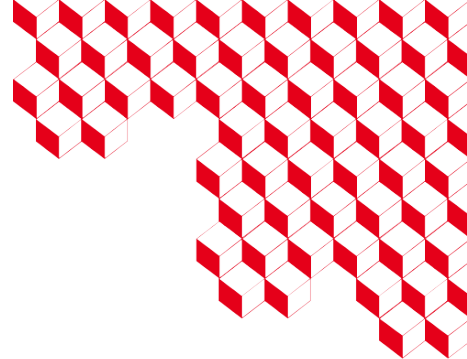




Bayesian calibration with functional outputs with elastic partial matching

| 08/10/2025

Paul Castéras^{1,2,3}, Josselin Garnier¹, Julien Bect² & Gwenaél Salin³

¹ CMAP, CNRS, École polytechnique, Institut polytechnique de Paris, 91120 Palaiseau, France

² Université Paris-Saclay, CNRS, CentraleSupélec, Laboratoire des signaux et systèmes, 91190, Gif-sur-Yvette, France

³ CEA, DAM, DIF, F-91297, Arpajon, France, paul.casteras@cea.fr

Table of contents

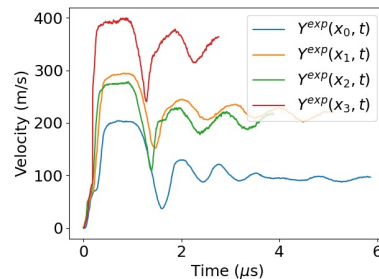
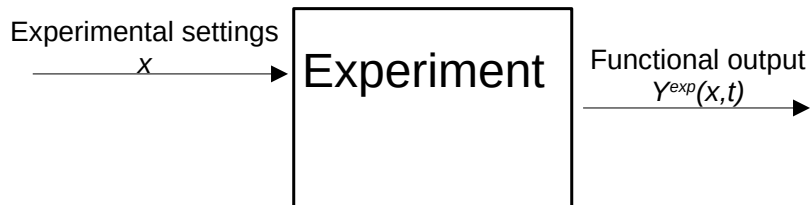
- 1 Bayesian calibration
- 2 Elastic calibration with partial alignment
- 3 Anharmonic oscillator
- 4 References



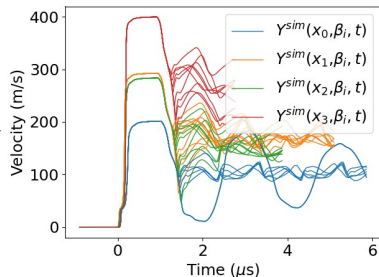
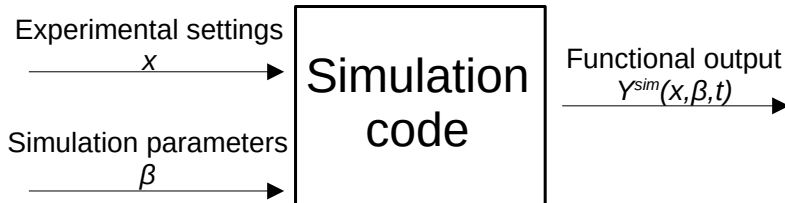
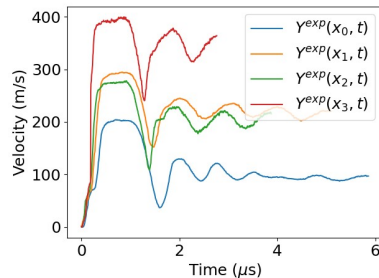
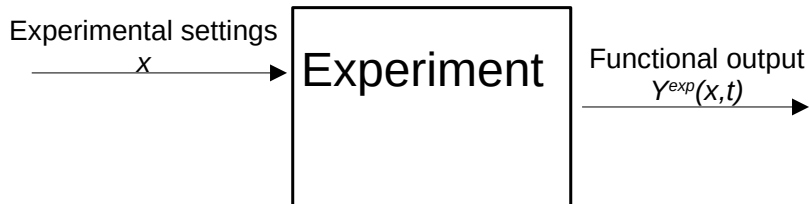
1.

BAYESIAN CALIBRATION

Calibration of functional outputs



Calibration of functional outputs



How to estimate/calibrate the parameter β ?

