

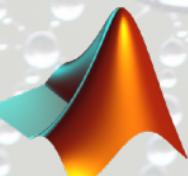
Numerical Optimal Transport

<http://optimaltransport.github.io>

Entropic Regularization

Gabriel Peyré

www.numerical-tours.com



ÉCOLE NORMALE
SUPÉRIEURE

Overview

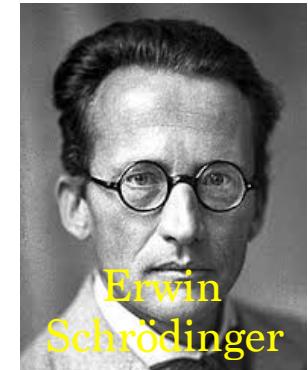
- Entropic Regularization and Sinkhorn
- Convergence Analysis
- Sinkhorn Divergences
- Generative Model Fitting

Entropic Regularization

Schrödinger's problem:

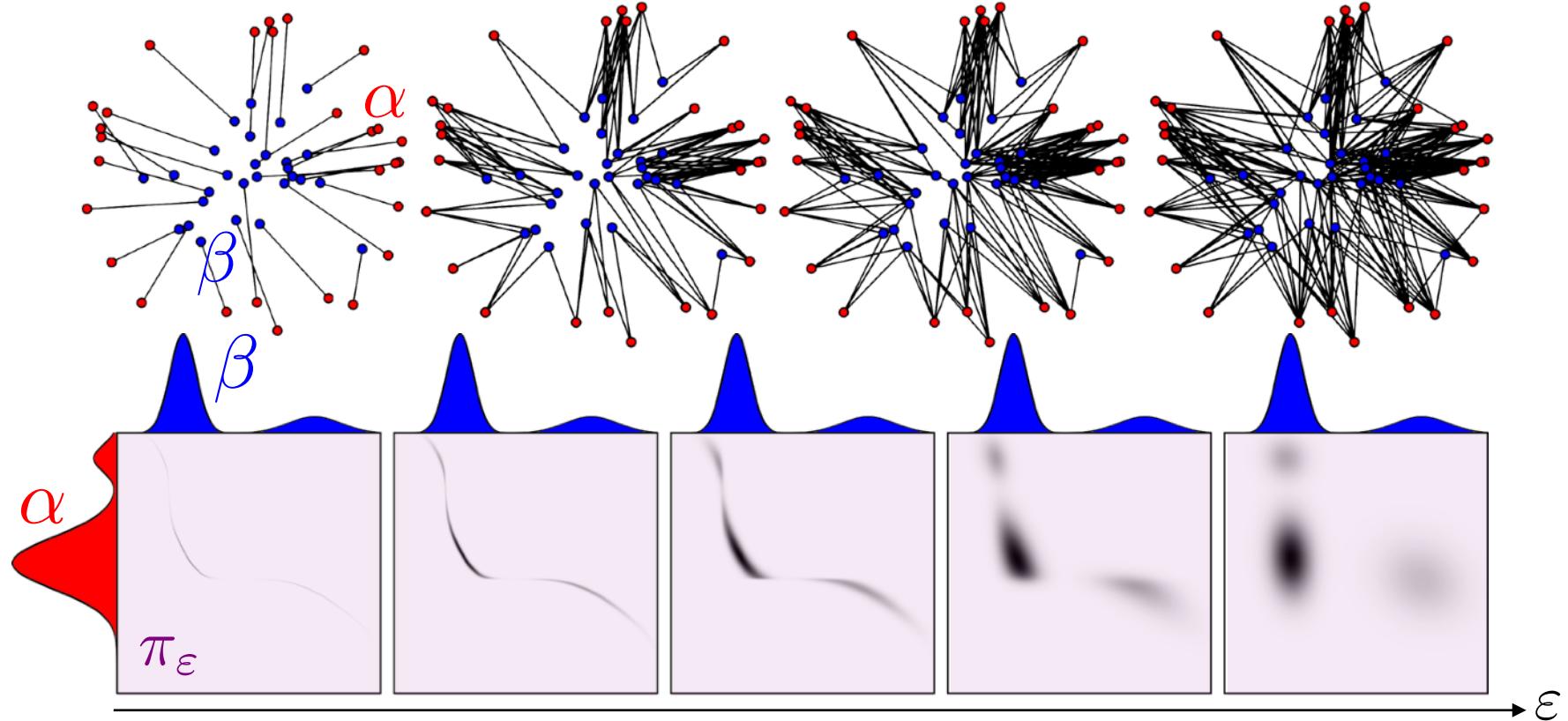
[1931]

$$\min_{\mathbf{P} \in \mathbf{U}(\mathbf{a}, \mathbf{b})} \sum_{i,j} d(x_i, y_j)^p \mathbf{P}_{i,j} + \varepsilon \mathbf{P}_{i,j} \log \left(\frac{\mathbf{P}_{i,j}}{\mathbf{a}_i \mathbf{b}_j} \right)$$



Erwin
Schrödinger

$$\pi = \sum_{i,j} \mathbf{P}_{i,j} \delta_{x_i, y_j}$$



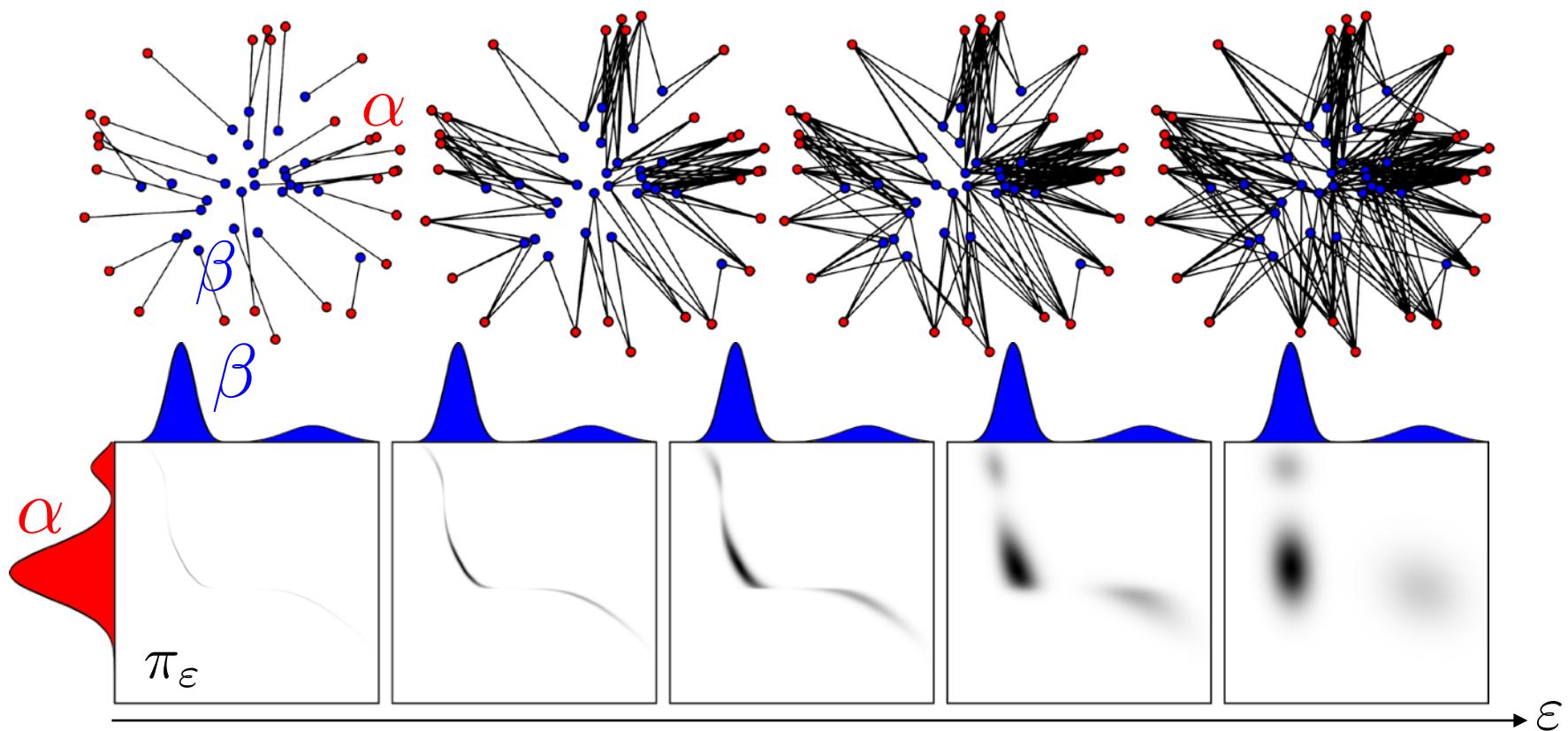
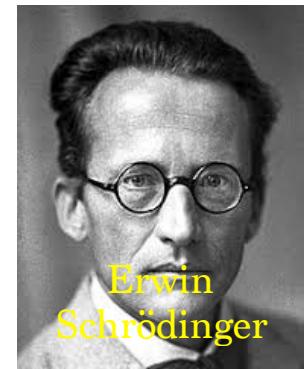
Entropic Regularization

Relative-entropy: $\text{KL}(\pi | \alpha \otimes \beta) \stackrel{\text{def.}}{=} \int_{\mathcal{X}^2} \log \left(\frac{d\pi}{d\alpha d\beta}(x, y) \right) d\pi(x, y)$

Schrödinger's problem:

[1931]

$$W_{\varepsilon, p}^p(\alpha, \beta) \stackrel{\text{def.}}{=} \min_{\pi_1 = \alpha, \pi_2 = \beta} \int_{\mathcal{X}^2} d^p(x, y) d\pi(x, y) + \varepsilon \text{KL}(\pi | \alpha \otimes \beta)$$

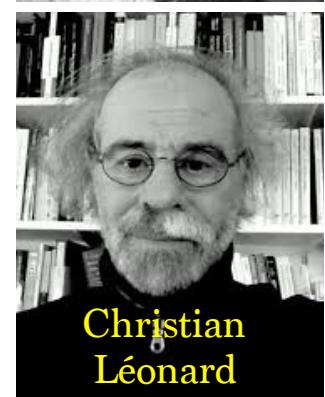
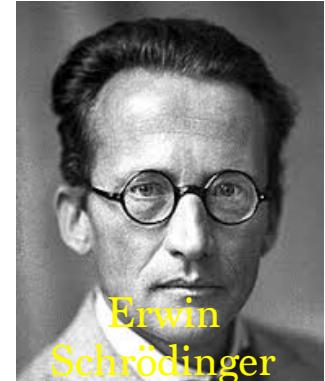


Probabilistic Interpretation

Relative-entropy: $\text{KL}(\pi|\alpha \otimes \beta) \stackrel{\text{def.}}{=} \int_{\mathcal{X}^2} \log \left(\frac{d\pi}{d\alpha d\beta}(x, y) \right) d\pi(x, y)$

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$$\min_{(X, Y)} \{ \mathbb{E}(c(X, Y)) + \varepsilon I(X, Y) ; X \sim \alpha, Y \sim \beta \}$$

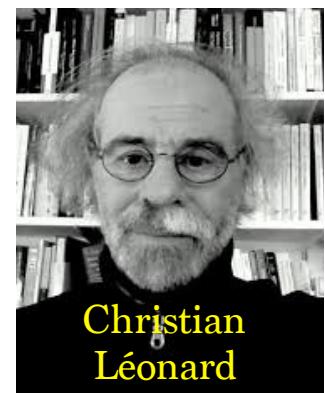
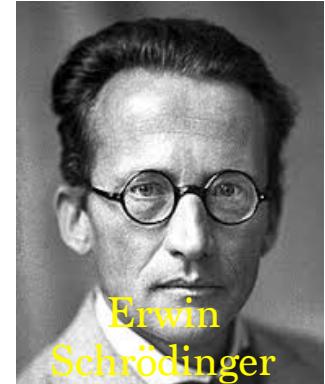
Mutual information

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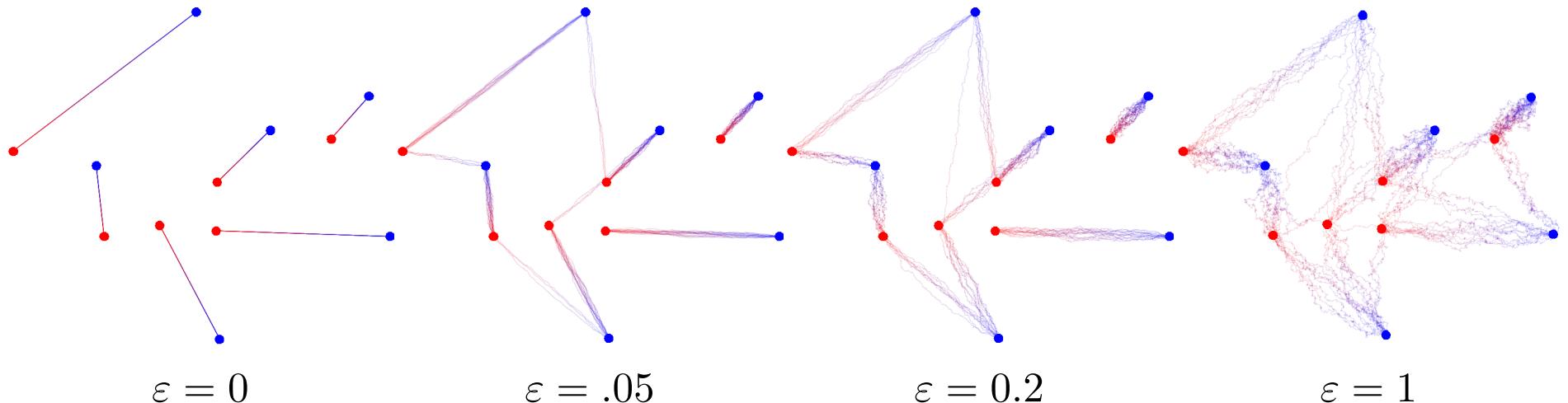
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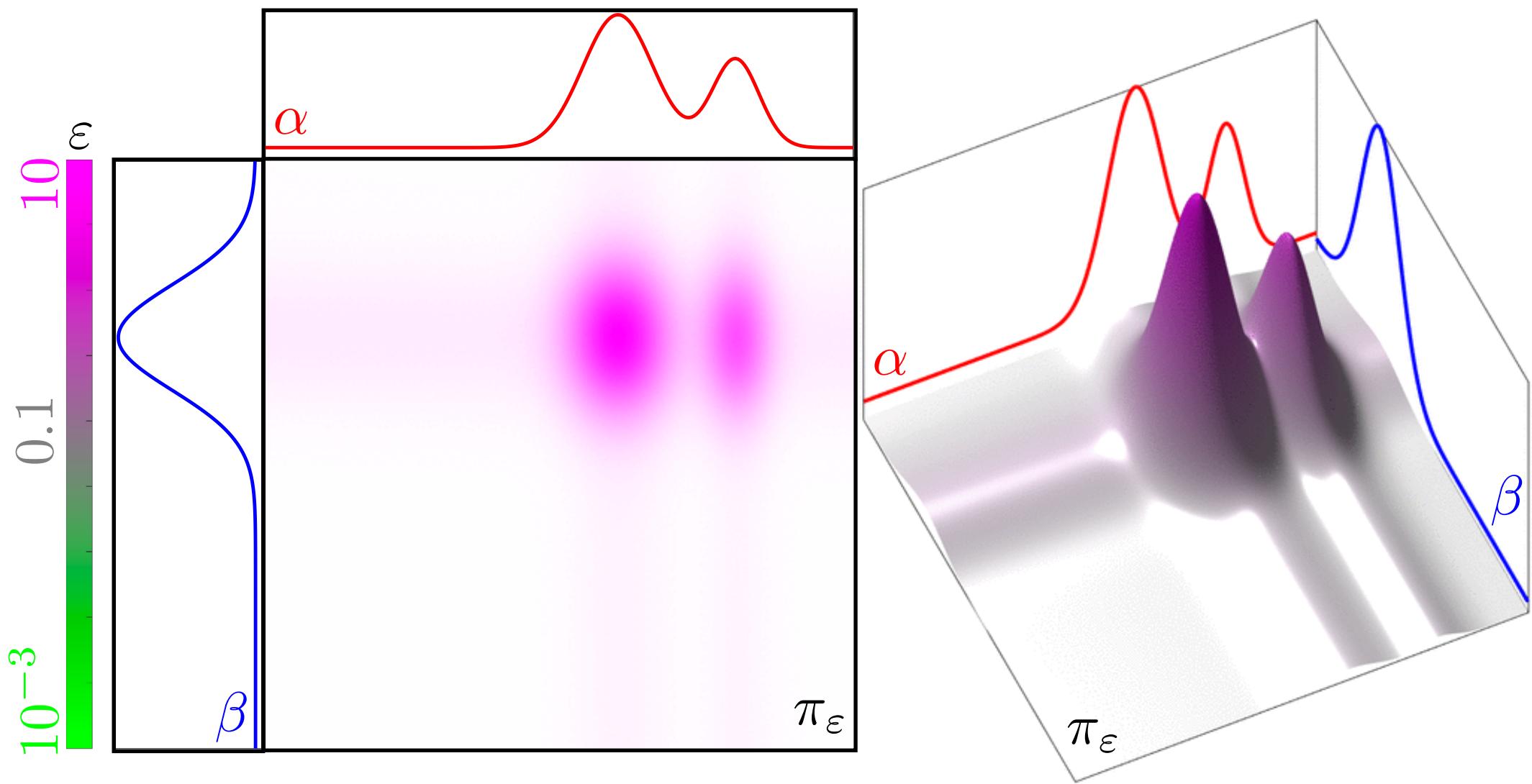


