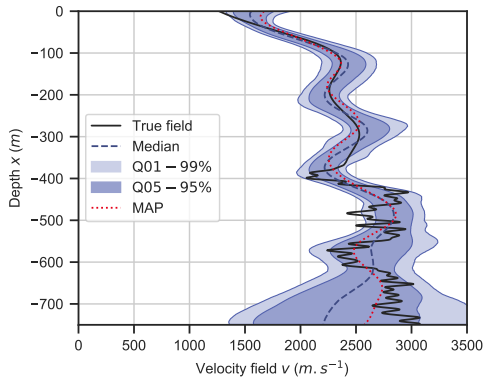
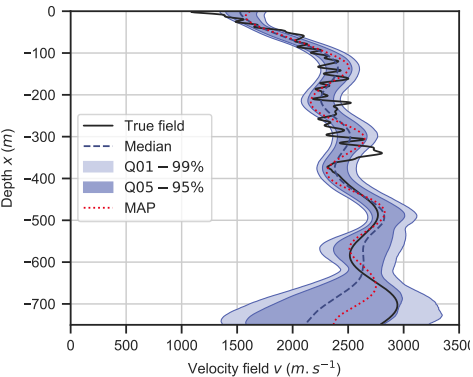
Inference of a discrete field



Projection of a non-stationnary field

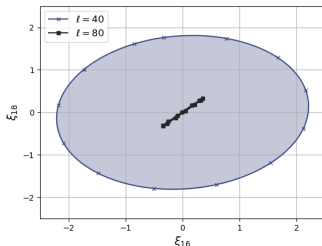


Inference of a non-stationnary field



Sampling problem

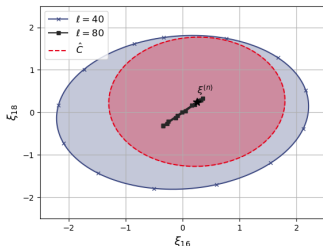
Hierarchical formulation: $p_{\text{post}}(\boldsymbol{\xi}, \mathbf{q} | \mathbf{d}^{\text{obs}}) \propto \mathcal{L}(\mathbf{d}^{\text{obs}} | \boldsymbol{\xi}) \pi(\boldsymbol{\xi} | \mathbf{q}) \pi(\mathbf{q})$,
 $\boldsymbol{\xi} \sim \mathcal{N}(0, \Sigma(\mathbf{q}))$: *the prior distribution of $\boldsymbol{\xi}$ is highly sensitive to \mathbf{q}*



Projection of $\boldsymbol{\xi}$ priors for two different \mathbf{q}

Sampling problem

Hierarchical formulation: $p_{\text{post}}(\boldsymbol{\xi}, \mathbf{q} | \mathbf{d}^{\text{obs}}) \propto \mathcal{L}(\mathbf{d}^{\text{obs}} | \boldsymbol{\xi}) \pi(\boldsymbol{\xi} | \mathbf{q}) \pi(\mathbf{q})$,
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Projection of $\boldsymbol{\xi}$ priors for two different \mathbf{q}

Initial sampling : Metropolis–Hastings (MH) random walk with adapted covariance proposal

$$Y^* := (\boldsymbol{\xi}^*, \mathbf{q}^*) \sim \mathcal{N}(Y^{(n)}, \hat{C}^{(n)}), \text{ with } \hat{C}^{(n)} \propto \text{Cov}(Y^{(1)}, \dots, Y^{(n)})$$