Bayesian calibration with functional outputs

Introduced by [Kennedy and O'Hagan, 2001] and extended to functional outputs by [Higdon et al., 2008].

Linking experiments, simulations, and the true model:

- Measurement error:

$$Y^{\text{exp}}(x, t) = Y^{\text{true}}(x, t) + \varepsilon^{\text{mes}}(x, t), \quad \varepsilon^{\text{mes}}(x, t) \sim \mathcal{N}(0, \sigma_{\text{mes}}^2)$$

- Model discrepancy:

$$Y^{\text{true}}(x, t) = Y^{\text{sim}}(x, \beta, t) + \varepsilon^{\text{mod}}(x, t), \quad \varepsilon^{\text{mod}}(x, t) \sim \mathcal{GP}(0, k_{\theta})$$

Bayesian calibration with functional outputs

Introduced by [Kennedy and O'Hagan, 2001] and extended to functional outputs by [Higdon et al., 2008].

Linking experiments, simulations, and the true model:

- Measurement error:

$$Y^{\text{exp}}(x, t) = Y^{\text{true}}(x, t) + \varepsilon^{\text{mes}}(x, t), \quad \varepsilon^{\text{mes}}(x, t) \sim \mathcal{N}(0, \sigma_{\text{mes}}^2)$$

- Model discrepancy:

$$Y^{\text{true}}(x, t) = Y^{\text{sim}}(x, \beta, t) + \varepsilon^{\text{mod}}(x, t), \quad \varepsilon^{\text{mod}}(x, t) \sim \mathcal{GP}(0, k_{\theta})$$

$$\Rightarrow Y^{\text{exp}}(x, t) \mid \beta, \sigma_{\text{mes}}^2, \theta \sim \mathcal{GP}(Y^{\text{sim}}(x, \beta, t), k_{\theta} + \sigma_{\text{mes}}^2 \delta_{(x,t)=(x',t')})$$

Bayesian calibration with functional outputs

Introduced by [Kennedy and O'Hagan, 2001] and extended to functional outputs by [Higdon et al., 2008].

Linking experiments, simulations, and the true model:

- Measurement error:

$$Y^{\text{exp}}(x, t) = Y^{\text{true}}(x, t) + \varepsilon^{\text{mes}}(x, t), \quad \varepsilon^{\text{mes}}(x, t) \sim \mathcal{N}(0, \sigma_{\text{mes}}^2)$$

- Model discrepancy:

$$Y^{\text{true}}(x, t) = Y^{\text{sim}}(x, \beta, t) + \varepsilon^{\text{mod}}(x, t), \quad \varepsilon^{\text{mod}}(x, t) \sim \mathcal{GP}(0, k_{\theta})$$

$$\Rightarrow Y^{\text{exp}}(x, t) \mid \beta, \sigma_{\text{mes}}^2, \theta \sim \mathcal{GP}(Y^{\text{sim}}(x, \beta, t), k_{\theta} + \sigma_{\text{mes}}^2 \delta_{(x,t)=(x',t')})$$

Bayesian inference: With priors $\pi(\beta)$, $\pi(\sigma_{\text{mes}}^2)$, and $\pi(\theta)$:

$$P(\beta, \sigma_{\text{mes}}^2, \theta \mid Y^{\text{exp}}) \propto P(Y^{\text{exp}} \mid \beta, \sigma_{\text{mes}}^2, \theta) \pi(\beta) \pi(\sigma_{\text{mes}}^2) \pi(\theta)$$

Surrogate modeling for functional outputs: GP with PCA

When simulations are expensive, we run the code N_{sim} times and build a surrogate model to replace it. [Perrin, 2020]

Inputs: $(\beta_j)_{j=1,\dots,N_{\text{sim}}}$, **Outputs:** $(Y^{\text{sim}}(x_i, \beta_j, t_k))_{j=1,\dots,N_{\text{sim}}, k=1,\dots,N_t}$

Surrogate modeling for functional outputs: GP with PCA

When simulations are expensive, we run the code N_{sim} times and build a surrogate model to replace it. [Perrin, 2020]

Inputs: $(\beta_j)_{j=1,\dots,N_{\text{sim}}}$, **Outputs:** $(Y^{\text{sim}}(x_i, \beta_j, t_k))_{j=1,\dots,N_{\text{sim}}, k=1,\dots,N_t}$