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Mutual information



Impact of Regularization



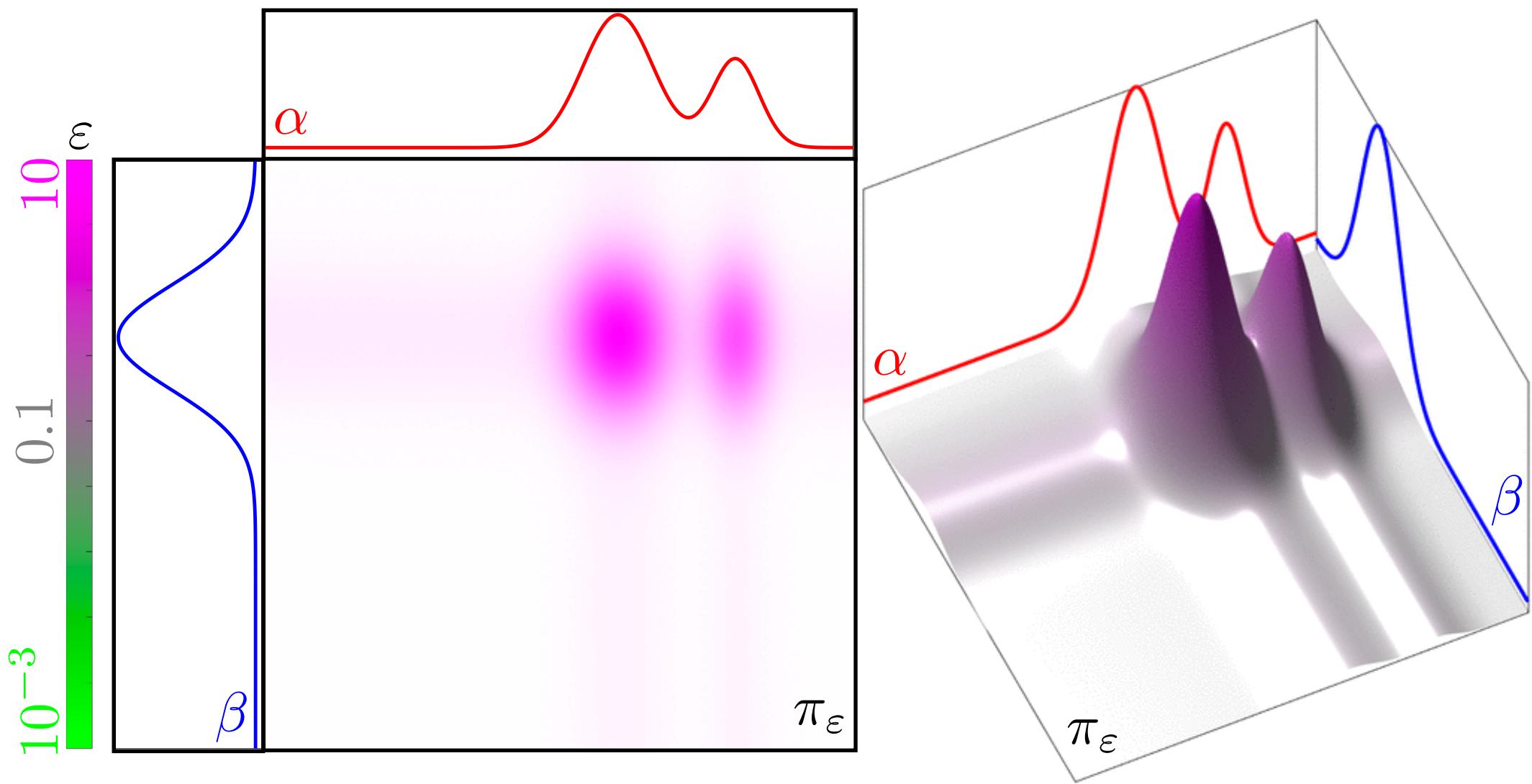
$$\pi_\varepsilon = \operatorname{argmin}_\pi \left\{ \int_{\mathbb{R}^2} \left(\|x - y\|^2 + \varepsilon \log \left(\frac{d\pi}{d\alpha d\beta}(x, y) \right) \right) d\pi(x, y) ; \; \pi_1 = \alpha, \pi_2 = \beta \right\}$$

Theorem:

$$\pi_\varepsilon \xrightarrow{\varepsilon \rightarrow +\infty} \alpha \otimes \beta$$

$$\pi_\varepsilon \xrightarrow{\varepsilon \rightarrow 0} \pi_{\text{OT}}$$

Impact of Regularization



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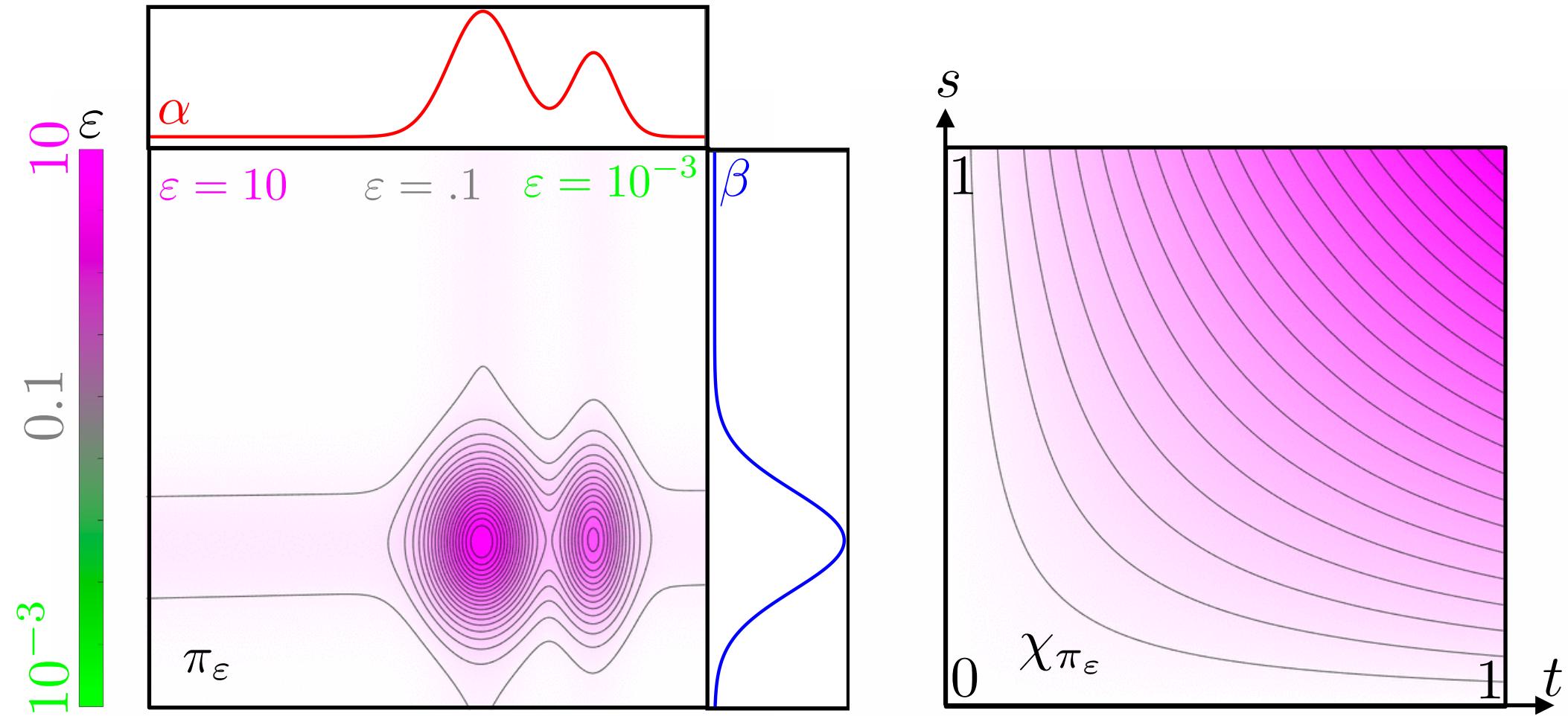
$$\pi_\varepsilon \xrightarrow{\varepsilon \rightarrow +\infty} \alpha \otimes \beta$$

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Impact of Regularization

Cumulative: $C_\pi(x, y) \stackrel{\text{def.}}{=} \int_{-\infty}^x \int_{-\infty}^y d\pi(x, y)$

Copula: $\chi_\pi(s, t) \stackrel{\text{def.}}{=} C_\pi(C_\alpha^{-1}(s), C_\beta^{-1}(t))$

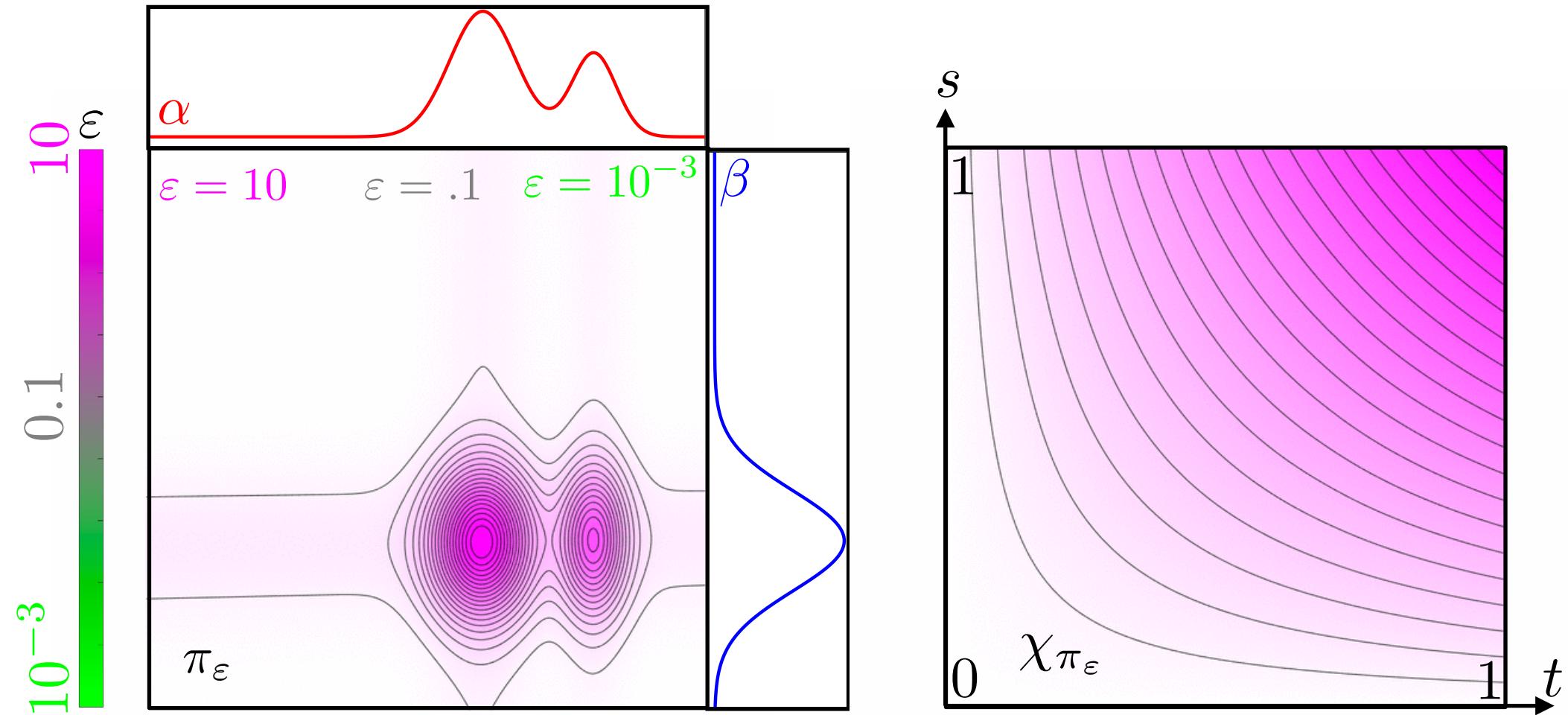


Theorem: $\chi_{\pi_\varepsilon}(s, t)$ $\begin{cases} \xrightarrow{\varepsilon \rightarrow 0} \min(s, t) & \text{(dependence)} \\ \xrightarrow{\varepsilon \rightarrow +\infty} st & \text{(independence)} \end{cases}$

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Sinkhorn's Algorithm

$$\min_{\mathbf{P} \in \mathbf{U}(\mathbf{a}, \mathbf{b})} \sum_{i,j} d(x_i, y_j)^p \mathbf{P}_{i,j} + \varepsilon \mathbf{P}_{i,j} \log \left(\frac{\mathbf{P}_{i,j}}{\mathbf{a}_i \mathbf{b}_j} \right)$$

$$Proposition: \quad \mathbf{P}_{i,j} = \mathbf{u}_i \mathbf{K}_{i,j} \mathbf{v}_j \quad \mathbf{K}_{i,j} \stackrel{\text{def.}}{=} e^{-\frac{d(x_i, y_j)^p}{\varepsilon}}$$

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Row constraint: $\mathbf{u} \odot (\mathbf{K}\mathbf{v}) = \mathbf{a}$

Col. constraint: $\mathbf{v} \odot (\mathbf{K}^\top \mathbf{u}) = \mathbf{b}$

Sinkhorn's Algorithm

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Sinkhorn iterations:

$$\mathbf{u} \leftarrow \frac{\mathbf{a}}{\mathbf{K}\mathbf{v}}$$

$$\mathbf{v} \leftarrow \frac{\mathbf{b}}{\mathbf{K}^\top \mathbf{u}}$$

Theorem: [Sinkhorn 1964] (\mathbf{u}, \mathbf{v}) converges.

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Only matrix/vector multiplications.

Matrix-vectors

$$\mathbf{K} \begin{array}{|c|} \hline \end{array}, \dots, \mathbf{K} \begin{array}{|c|} \hline \end{array} \mathbf{v}^1, \dots, \mathbf{v}^q$$

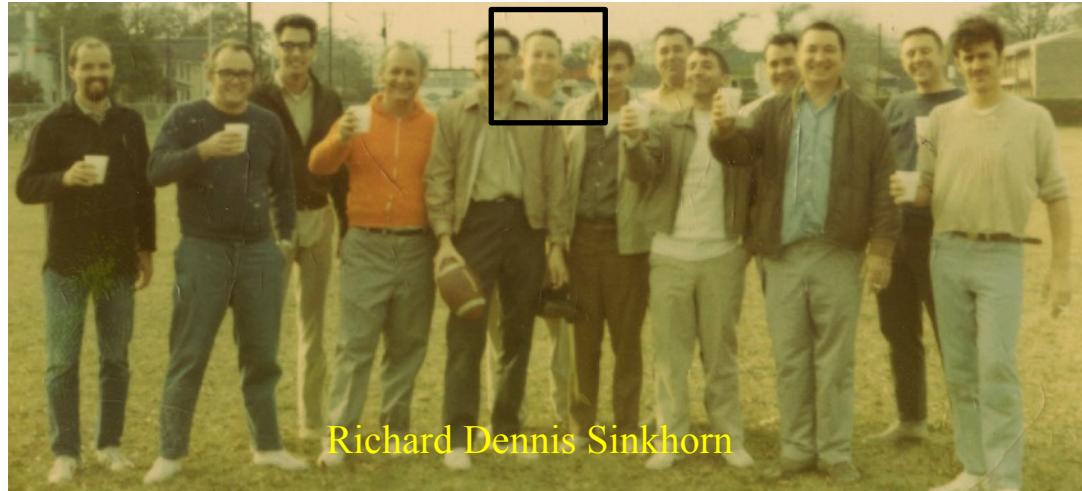
parallelization
GPU

Matrix-matrix

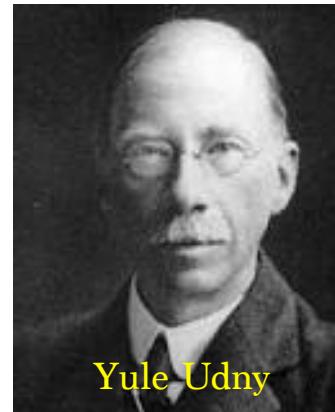
$$\mathbf{K} \begin{array}{|c|} \hline \end{array}, \dots, \mathbf{V} \begin{array}{|c|} \hline \end{array} \mathbf{v}^1, \dots, \mathbf{v}^q$$

→ Convolution on regular grids, separable kernels.

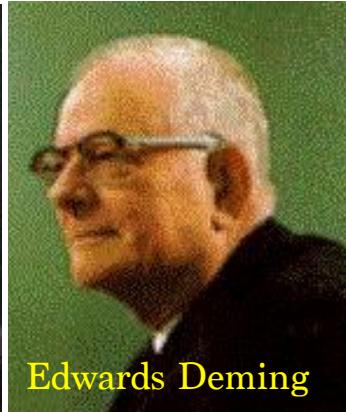
Sinkhorn, IPFP, RAS, ...