Step 1: Dimension reduction (PCA)

$$Y_Q^{\text{sim}} = D_Q^T Y^{\text{sim}} \in \mathbb{R}^Q, \quad Q \ll N_t$$

Surrogate modeling for functional outputs: GP with PCA

When simulations are expensive, we run the code N_{sim} times and build a surrogate model to replace it. [Perrin, 2020]

Inputs: $(\beta_j)_{j=1,\dots,N_{\text{sim}}}$, **Outputs:** $(Y^{\text{sim}}(x_i, \beta_j, t_k))_{j=1,\dots,N_{\text{sim}}, k=1,\dots,N_t}$

Step 1: Dimension reduction (PCA)

$$Y_Q^{\text{sim}} = D_Q^T Y^{\text{sim}} \in \mathbb{R}^Q, \quad Q \ll N_t$$

Step 2: Gaussian process regression [Williams and Rasmussen, 2006]

Each component is treated independently: $\tilde{Y}_{Q,l}^{\text{sim}} \sim \mathcal{GP}(0, k_{\theta_l}^{\text{meta}})$, where θ_l is learned by maximizing the likelihood. We can compute the posterior distribution:

$$\tilde{Y}_{Q,l}^{\text{sim}}(x_i, \beta) \mid (\beta_j, Y_{Q,l}^{\text{sim}}(x_i, \beta_j))_j \sim \mathcal{GP}(\mu_Q^{\text{post}}, k_Q^{\text{post}})$$

Surrogate modeling for functional outputs: GP with PCA

When simulations are expensive, we run the code N_{sim} times and build a surrogate model to replace it. [Perrin, 2020]

Inputs: $(\beta_j)_{j=1,\dots,N_{\text{sim}}}$, **Outputs:** $(Y^{\text{sim}}(x_i, \beta_j, t_k))_{j=1,\dots,N_{\text{sim}}, k=1,\dots,N_t}$

Step 1: Dimension reduction (PCA)

$$Y_Q^{\text{sim}} = D_Q^T Y^{\text{sim}} \in \mathbb{R}^Q, \quad Q \ll N_t$$

Step 2: Gaussian process regression [Williams and Rasmussen, 2006]

Each component is treated independently: $\tilde{Y}_{Q,l}^{\text{sim}} \sim \mathcal{GP}(0, k_{\theta_l}^{\text{meta}})$, where θ_l is learned by maximizing the likelihood. We can compute the posterior distribution:

$$\tilde{Y}_{Q,l}^{\text{sim}}(x_i, \beta) \mid (\beta_j, Y_{Q,l}^{\text{sim}}(x_i, \beta_j))_j \sim \mathcal{GP}(\mu_Q^{\text{post}}, k_Q^{\text{post}})$$

Step 3: Reconstruction in the original space

$$\tilde{Y}^{\text{sim}}(x_i, \beta) \sim \mathcal{GP}(D_Q(\mu_Q^{\text{post}}), D_Q^T \text{diag}(k_Q^{\text{post}}) D_Q)$$

Bayesian calibration and time warping

Linking experiments, simulations, and the true model:

- Measurement error:

$$Y^{\text{exp}}(x, t) = Y^{\text{true}}(x, t) + \varepsilon^{\text{mes}}(x, t), \quad \varepsilon^{\text{mes}}(x, t) \sim \mathcal{N}(0, \sigma_{\text{mes}}^2)$$

- Model discrepancy:

$$Y^{\text{true}}(x, t) = Y^{\text{sim}}(x, \beta, t) + \varepsilon^{\text{mod}}(x, t), \quad \varepsilon^{\text{mod}}(x, t) \sim \mathcal{GP}(0, k_{\theta})$$

→ **Comparison of events that occur at the same time.**

Bayesian calibration and time warping

Linking experiments, simulations, and the true model:

- Measurement error:

$$Y^{\text{exp}}(x, t) = Y^{\text{true}}(x, t) + \varepsilon^{\text{mes}}(x, t), \quad \varepsilon^{\text{mes}}(x, t) \sim \mathcal{N}(0, \sigma_{\text{mes}}^2)$$

- Model discrepancy:

$$Y^{\text{true}}(x, t) = Y^{\text{sim}}(x, \beta, t) + \varepsilon^{\text{mod}}(x, t), \quad \varepsilon^{\text{mod}}(x, t) \sim \mathcal{GP}(0, k_{\theta})$$

→ **Comparison of events that occur at the same time.**

[[Francom et al., 2025](#)] suggests calibrating in a new space to compare

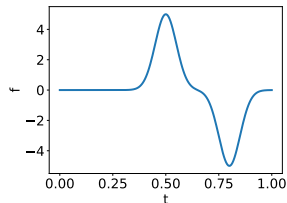
- **Amplitudes:** aligned versions of the functions,
- **Phases:** time warping required for alignment.



2. ELASTIC CALIBRATION WITH PARTIAL ALIGNMENT

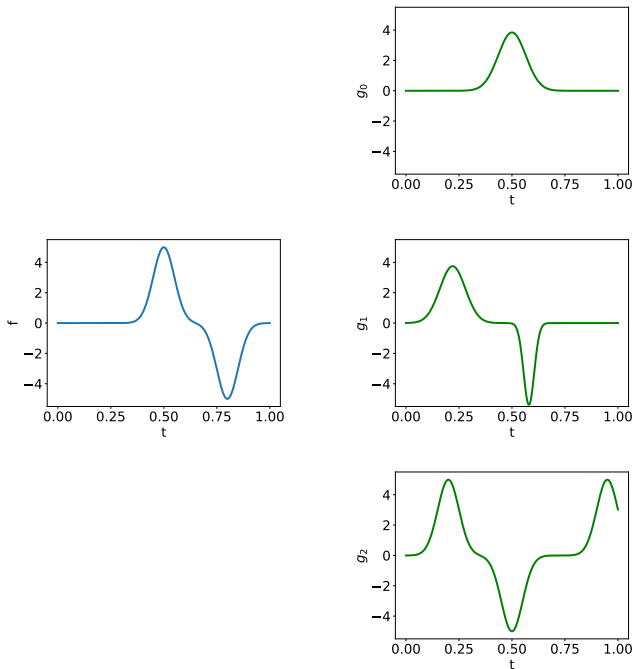
Distances between functions

Which function is the closest to f ?



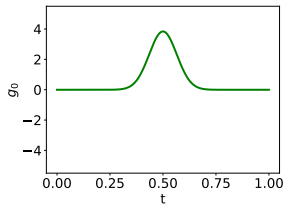
Distances between functions

Which function is the closest to f ?

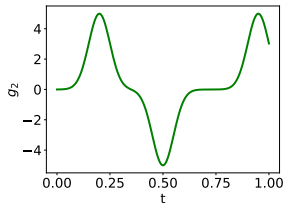
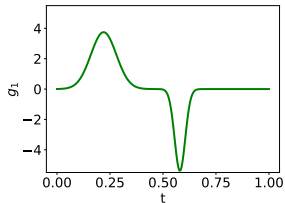
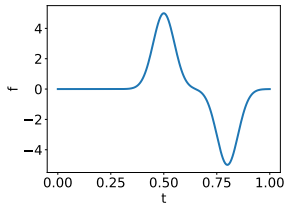
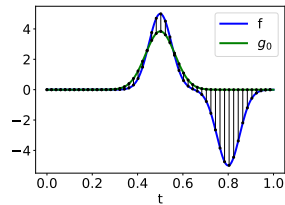


Distances between functions

Which function is the closest to f ?

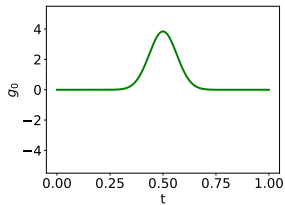


L2 distance $\rightarrow$

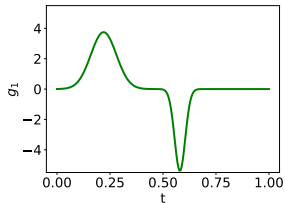
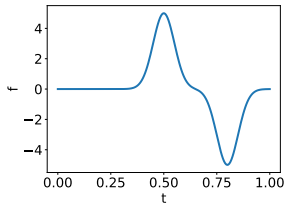
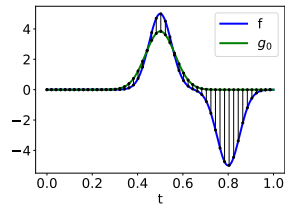


Distances between functions

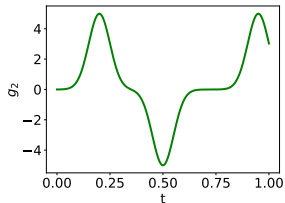
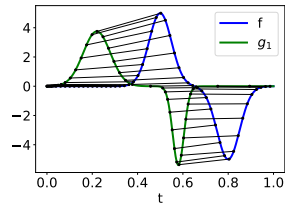
Which function is the closest to f ?