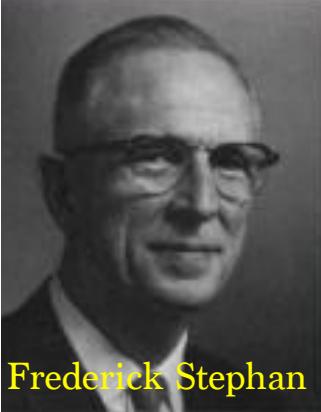
Richard Dennis Sinkhorn



Yule Udney



Edwards Deming



Frederick Stephan

Many names:

Sinkhorn algorithm

DAD scaling

Iterative proportional fitting

Biproportional fitting

RAS algorithm

Matrix scaling

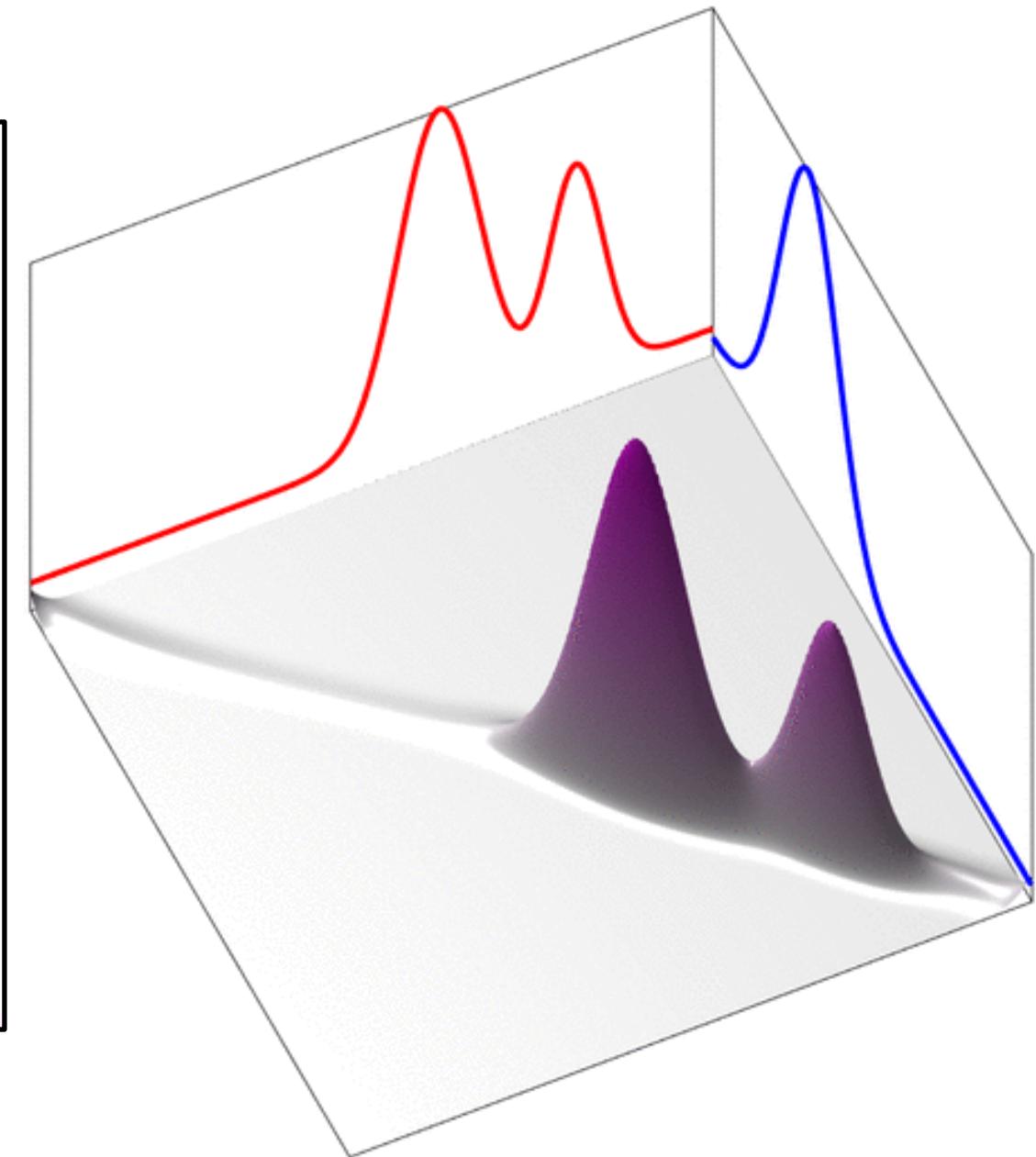
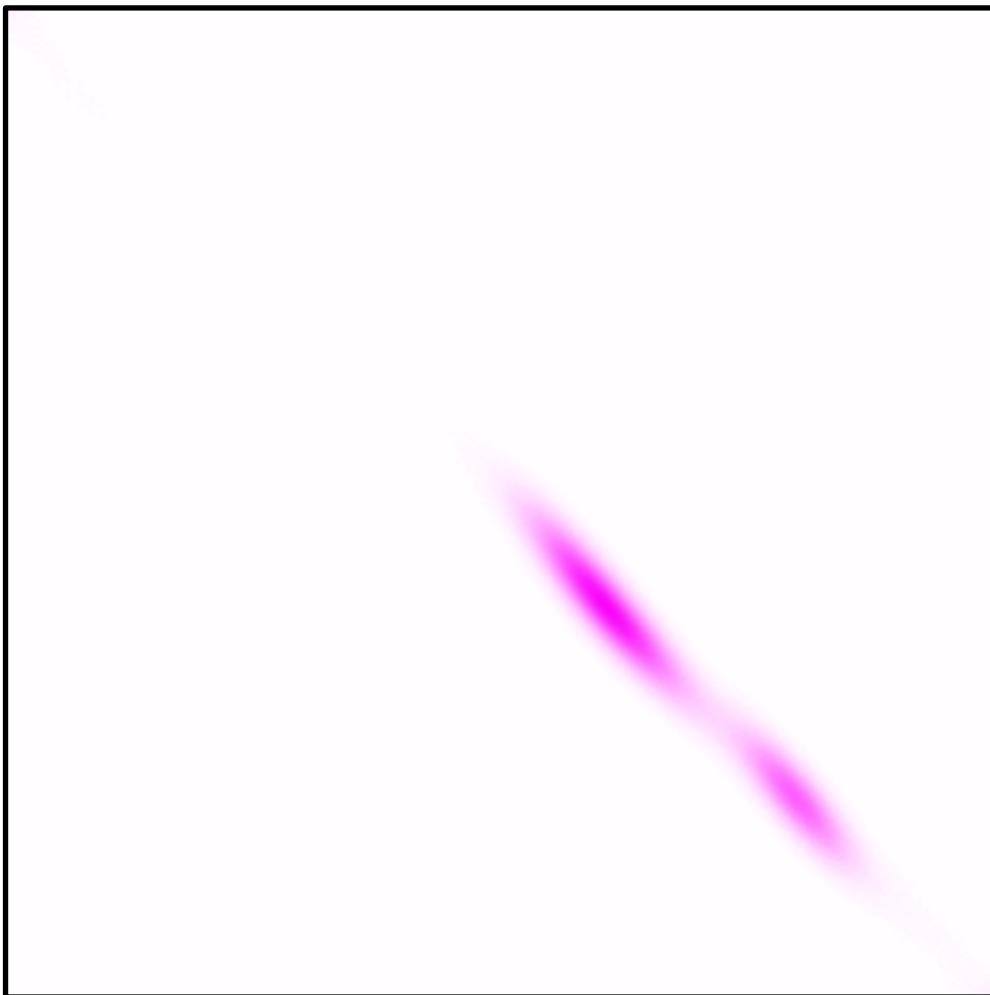
Udny 1912

Kruithof, 1937

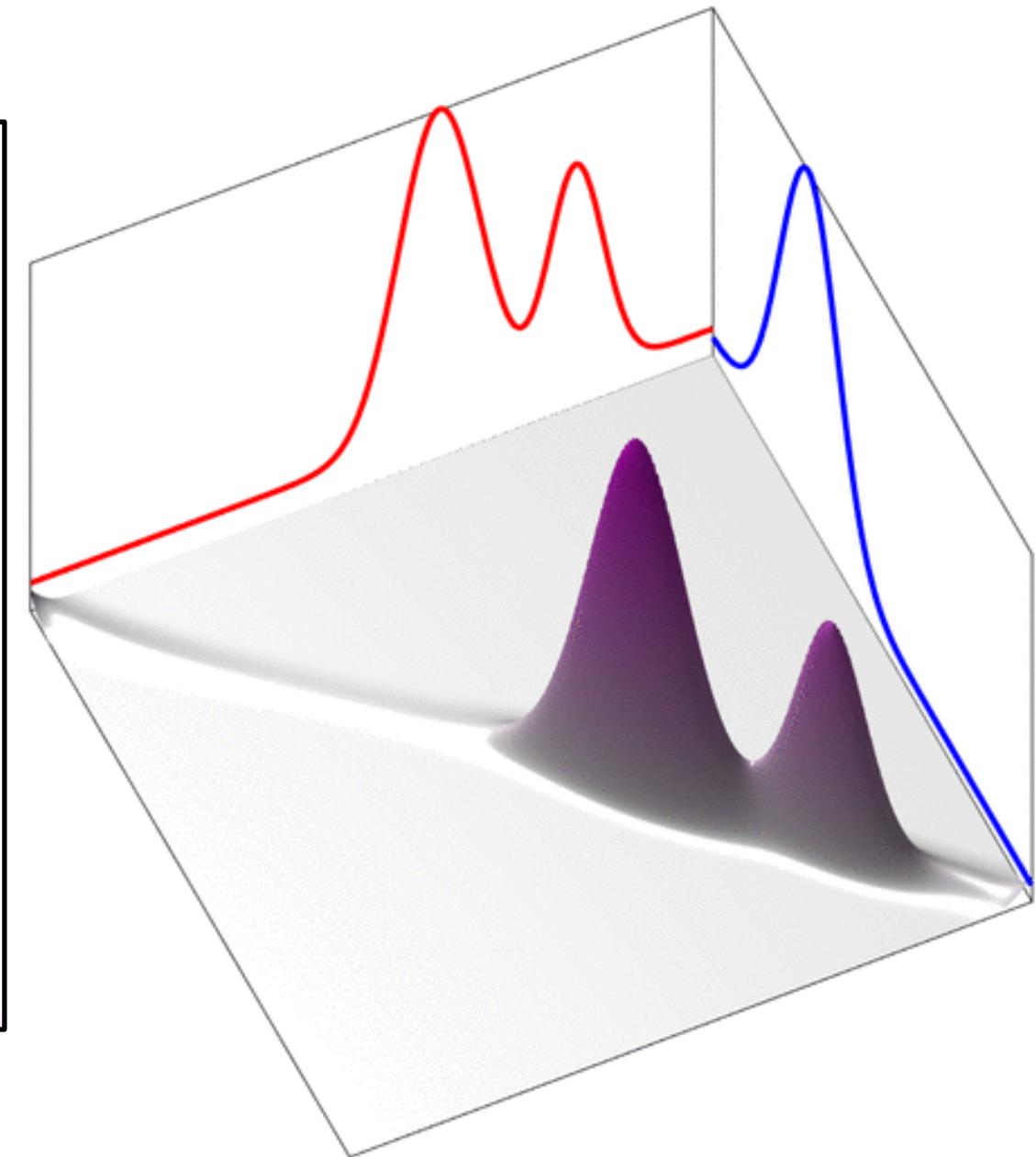
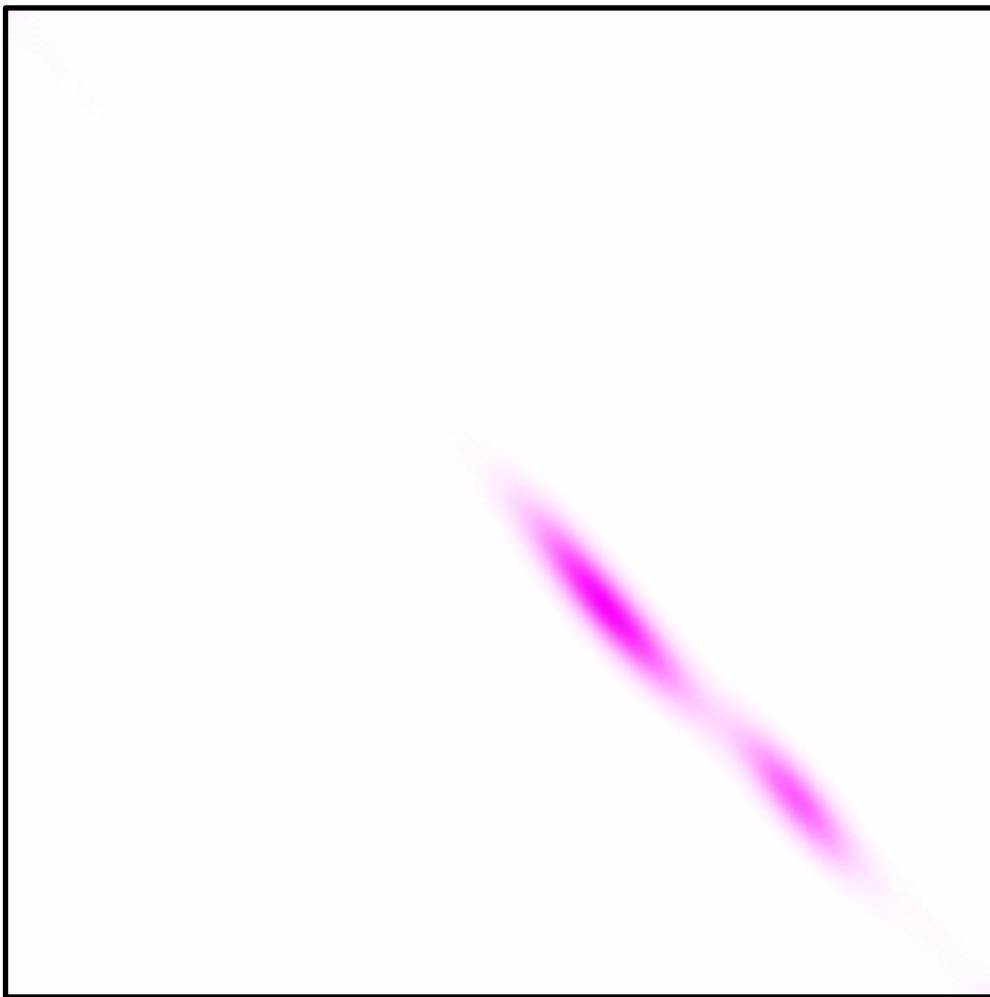
Deming and Stephan in 1940

Sinkhorn 1964

Sinkhorn Evolution

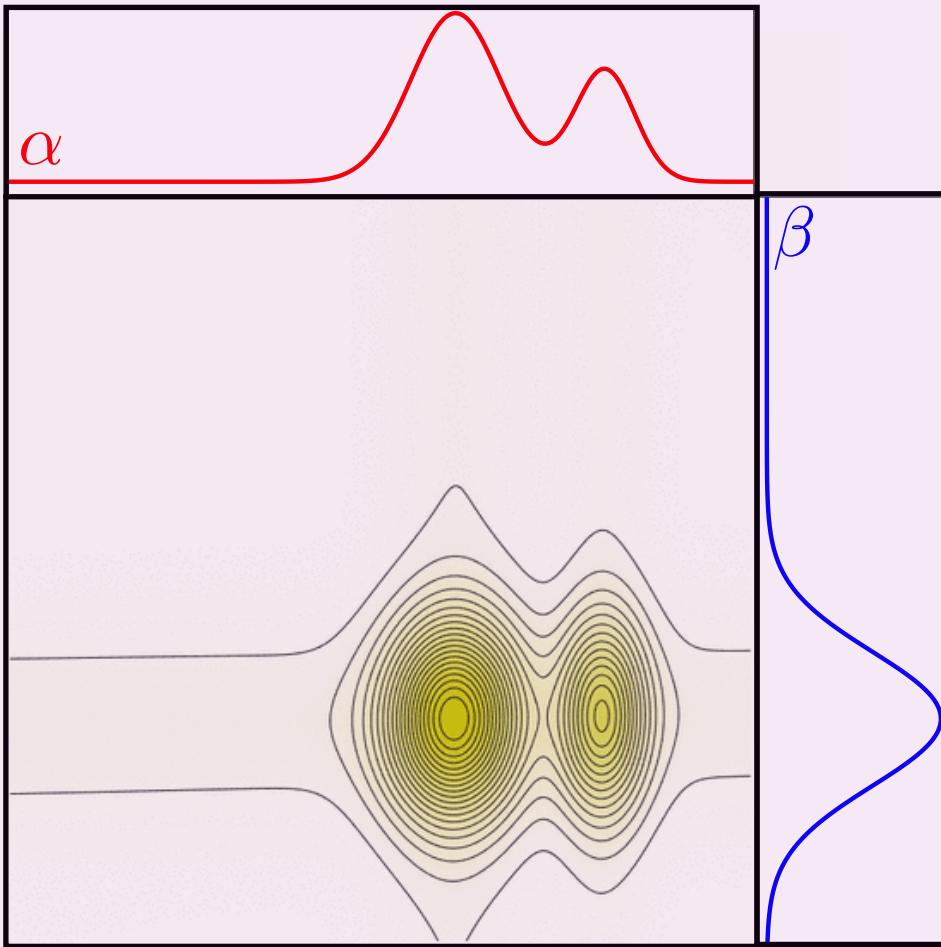


Sinkhorn Evolution



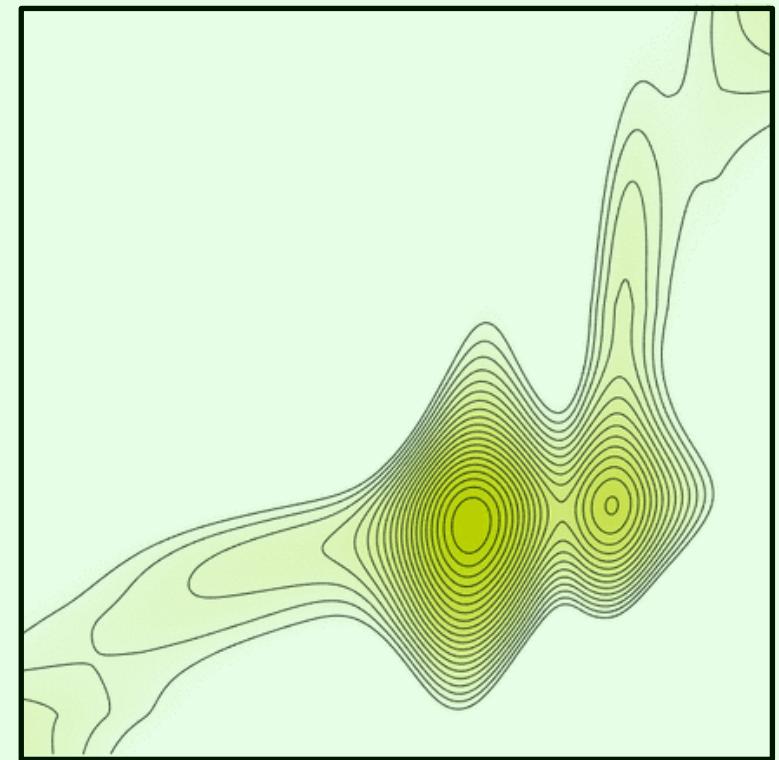
Other Regularizations

$$\min_{\pi} \left\{ \int_{\mathbb{R}^2} \|x - y\|^2 d\pi(x, y) + \varepsilon R(\pi) ; \pi_1 = \alpha, \pi_2 = \beta \right\}$$