L2 distance

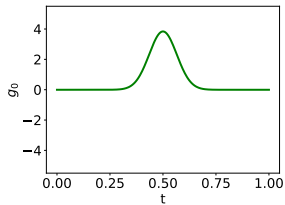


Elastic distance

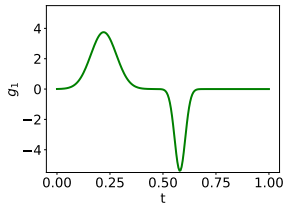
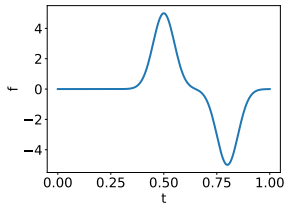
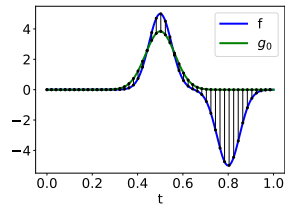


Distances between functions

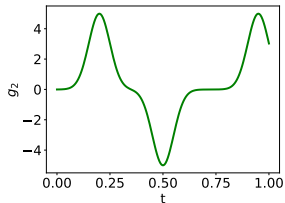
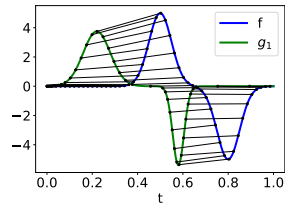
Which function is the closest to f ?



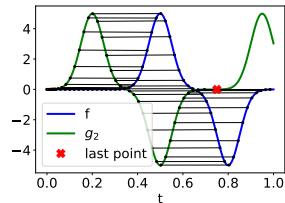
L2 distance



Elastic distance



Partial elastic distance



Elastic distance

We call a **phase** a function γ belonging to:

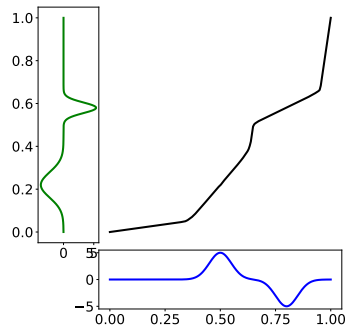
$$\Gamma = \left\{ \gamma : [0, 1] \rightarrow [0, 1] \mid \begin{array}{l} \gamma(0) = 0, \quad \gamma(1) = 1, \\ \gamma, \gamma^{-1} \text{ increasing and differentiable} \end{array} \right\}$$

$$d(f, g_1) = \inf_{\gamma \in \Gamma} E(f, g_1 \circ \gamma)$$

where

$$E(f_1, f_2) = \|Q(f_1) - Q(f_2)\|_2^2 \text{ and } Q(f)(t) = \text{sgn}(\dot{f}(t))\sqrt{|\dot{f}(t)|}$$

Phase



Elastic distance

We call a **phase** a function γ belonging to:

$$\Gamma = \left\{ \gamma : [0, 1] \rightarrow [0, 1] \mid \begin{array}{l} \gamma(0) = 0, \quad \gamma(1) = 1, \\ \gamma, \gamma^{-1} \text{ increasing and differentiable} \end{array} \right\}$$

$$d(f, g_1) = \inf_{\gamma \in \Gamma} E(f, g_1 \circ \gamma)$$

where

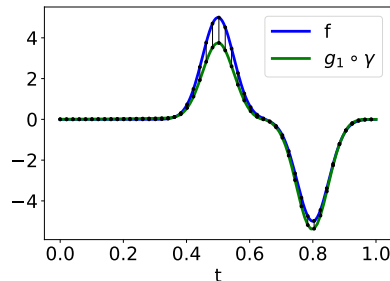
$$E(f_1, f_2) = \|Q(f_1) - Q(f_2)\|_2^2 \text{ and } Q(f)(t) = \text{sgn}(\dot{f}(t))\sqrt{|\dot{f}(t)|}$$