$$R(\pi) = \int \log \left(\frac{d\pi}{dxdy} \right) d\pi(x, y)$$

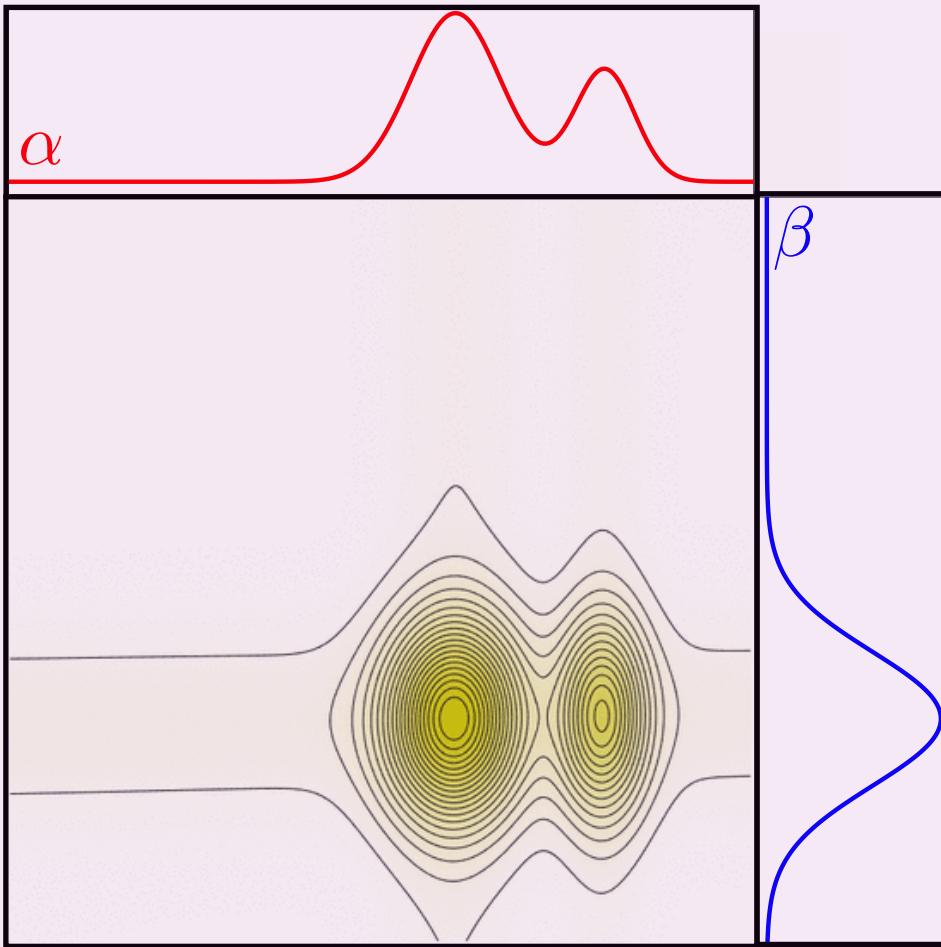
Dykstra's algorithm



$$R(\pi) = \int \left(\frac{d\pi}{dxdy} \right)^2 dx dy$$

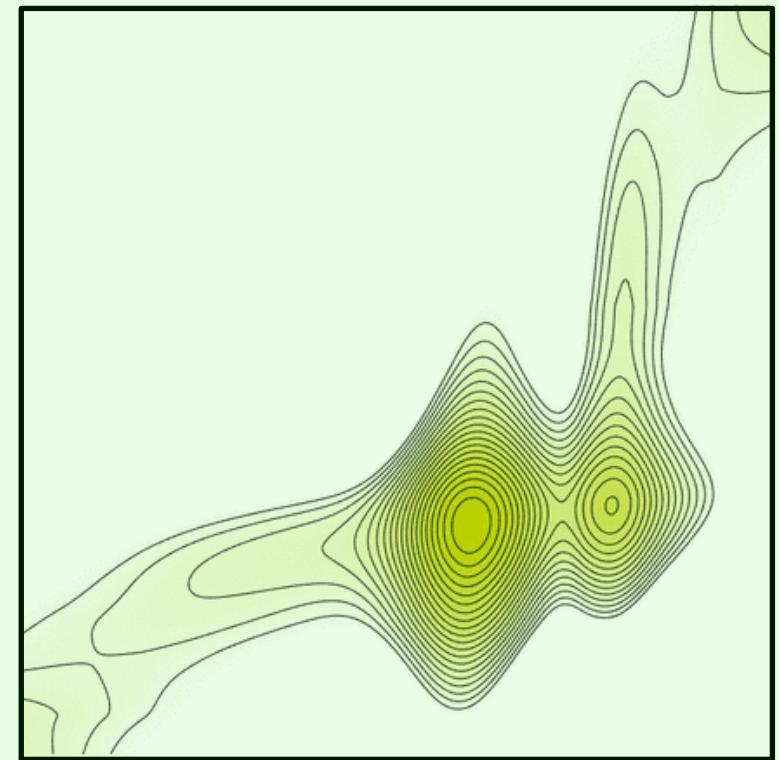
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Unbalanced OT

$$W_p^{\tau,p}(\alpha, \beta) \stackrel{\text{def.}}{=} \min_{\pi} \int d^p d\pi + \tau \text{KL}(\pi_1 | \alpha) + \tau \text{KL}(\pi_2 | \beta)$$

[Liero, Mielke, Savaré 2015]

See also:

[Chizat, Schmitzer, Peyré, Vialard 2015]
[Kondratyev, Monsaingeon, Vorotnikov 2015]

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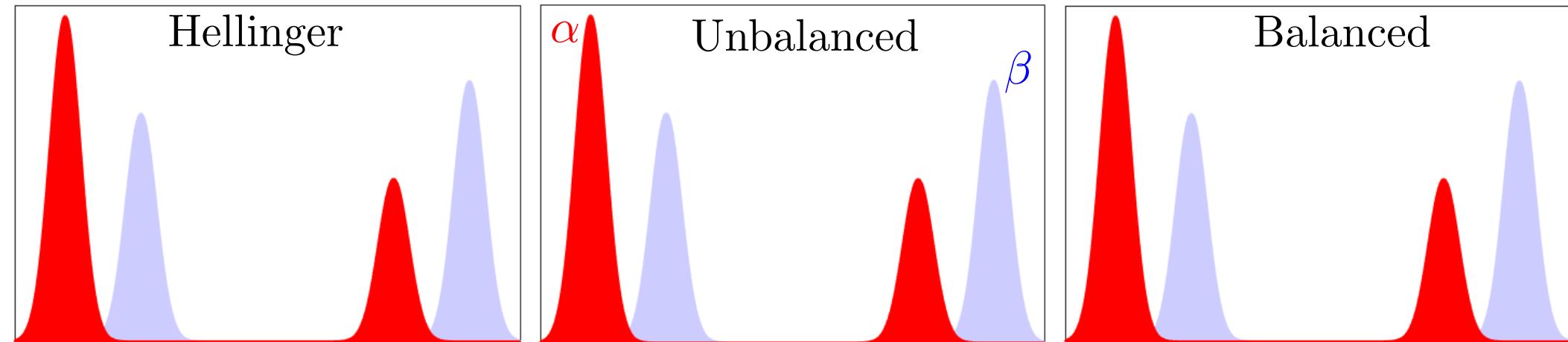
See also: [Chizat, Schmitzer, Peyré, Vialard 2015]
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$$\int (\sqrt{\alpha} - \sqrt{\beta})^2 \xleftarrow{\tau \rightarrow 0} W_p^{\tau,p}(\alpha, \beta) \xrightarrow{\tau \rightarrow +\infty} W_p^p(\alpha, \beta)$$

Hellinger

Unbalanced

Balanced



Unbalanced OT

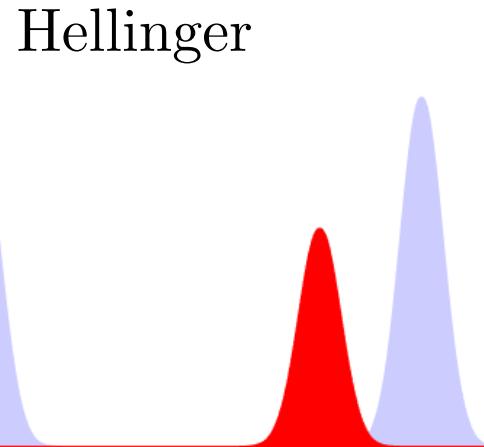
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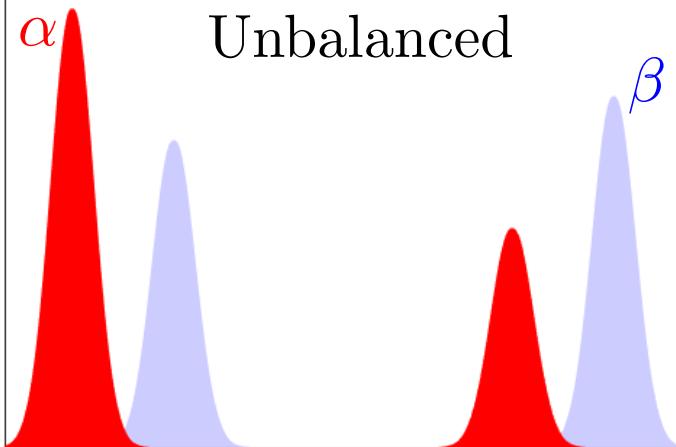
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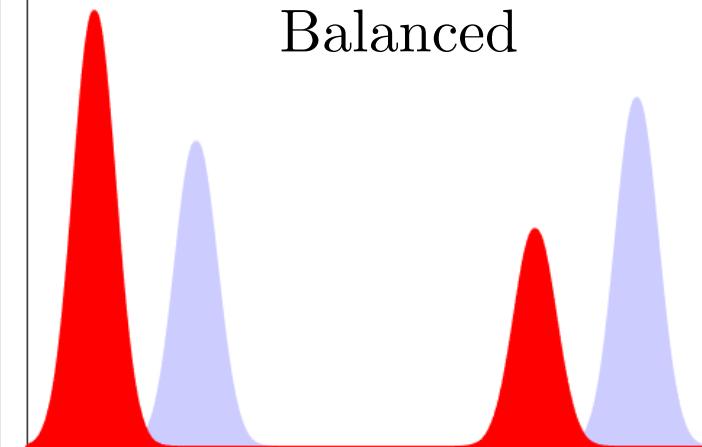
Hellinger



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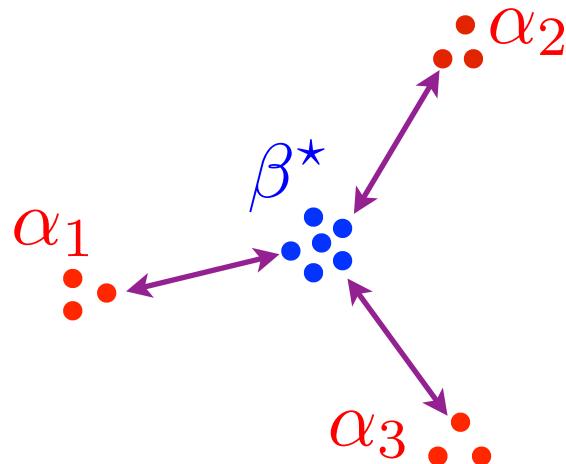
Sinkhorn's algorithm:

$$\mathbf{u} \leftarrow \left(\frac{\mathbf{a}}{\mathbf{K}\mathbf{v}} \right)^{1+\frac{\varepsilon}{\tau}} \quad \longleftrightarrow \quad \mathbf{v} \leftarrow \left(\frac{\mathbf{b}}{\mathbf{K}^\top \mathbf{u}} \right)^{1+\frac{\varepsilon}{\tau}}$$

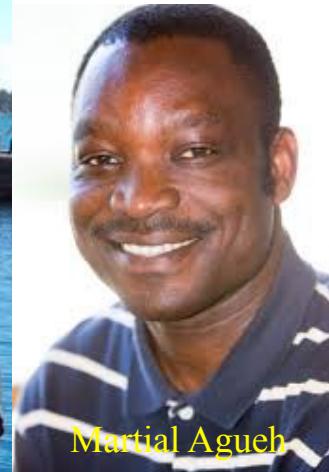
Wasserstein Barycenters

Barycenters of measures $(\alpha_s)_s$: $\sum_s \lambda_s = 1$

$$\beta^* \in \operatorname{argmin}_{\beta} \sum_s \lambda_s W_p^p(\alpha_s, \beta)$$



Guillaume Carlier

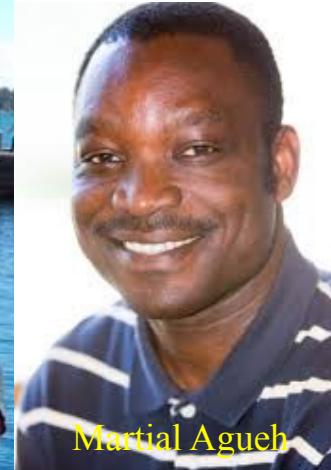
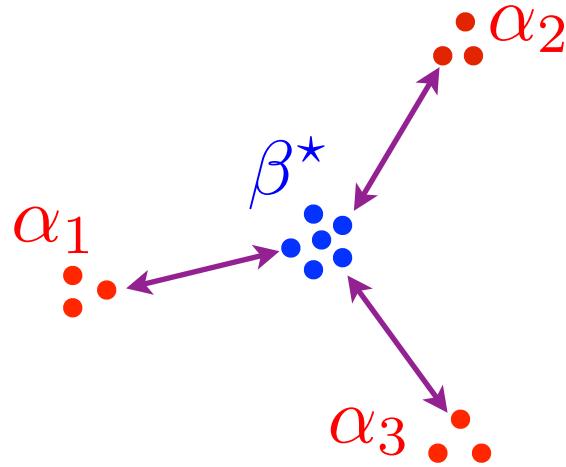


Martial Aguech

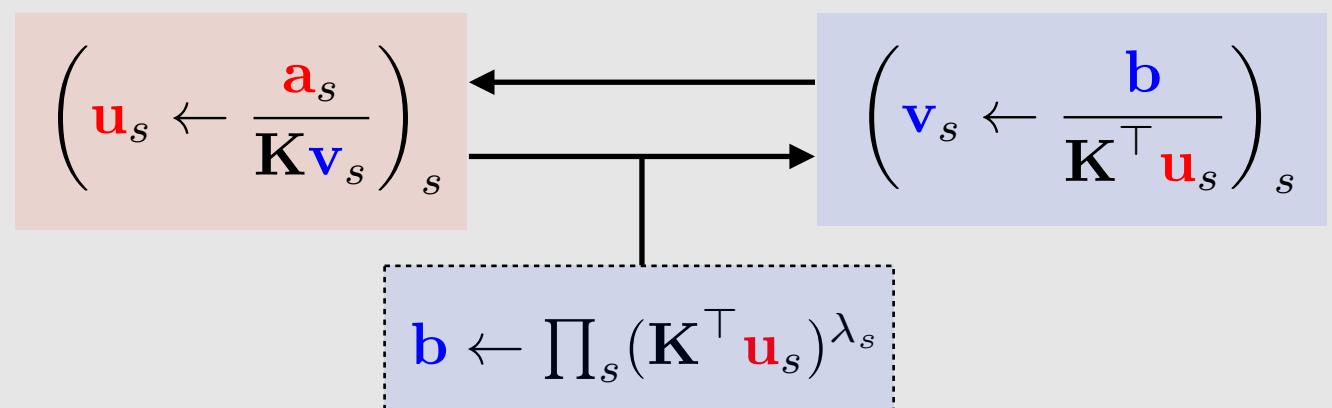
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Sinkhorn's algorithm:



Overview

- Entropic Regularization and Sinkhorn
- **Convergence Analysis**
- Sinkhorn Divergences
- Generative Model Fitting

KL divergence:

$$\text{KL}(\mathbf{P}|\mathbf{K}) \stackrel{\text{def.}}{=} \sum_{i,j} \mathbf{P}_{i,j} \log \left(\frac{\mathbf{P}_{i,j}}{\mathbf{K}_{i,j}} \right) - \mathbf{P}_{i,j} + \mathbf{K}_{i,j}$$

$$\text{KL}(\mathbf{P}|\mathbf{K}) = D_\varphi(\mathbf{P}|\mathbf{K}) \quad \text{for} \quad \varphi(\mathbf{P}) = \sum_{i,j} \mathbf{P}_{i,j} \log(\mathbf{P}_{i,j})$$

$$\min_{\mathbf{P} \in \mathbf{U}(\mathbf{a}, \mathbf{b})} \langle \mathbf{P}, \mathbf{C} \rangle + \varepsilon \text{KL}(\mathbf{P} | \mathbf{a} \otimes \mathbf{b}) \Leftrightarrow \min_{\mathbf{P} \in \mathbf{U}(\mathbf{a}, \mathbf{b})} \varepsilon \text{KL}(\mathbf{P}|\mathbf{K}) \quad \mathbf{K}_{i,j} \stackrel{\text{def.}}{=} e^{-\frac{\mathbf{C}_{i,j}}{\varepsilon}}$$

[Bregman, 1967]

Iterative projections: $\mathbf{P}^{(\ell+1)} \stackrel{\text{def.}}{=} \text{Proj}_{\mathcal{C}_{\mathbf{a}}^1}^{\mathbf{KL}}(\mathbf{P}^{(\ell)})$ and $\mathbf{P}^{(\ell+2)} \stackrel{\text{def.}}{=} \text{Proj}_{\mathcal{C}_{\mathbf{b}}^2}^{\mathbf{KL}}(\mathbf{P}^{(\ell+1)})$

Theorem: $\mathbf{P}^{(\ell)} \rightarrow \mathbf{P}^\star = \underset{\mathbf{P} \in \mathcal{C}_{\mathbf{a}}^1 \cap \mathcal{C}_{\mathbf{b}}^1}{\operatorname{argmin}} \text{KL}(\mathbf{P}|\mathbf{K})$
 For affine $(\mathcal{C}_{\mathbf{a}}^1, \mathcal{C}_{\mathbf{b}}^2)$,

Bregman Iterative Projections

$$\langle \mathbf{P}, \mathbf{C} \rangle + \varepsilon \text{KL}(\mathbf{P}|\mathbf{a} \otimes \mathbf{b}) = \varepsilon \text{KL}(\mathbf{P}|\mathbf{K}) + \text{cst} \quad \text{where} \quad \mathbf{K}_{i,j} = e^{-\frac{\mathbf{C}_{i,j}}{\varepsilon}} \mathbf{a}_i \mathbf{b}_j$$

Shrödinger problem: $\min_{\mathbf{P} \in \mathbf{U}(\mathbf{a}, \mathbf{b})} \text{KL}(\mathbf{P}|\mathbf{K})$

$$\mathbf{U}(\mathbf{a}, \mathbf{b}) = \mathcal{C}_{\mathbf{a}}^1 \cup \mathcal{C}_{\mathbf{b}}^2$$

$$\mathcal{C}_{\mathbf{a}}^1 \stackrel{\text{def.}}{=} \{\mathbf{P} : \mathbf{P}\mathbb{1}_m = \mathbf{a}\}$$

$$\mathcal{C}_{\mathbf{b}}^2 \stackrel{\text{def.}}{=} \left\{ \mathbf{P} : \mathbf{P}^T \mathbb{1}_m = \mathbf{b} \right\}$$

Bregman Iterative Projections

$$\langle \mathbf{P}, \mathbf{C} \rangle + \varepsilon \text{KL}(\mathbf{P}|\mathbf{a} \otimes \mathbf{b}) = \varepsilon \text{KL}(\mathbf{P}|\mathbf{K}) + \text{cst} \quad \text{where} \quad \mathbf{K}_{i,j} = e^{-\frac{\mathbf{C}_{i,j}}{\varepsilon}} \mathbf{a}_i \mathbf{b}_j$$

Shrödinger problem: $\min_{\mathbf{P} \in \mathbf{U}(\mathbf{a}, \mathbf{b})} \text{KL}(\mathbf{P}|\mathbf{K})$

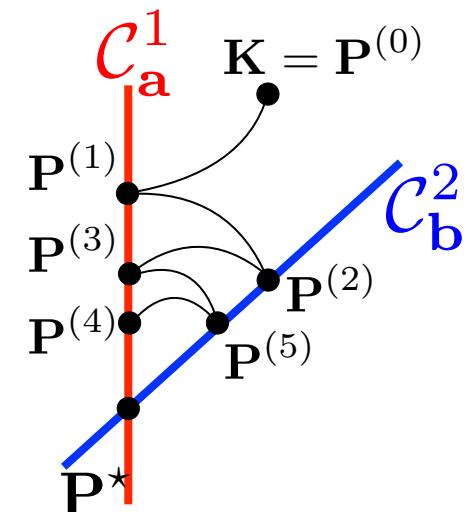
$$\mathbf{U}(\mathbf{a}, \mathbf{b}) = \mathcal{C}_{\mathbf{a}}^1 \cup \mathcal{C}_{\mathbf{b}}^2$$

$$\mathcal{C}_{\mathbf{a}}^1 \stackrel{\text{def.}}{=} \{\mathbf{P} : \mathbf{P}\mathbb{1}_m = \mathbf{a}\}$$

$$\mathcal{C}_{\mathbf{b}}^2 \stackrel{\text{def.}}{=} \left\{ \mathbf{P} : \mathbf{P}^T \mathbb{1}_m = \mathbf{b} \right\}$$

Iterative projections: $\mathbf{P}^{(\ell+1)} \stackrel{\text{def.}}{=} \text{Proj}_{\mathcal{C}_{\mathbf{a}}^1}^{\text{KL}}(\mathbf{P}^{(\ell)})$ and $\mathbf{P}^{(\ell+2)} \stackrel{\text{def.}}{=} \text{Proj}_{\mathcal{C}_{\mathbf{b}}^2}^{\text{KL}}(\mathbf{P}^{(\ell+1)})$

Theorem: $\mathbf{P}^{(\ell)} \rightarrow \mathbf{P}^* = \underset{\mathbf{P} \in \mathcal{C}_{\mathbf{a}}^1 \cap \mathcal{C}_{\mathbf{b}}^2}{\operatorname{argmin}} \text{KL}(\mathbf{P}|\mathbf{K})$
 For affine $(\mathcal{C}_{\mathbf{a}}^1, \mathcal{C}_{\mathbf{b}}^2)$,



Bregman Iterative Projections

$$\langle \mathbf{P}, \mathbf{C} \rangle + \varepsilon \text{KL}(\mathbf{P}|\mathbf{a} \otimes \mathbf{b}) = \varepsilon \text{KL}(\mathbf{P}|\mathbf{K}) + \text{cst} \quad \text{where} \quad \mathbf{K}_{i,j} = e^{-\frac{\mathbf{C}_{i,j}}{\varepsilon}} \mathbf{a}_i \mathbf{b}_j$$

Shrödinger problem: $\min_{\mathbf{P} \in \mathbf{U}(\mathbf{a}, \mathbf{b})} \text{KL}(\mathbf{P}|\mathbf{K})$

$$\mathbf{U}(\mathbf{a}, \mathbf{b}) = \mathcal{C}_{\mathbf{a}}^1 \cup \mathcal{C}_{\mathbf{b}}^2$$

$$\mathcal{C}_{\mathbf{a}}^1 \stackrel{\text{def.}}{=} \{\mathbf{P} : \mathbf{P}\mathbb{1}_m = \mathbf{a}\}$$

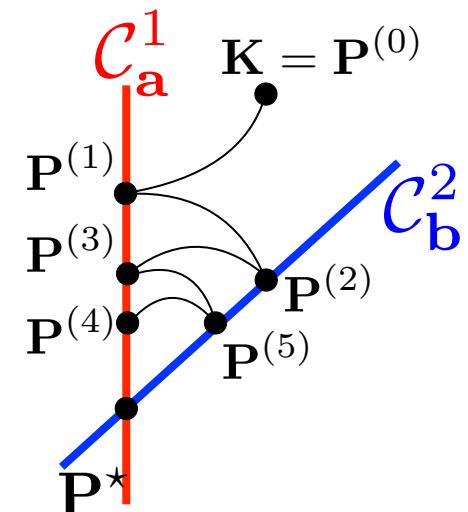
$$\mathcal{C}_{\mathbf{b}}^2 \stackrel{\text{def.}}{=} \left\{ \mathbf{P} : \mathbf{P}^T \mathbb{1}_m = \mathbf{b} \right\}$$

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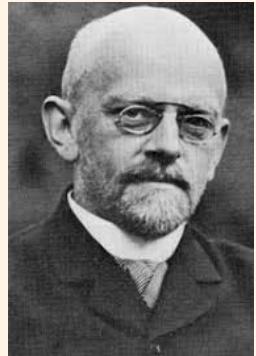
Sinkhorn \iff iterative projections.

$$\mathbf{P}^{(2\ell)} \stackrel{\text{def.}}{=} \text{diag}(\mathbf{u}^{(\ell)}) \mathbf{K} \text{diag}(\mathbf{v}^{(\ell)}), \quad \mathbf{P}^{(2\ell+1)} \stackrel{\text{def.}}{=} \text{diag}(\mathbf{u}^{(\ell+1)}) \mathbf{K} \text{diag}(\mathbf{v}^{(\ell)})$$



Hilbert Projective Metric

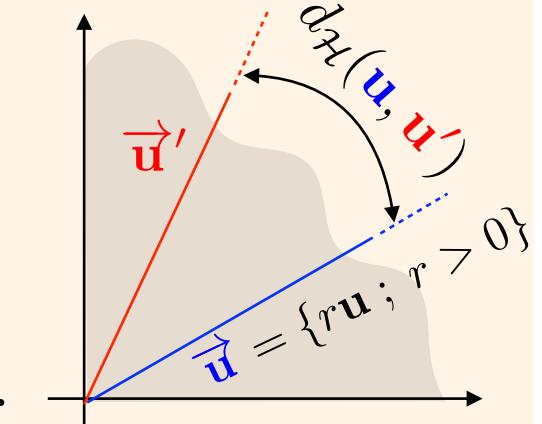
Hilbert's projective metric: $\forall (\mathbf{u}, \mathbf{u}') \in (\mathbb{R}_{+,*}^n)^2$



$$d_{\mathcal{H}}(\mathbf{u}, \mathbf{u}') \stackrel{\text{def.}}{=} \|\log(\mathbf{u}) - \log(\mathbf{u}')\|_V$$

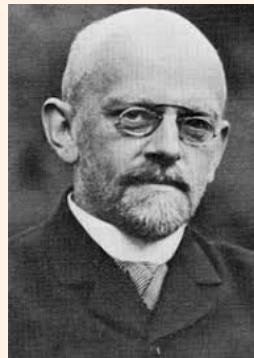
$$\|f\|_V \stackrel{\text{def.}}{=} \max(f) - \min(f)$$

$d_{\mathcal{H}}$ is a distance on the set of rays $\overrightarrow{\mathbf{u}}$.



Hilbert Projective Metric

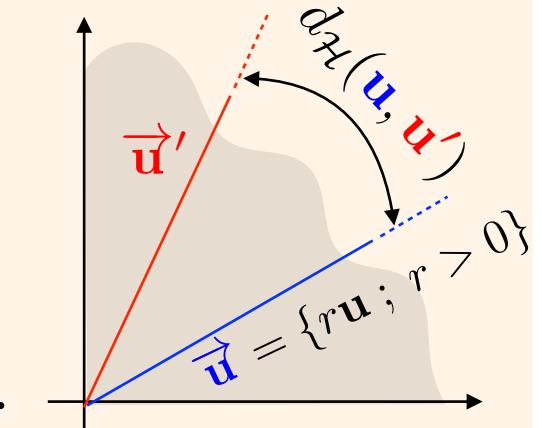
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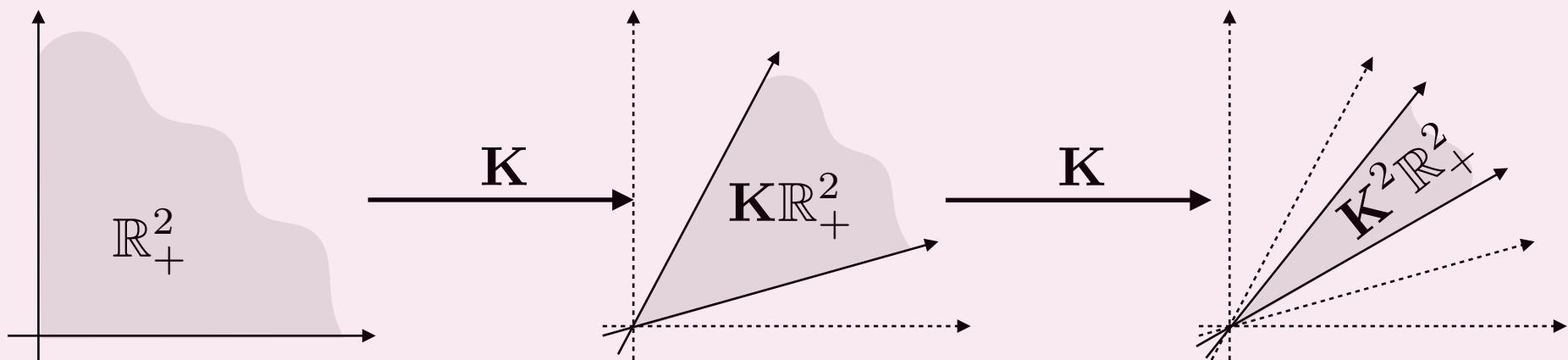
Birkhoff's contraction theorem:



Theorem 1.1. Let $\mathbf{K} \in \mathbb{R}_{+,*}^{n \times m}$, then for $(\mathbf{v}, \mathbf{v}') \in (\mathbb{R}_{+,*}^m)^2$

$$d_{\mathcal{H}}(\mathbf{K}\mathbf{v}, \mathbf{K}\mathbf{v}') \leq \lambda(\mathbf{K})d_{\mathcal{H}}(\mathbf{v}, \mathbf{v}')$$

where $\begin{cases} \lambda(\mathbf{K}) \stackrel{\text{def.}}{=} \frac{\sqrt{\eta(\mathbf{K})}-1}{\sqrt{\eta(\mathbf{K})}+1} < 1 \\ \eta(\mathbf{K}) \stackrel{\text{def.}}{=} \max_{i,j,k,\ell} \frac{\mathbf{K}_{i,k}\mathbf{K}_{j,\ell}}{\mathbf{K}_{j,k}\mathbf{K}_{i,\ell}}. \end{cases}$



Perron Frobenius

Simplex: $\Sigma_k = \{p \in \mathbb{R}_+^k ; \sum_i p_i = 1\}$

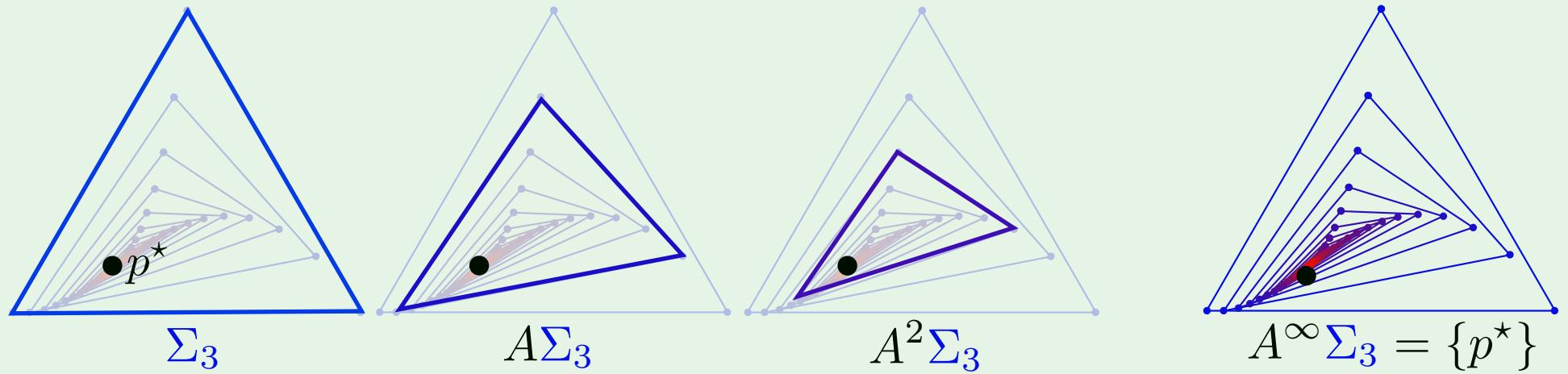
$$A : \Sigma_k \rightarrow \Sigma_k$$

Stochastic matrix: $A \in \mathbb{R}_+^n, A^\top \mathbf{1}_k = \mathbf{1}_k$

Theorem: [Perron-Frobenius]

If $A > 0$, $\exists! p^*$, $Ap^* = p^*$.

$\exists \rho \in [0, 1[, \|A^k p - p^*\| \leq \rho^k$



Sinkhorn under Hilbert's Metric

Sinkhorn iterations:

$$\mathbf{u}^{(\ell+1)} \stackrel{\text{def.}}{=} \frac{\mathbf{a}}{\mathbf{K}\mathbf{v}^{(\ell)}} \quad \text{and} \quad \mathbf{v}^{(\ell+1)} \stackrel{\text{def.}}{=} \frac{\mathbf{b}}{\mathbf{K}^T \mathbf{u}^{(\ell+1)}}$$

[Franklin and Lorenz, 1989]

Theorem: One has $(\mathbf{u}^{(\ell)}, \mathbf{v}^{(\ell)}) \rightarrow (\mathbf{u}^*, \mathbf{v}^*)$

$$d_{\mathcal{H}}(\mathbf{u}^{(\ell)}, \mathbf{u}^*) = O(\lambda(\mathbf{K})^{2\ell}), \quad d_{\mathcal{H}}(\mathbf{v}^{(\ell)}, \mathbf{v}^*) = O(\lambda(\mathbf{K})^{2\ell}).$$

$$d_{\mathcal{H}}(\mathbf{u}^{(\ell)}, \mathbf{u}^*) \leq \frac{d_{\mathcal{H}}(\mathbf{P}^{(\ell)} \mathbb{1}_m, \mathbf{a})}{1 - \lambda(\mathbf{K})^2}$$

$$d_{\mathcal{H}}(\mathbf{v}^{(\ell)}, \mathbf{v}^*) \leq \frac{d_{\mathcal{H}}(\mathbf{P}^{(\ell), \top} \mathbb{1}_n, \mathbf{b})}{1 - \lambda(\mathbf{K})^2}$$

$$\|\log(\mathbf{P}^{(\ell)}) - \log(\mathbf{P}^*)\|_\infty \leq d_{\mathcal{H}}(\mathbf{u}^{(\ell)}, \mathbf{u}^*) + d_{\mathcal{H}}(\mathbf{v}^{(\ell)}, \mathbf{v}^*)$$

Local Analysis of Sinkhorn

Sinkhorn fixed point: $\mathbf{f}^{(\ell+1)} = \Phi(\mathbf{f}^{(\ell)})$

$$\Phi \stackrel{\text{def.}}{=} \Phi_2 \odot \Phi_1 \quad \text{where} \quad \begin{cases} \Phi_1(\mathbf{f}) = \varepsilon \log \mathbf{K}^T(e^{\mathbf{f}/\varepsilon}) - \log(\mathbf{b}), \\ \Phi_2(\mathbf{g}) = \varepsilon \log \mathbf{K}(e^{\mathbf{g}/\varepsilon}) - \log(\mathbf{a}). \end{cases}$$

Proposition: $\partial\Phi(\mathbf{f}) = \text{diag}(\mathbf{a})^{-1} \odot \mathbf{P} \odot \text{diag}(\mathbf{b})^{-1} \odot \mathbf{P}^T$.

For ℓ large enough, $\|\mathbf{f}^{(\ell)} - \mathbf{f}\| = O((1 - \kappa)^\ell)$

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For ℓ large enough, $\|\mathbf{f}^{(\ell)} - \mathbf{f}\| = O((1 - \kappa)^\ell)$

Global rate: $\kappa \sim e^{-\frac{1}{\varepsilon}}$

[Franklin and Lorenz, 1989]

Local rate: $\kappa \sim \varepsilon$

[Robert Berman 2017]

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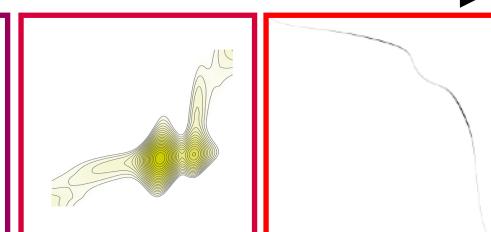
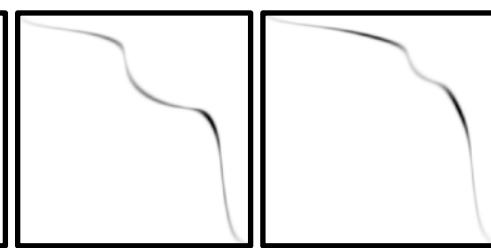
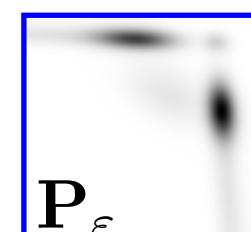
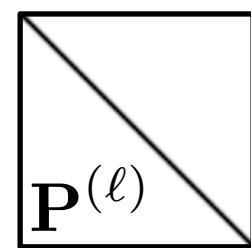
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[Robert Berman 2017]



$$\log(\|\mathbf{P}^{(\ell)} - \mathbf{P}_\varepsilon\|_1)$$

1000 2000 3000 4000 5000

ℓ

ε

Overview

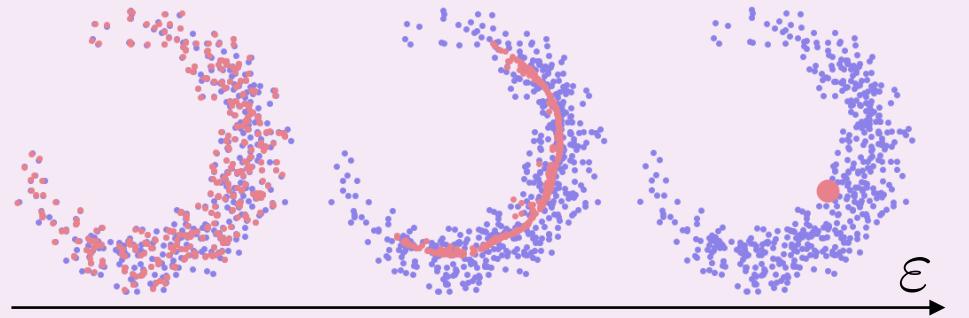
- Entropic Regularization and Sinkhorn
- Convergence Analysis
- **Sinkhorn Divergences**
- Generative Model Fitting

Sinkhorn Divergences

$$W_{\varepsilon,p}^p(\alpha, \beta) \stackrel{\text{def.}}{=} \min_{\pi_1 = \alpha, \pi_2 = \beta} \int_{\mathcal{X}^2} d^p(x, y) d\pi(x, y) + \varepsilon \text{KL}(\pi | \xi)$$

Problem: $W_\varepsilon(\alpha, \alpha) \neq 0$

$$\min_{\alpha} W_{\varepsilon,p}^p(\alpha, \beta)$$

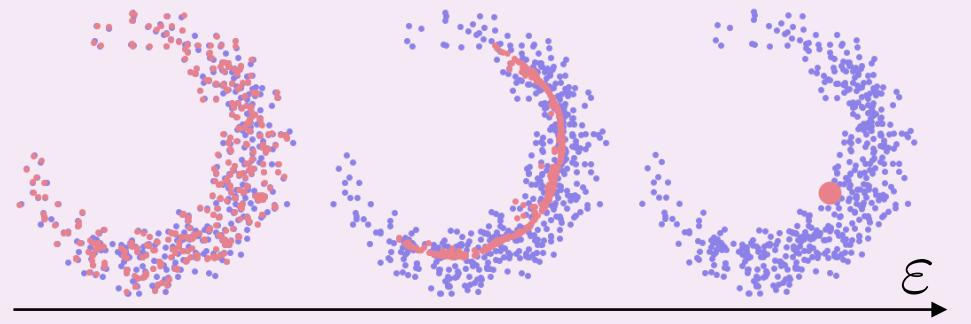


Sinkhorn Divergences

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$$\min_{\alpha} W_{\varepsilon,p}^p(\alpha, \beta)$$



$$\overline{W}_{p,\varepsilon}^p(\alpha, \beta) \stackrel{\text{def.}}{=} W_{p,\varepsilon}^p(\alpha, \beta) - \frac{1}{2} W_{p,\varepsilon}^p(\alpha, \alpha) - \frac{1}{2} W_{p,\varepsilon}^p(\beta, \beta)$$

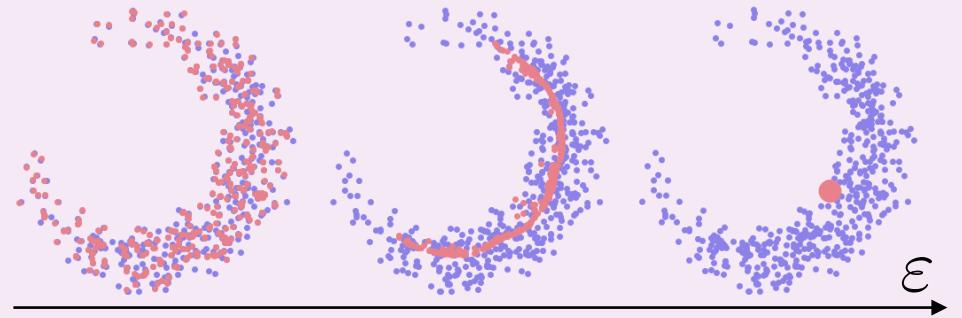
[Ramdas, García Trillo, Cuturi, 2017]

Sinkhorn Divergences

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[Ramdas, García Trillos, Cuturi, 2017]

$$\text{Theorem: } W_p^p(\alpha, \beta) \xleftarrow[\substack{[Léonard 2012] \\ [Carlier et al 2017]}}^{\varepsilon \rightarrow 0} \overline{W}_{\varepsilon,p}^p(\alpha, \beta) \xrightarrow[\substack{[Ramdas, García Trillos, \\ Cuturi, 2017]}]{\varepsilon \rightarrow +\infty} \|\alpha - \beta\|_{-d^p}^2$$

Kernel norms (MMD): $\|\xi\|_{-d^p}^2 \stackrel{\text{def.}}{=} - \int_{\mathcal{X}^2} d(x, y)^p d\xi(x) d\xi(y)$

Proposition: $\|\cdot\|_{-\|\cdot\|_p}$ is a norm for $0 < p < 2$.



Arthur
Gretton

Sinkhorn Divergences

$$\overline{W}_{p,\varepsilon}^p(\alpha, \beta) \stackrel{\text{def.}}{=} W_{p,\varepsilon}^p(\alpha, \beta) - \frac{1}{2} W_{p,\varepsilon}^p(\alpha, \alpha) - \frac{1}{2} W_{p,\varepsilon}^p(\beta, \beta)$$

↓ concave ↓ concave

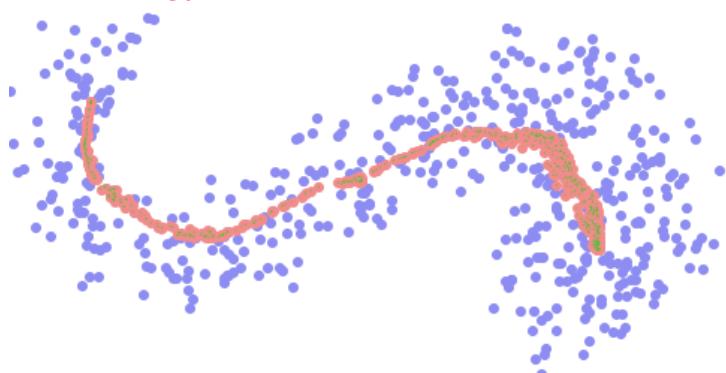
Theorem: [Feydy, Séjourné, P, Vialard, Trouvé, Amari 2018]

If $e^{-\frac{d^p}{\varepsilon}}$ is positive:

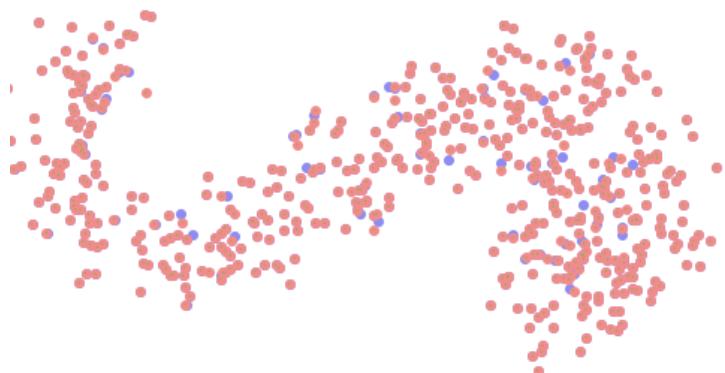
$\overline{W}_{\varepsilon,p} \geqslant 0$ and $\overline{W}_{\varepsilon,p}^p(\cdot, \beta)$ is convex.

$\overline{W}_{\varepsilon,p}(\alpha_n, \beta) \rightarrow 0 \iff \alpha_n \xrightarrow{\text{weak*}} \beta$

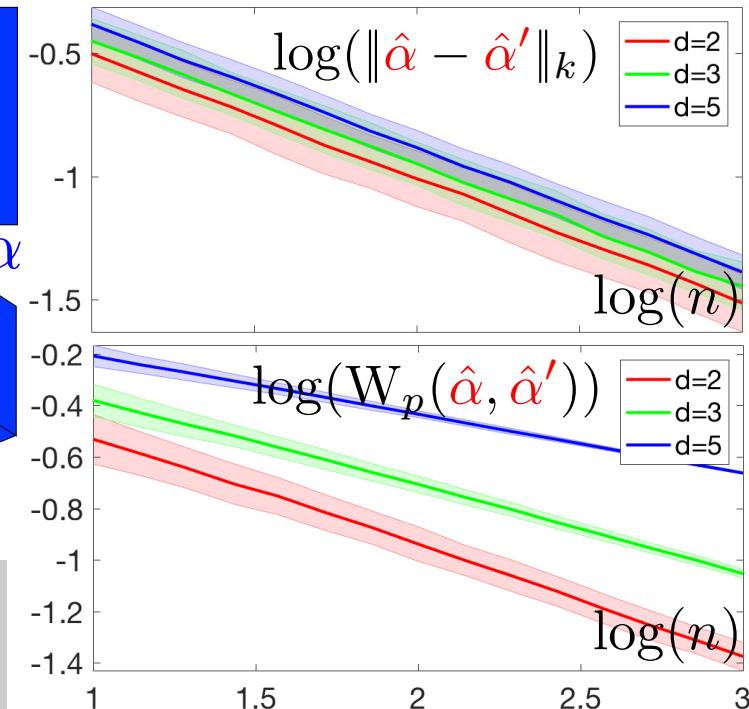
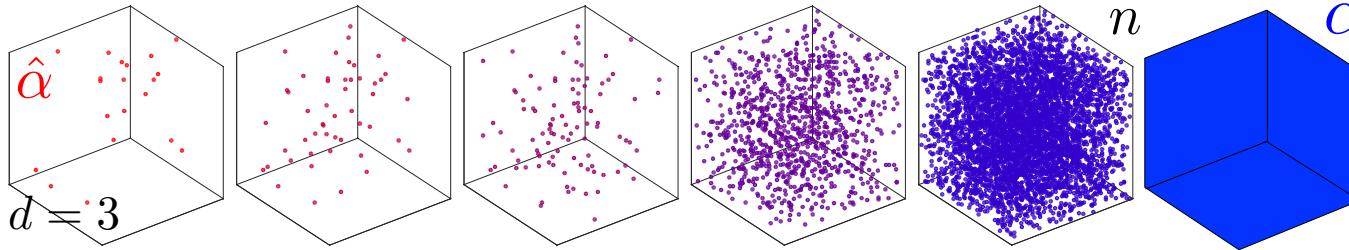
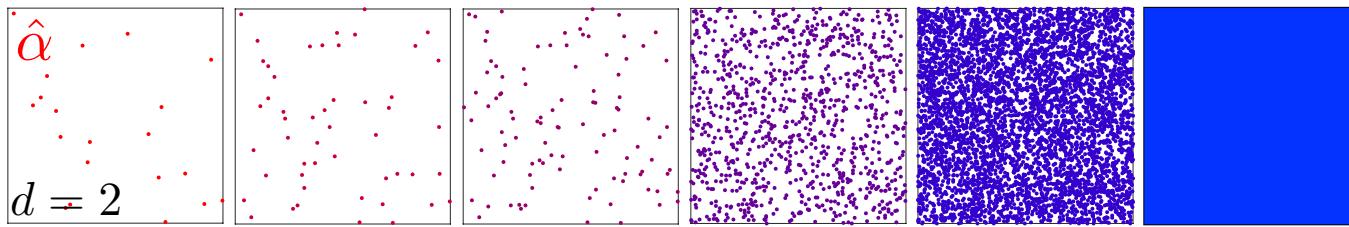
$$\min_{\alpha} W_{\varepsilon,p}^p(\alpha, \beta)$$



$$\min_{\alpha} \overline{W}_{\varepsilon,p}^p(\alpha, \beta)$$



Sample Complexity

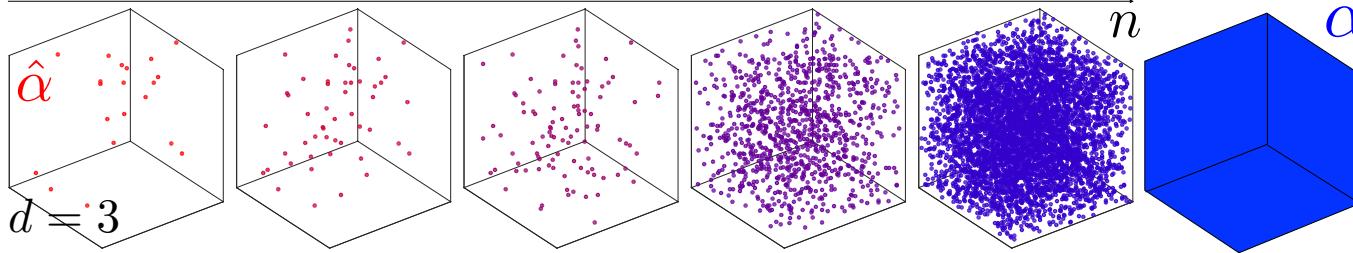
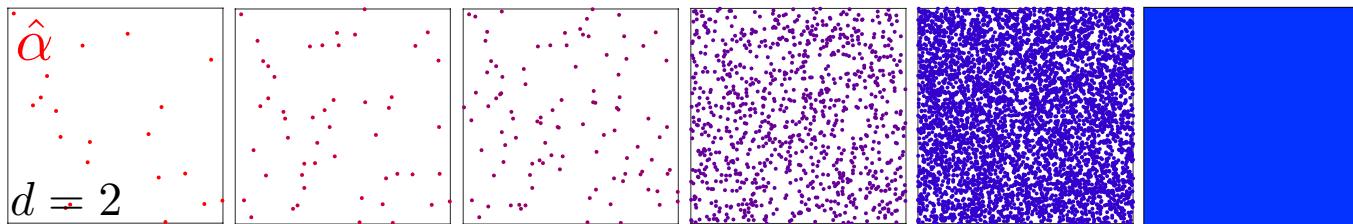


Theorem: $\mathbb{E}(|W_p(\hat{\alpha}, \hat{\beta}) - W_p(\alpha, \beta)|) = O(n^{-\frac{1}{d}})$
 $\mathbb{E}(|\|\hat{\alpha} - \hat{\beta}\|_k - \|\alpha - \beta\|_k|) = O(n^{-\frac{1}{2}})$

Optimal transport: suffers from curse of dimensionality.

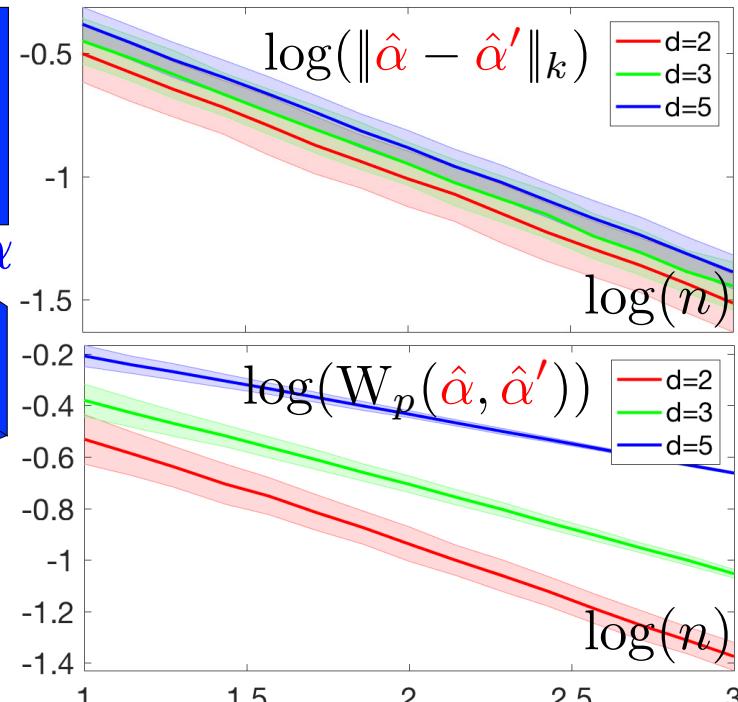
→ Adapt to support dimensionality [Weed, Bach 2017]

Sample Complexity



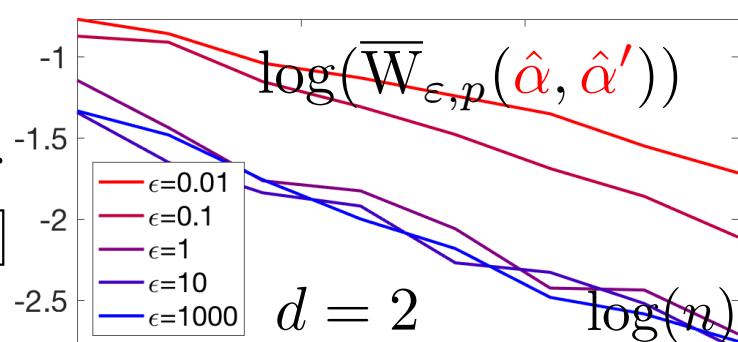
Theorem:

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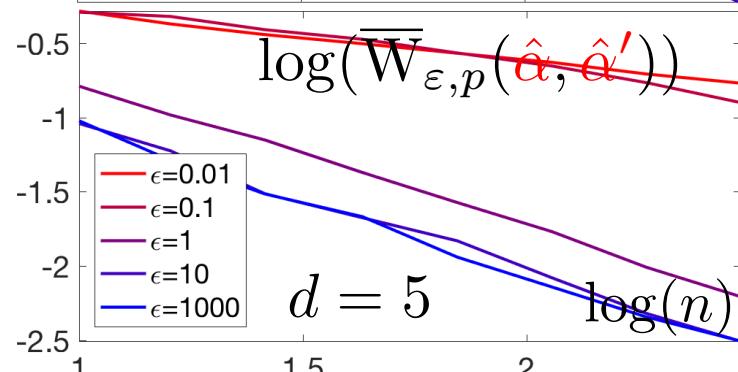
Optimal transport: suffers from curse of dimensionality.

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Theorem: [Genevay, Bach, P, Cuturi]

$$\mathbb{E}(|\bar{W}_{\epsilon,p}(\hat{\alpha}, \hat{\beta}) - \bar{W}_{\epsilon,p}(\alpha, \beta)|) = O(\epsilon^{-\frac{d}{2}} n^{-\frac{1}{2}})$$



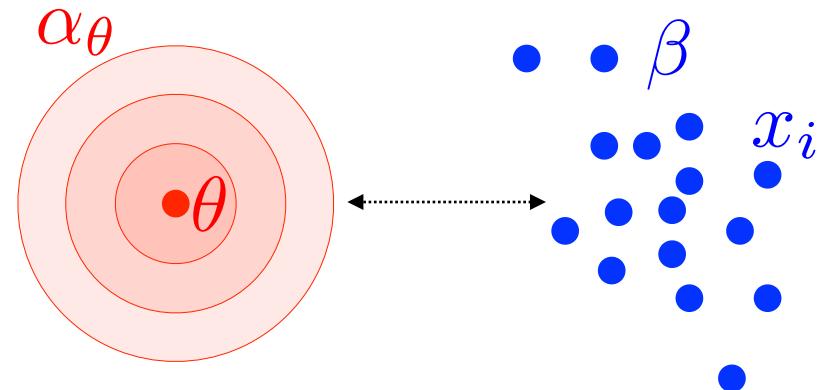
Overview

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- **Generative Model Fitting**

Density Fitting and Generative Models

Observations: $\beta \stackrel{\text{def.}}{=} \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$

Parametric model: $\theta \mapsto \alpha_\theta$



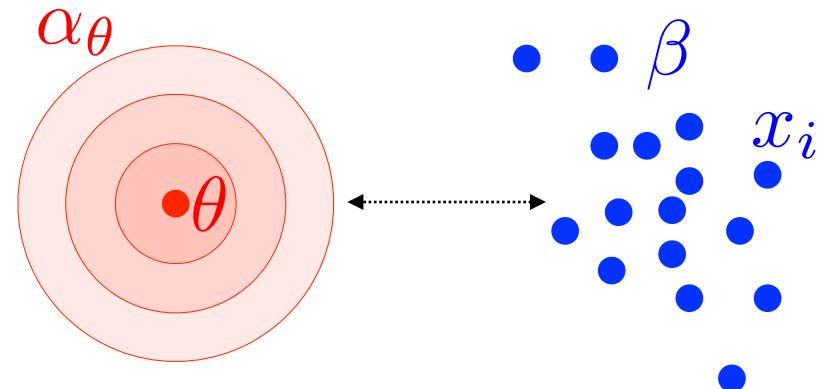
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Parametric model: $\theta \mapsto \alpha_\theta$

Density fitting: $d\alpha_\theta(x) = \rho_\theta(x)dx$

$$\min_{\theta} \widehat{\text{KL}}(\alpha_\theta | \beta) \stackrel{\text{def.}}{=} - \sum_i \log(\rho_\theta(x_i))$$

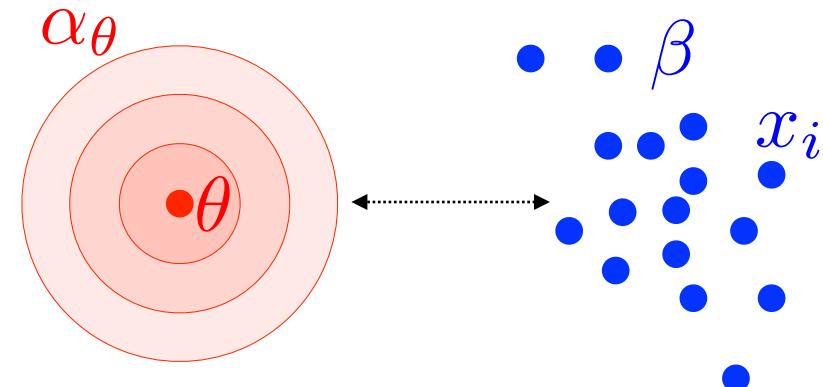


Maximum likelihood (MLE)

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Maximum likelihood (MLE)

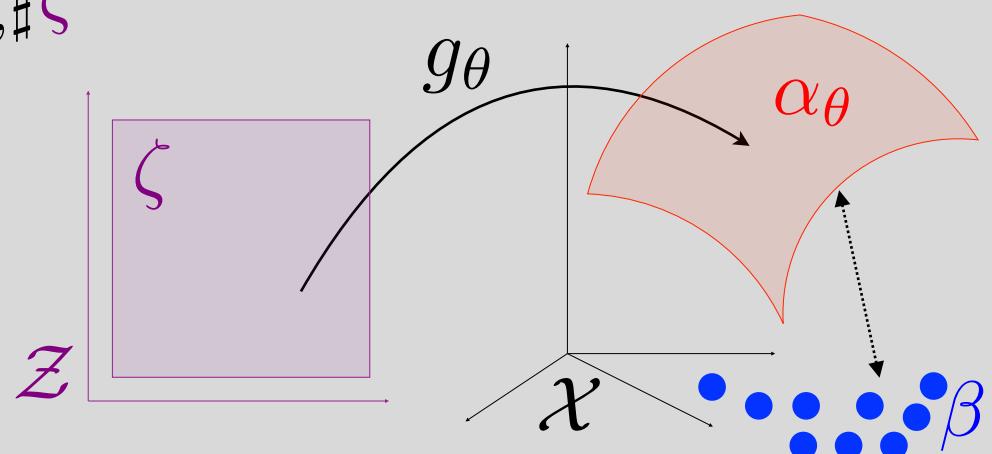
Generative model fit: $\alpha_\theta = g_{\theta, \sharp} \zeta$

$$\widehat{\text{KL}}(\alpha_\theta | \beta) = +\infty$$

→ MLE undefined.

→ Need a weaker metric.

$$\min_{\theta} \overline{W}_{\varepsilon, p}^p(\alpha_\theta, \beta)$$



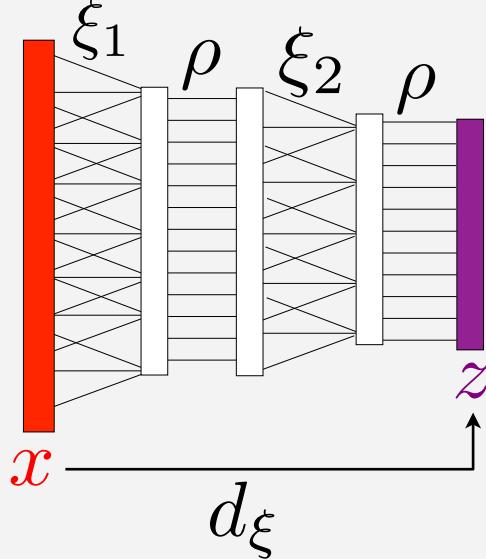
Deep Discriminative vs Generative Models

Deep networks:

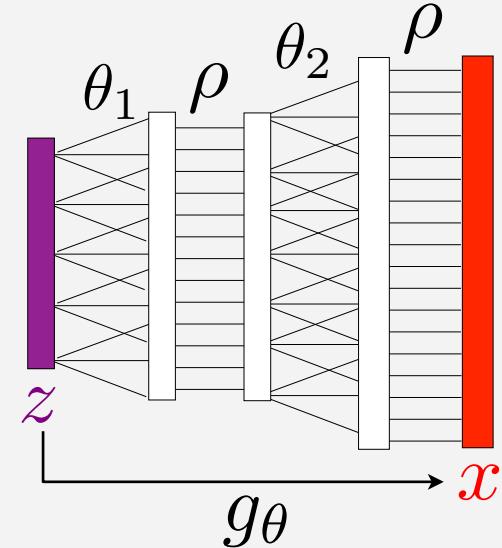
$$d_\xi(\textcolor{red}{x}) = \rho(\xi_K(\dots \rho(\xi_2(\rho(\xi_1(\textcolor{red}{x}) \dots)$$

$$g_\theta(\textcolor{violet}{z}) = \rho(\theta_K(\dots \rho(\theta_2(\rho(\theta_1(\textcolor{violet}{z}) \dots)$$

Discriminative



Generative



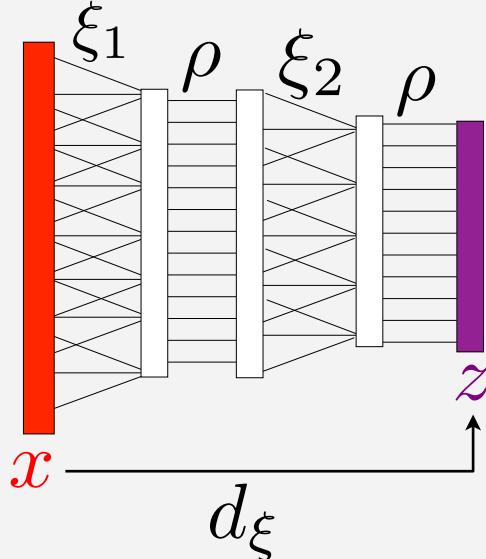
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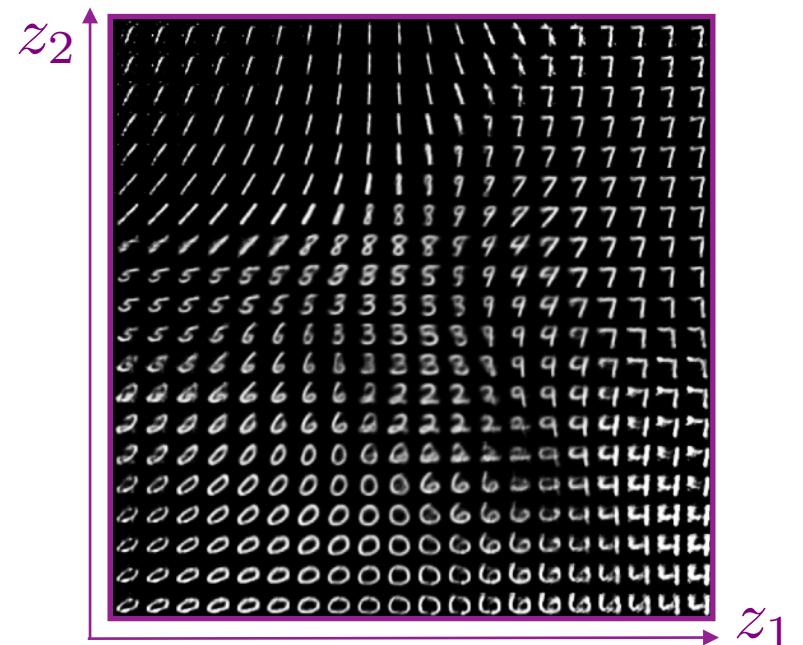
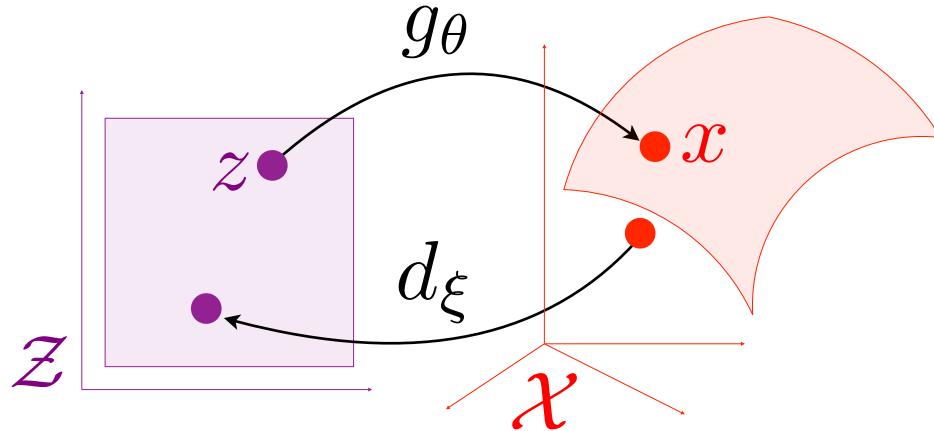
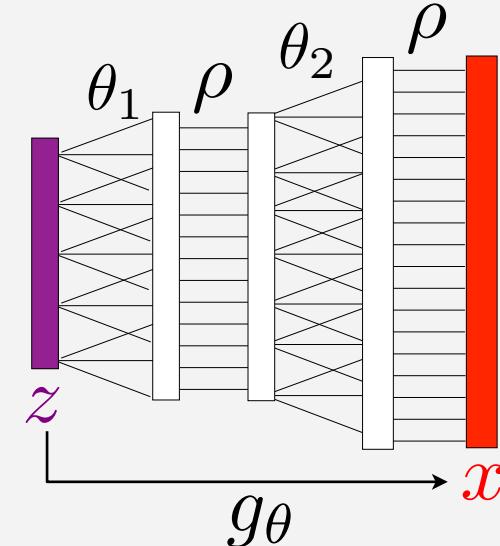
$$d_\xi(\mathbf{x}) = \rho(\xi_K(\dots \rho(\xi_2(\rho(\xi_1(\mathbf{x}) \dots)$$

$$g_\theta(\mathbf{z}) = \rho(\theta_K(\dots \rho(\theta_2(\rho(\theta_1(\mathbf{z}) \dots)$$

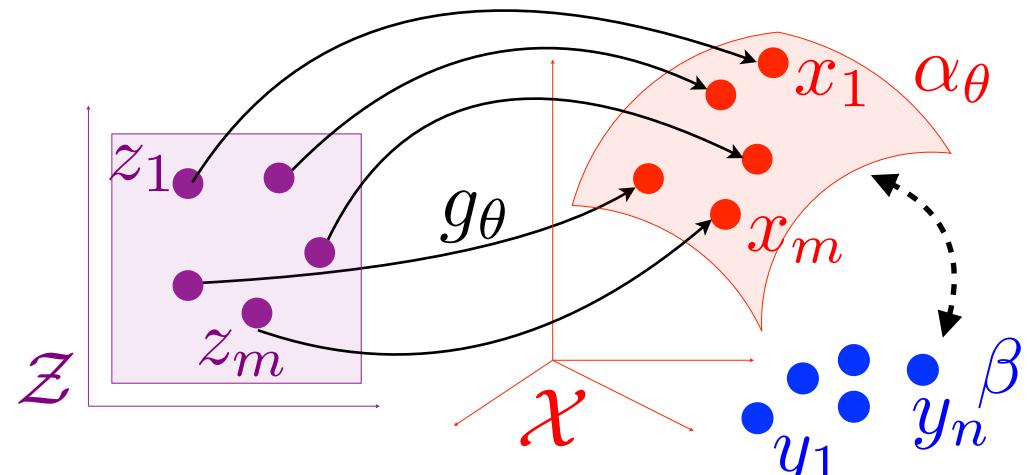
Discriminative



Generative



Training Architecture



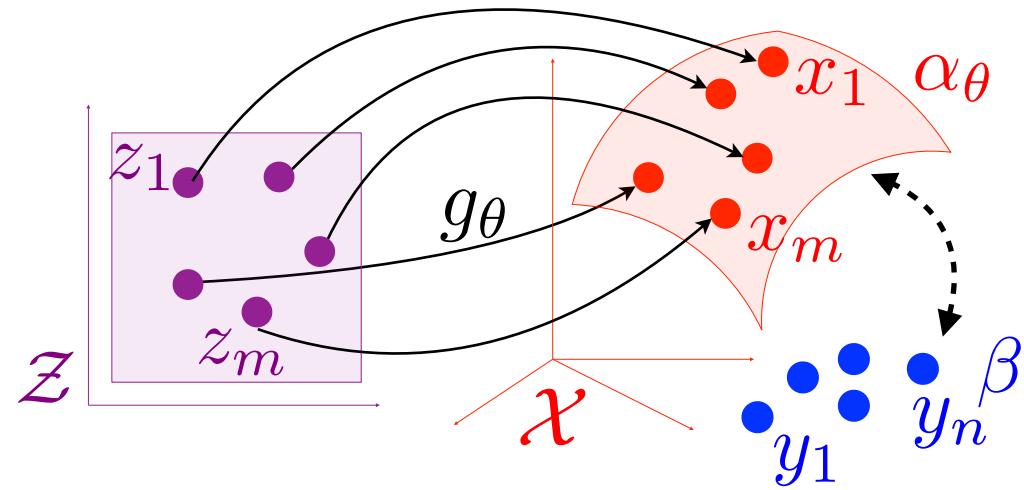
$$\min_{\theta} \mathcal{E}(\theta) \stackrel{\text{def.}}{=} \overline{\mathbf{W}}_{\varepsilon,p}^p(\alpha_\theta, \beta)$$

Stochastic gradient descent

$$\theta \leftarrow \theta - \tau \nabla \hat{\mathcal{E}}(\theta)$$

$$\hat{\mathcal{E}}(\theta) \stackrel{\text{def.}}{=} \overline{\mathbf{W}}_{\varepsilon,p}^p\left(\frac{1}{m} \sum_i \delta_{g_\theta(z_i)}, \beta\right)$$

Training Architecture

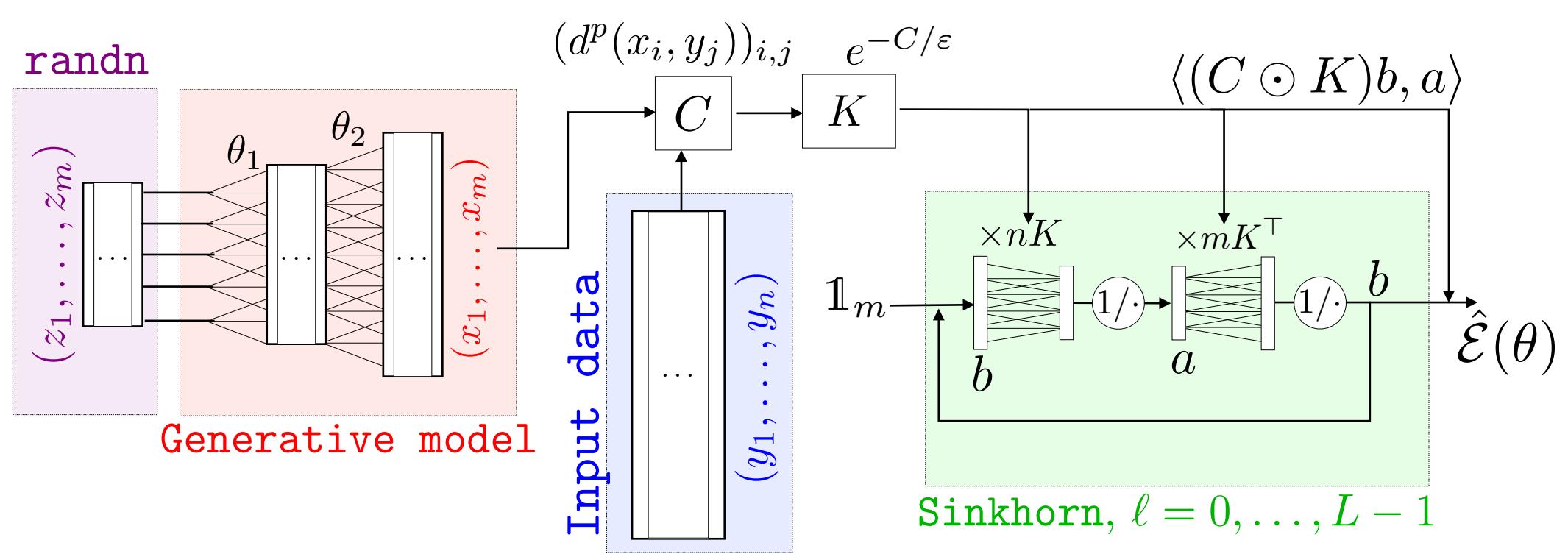


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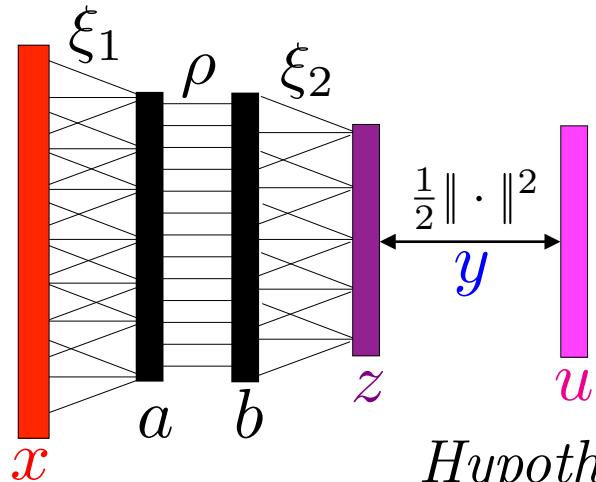
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Automatic Differentiation

Setup: $\mathcal{E} : \mathbb{R}^n \rightarrow \mathbb{R}$ computable in K operations.



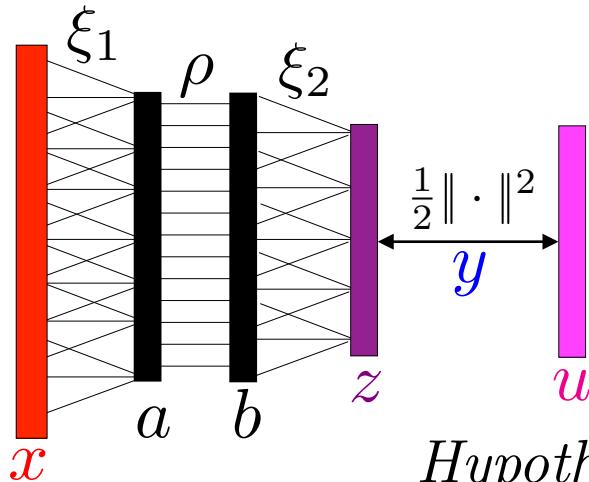
```
function y = E(x)
  a = xi1*x
  b = rho(a)
  z = xi2*b
  y = 1/2*norm(z-u)^2
```

Hypothesis: elementary operations ($a \times b, \log(a), \sqrt{a} \dots$)
and their derivatives cost $O(1)$.

Question: What is the complexity of computing $\nabla \mathcal{E} : \mathbb{R}^n \rightarrow \mathbb{R}^n$?

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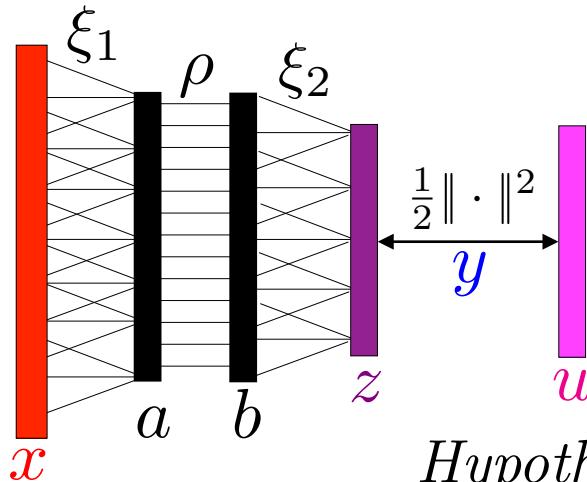
Finite differences:

$$\nabla \mathcal{E}(\theta) \approx \frac{1}{\varepsilon} (\mathcal{E}(\theta + \varepsilon \delta_1) - \mathcal{E}(\theta), \dots, \mathcal{E}(\theta + \varepsilon \delta_n) - \mathcal{E}(\theta))$$

$K(n+1)$ operations, intractable for large n .

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```
function dx = nablaE(x)
    dz = z-u
    db = xi2'*dz
    da = diag(dphi(a)) * db
    dx = xi1'*da
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Theorem: there is an algorithm to compute $\nabla \mathcal{E}$
in $O(K)$ operations. [Seppo Linnainmaa, 1970]

This algorithm is reverse mode automatic differentiation



Seppo
Linnainmaa

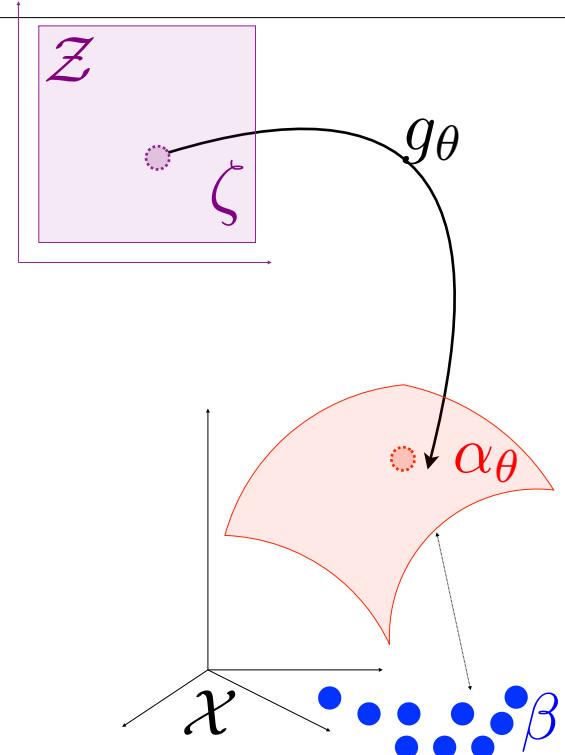
Examples of Images Generation

Inputs β

3	4	2	1	9	5	6	2	1
8	9	1	2	5	0	0	6	6
6	7	0	1	6	3	6	3	7
3	7	7	9	4	6	6	1	8
2	9	3	4	3	9	8	7	2
1	5	9	8	3	6	5	7	2
9	3	1	9	1	5	8	0	8
5	6	2	6	8	5	8	8	9
3	7	7	0	9	4	8	5	4

Generated α_θ

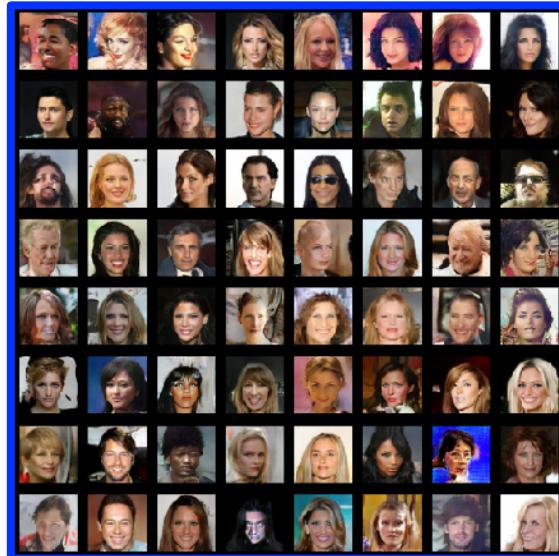
9	4	7	3	3	7	6	8
5	5	1	0	8	1	2	0
5	4	0	8	0	0	5	9
8	8	6	0	7	2	4	7
3	9	0	6	1	9	1	8
4	2	6	7	9	3	6	2
8	7	0	8	4	8	5	7
2	6	0	5	3	4	0	3



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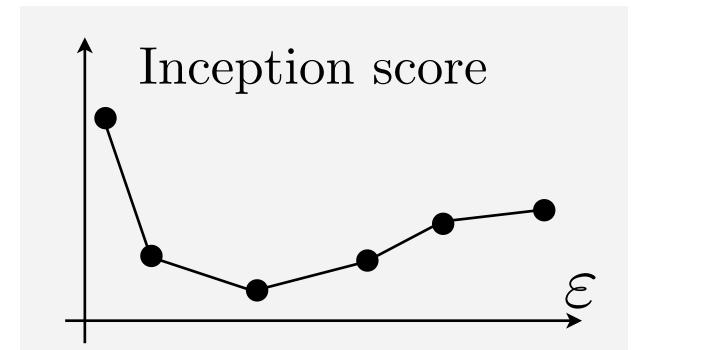
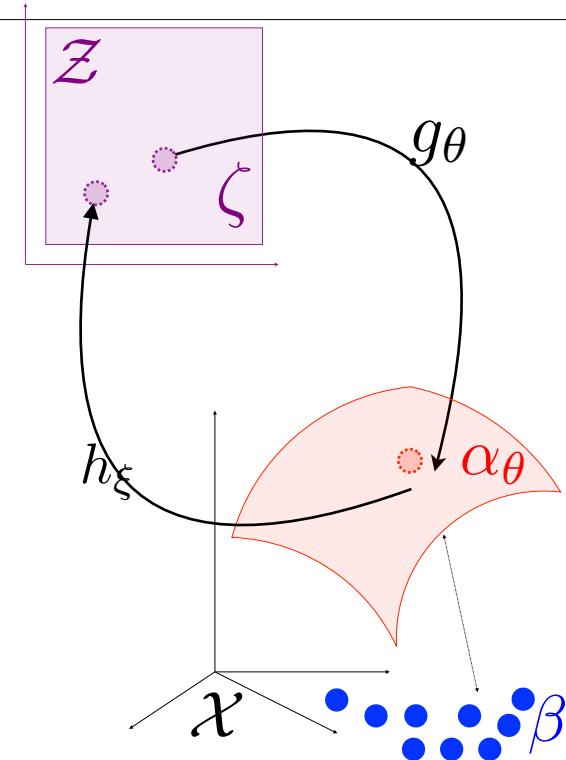
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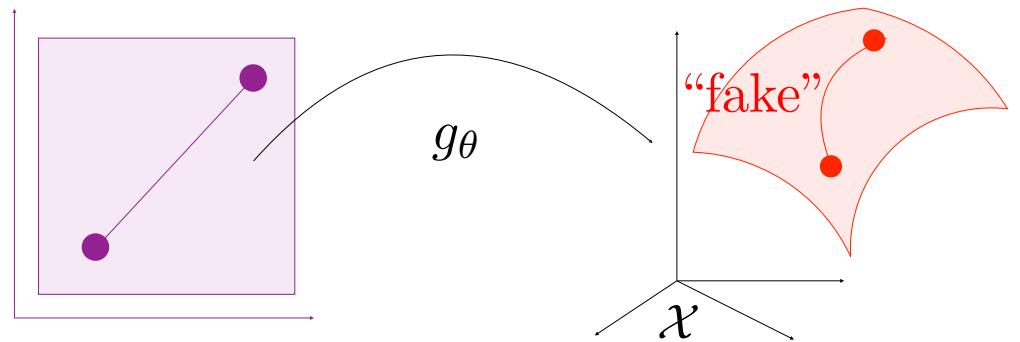
- Need to learn the metric $d(x, y) = \|h_\xi(x) - h_\xi(y)\|$ (GANs)
- Influence of ϵ ?
- Performance evaluation of generative models is an open problem.

Ian Goodfellow



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