[[Srivastava and Klassen, 2016](#)] introduces two important properties for E :

- **Invariance to simultaneous warping:** For $\gamma \in \Gamma$, $E(f_1, f_2) = E(f_1 \circ \gamma, f_2 \circ \gamma)$.
- **Inverse symmetry:** If $\gamma = \arg \inf_{\gamma \in \Gamma} E(f_1, f_2 \circ \gamma)$, then $\gamma^{-1} = \arg \inf_{\gamma \in \Gamma} E(f_1 \circ \gamma, f_2)$.

[[Srivastava et al., 2011](#)] shows that E satisfies these properties.

Amplitude



Partial elastic distance [Bryner and Srivastava, 2021]

We call a **phase** a function γ belonging to:

$$\Gamma = \left\{ \gamma : [0, 1] \rightarrow [0, 1] \mid \begin{array}{l} \gamma(0) = 0, \gamma(1) = 1 \\ \gamma, \gamma^{-1} \text{ increasing and differentiable} \end{array} \right\}$$

$$d(f, g_1) = \inf_{\gamma \in \Gamma, t_f \in \mathbb{R}} E(f, g_1 \circ \gamma) \Big|_{[0, t_f]} + \text{pen}(t_f)$$

where

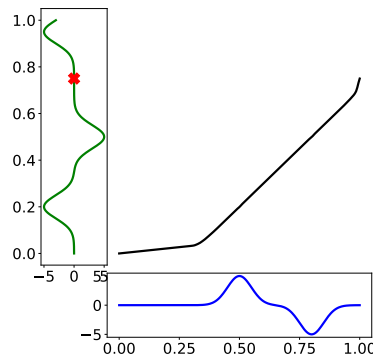
$$E(f_1, f_2) = \|Q(f_1) - Q(f_2)\|_2^2 \text{ and } Q(f)(t) = \text{sgn}(\dot{f}(t)) \sqrt{|\dot{f}(t)|}$$

[Srivastava and Klassen, 2016] introduces two important properties for E :

- **Invariance to simultaneous warping:** For $\gamma \in \Gamma$, $E(f_1, f_2) = E(f_1 \circ \gamma, f_2 \circ \gamma)$.
- **Inverse symmetry:** If $\gamma = \arg \min_{\gamma \in \Gamma} E(f_1, f_2 \circ \gamma)$, then $\gamma^{-1} = \arg \min_{\gamma \in \Gamma} E(f_1 \circ \gamma, f_2)$.

[Srivastava et al., 2011] shows that E satisfies these properties.

Phase



Alignment of set of functions

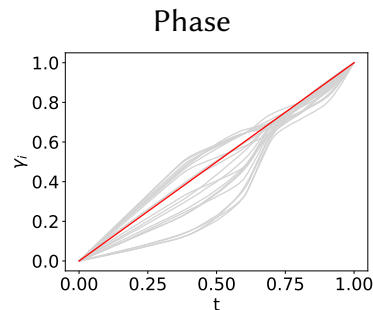
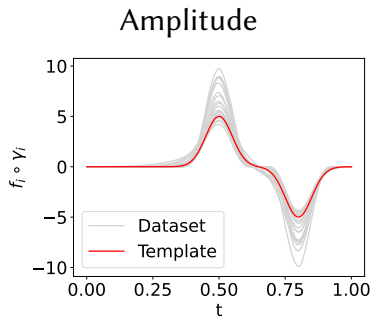
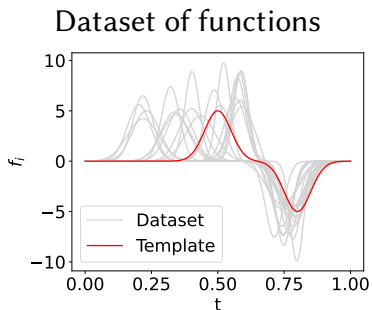
For a set of functions f_i :

- We choose one function f_{ref} from the dataset
- For each function we compute, $\gamma_i = \arg \min_{\gamma \in \Gamma} E(f_{\text{ref}}, f_i \circ \gamma)$

Alignment of set of functions

For a set of functions f_i :

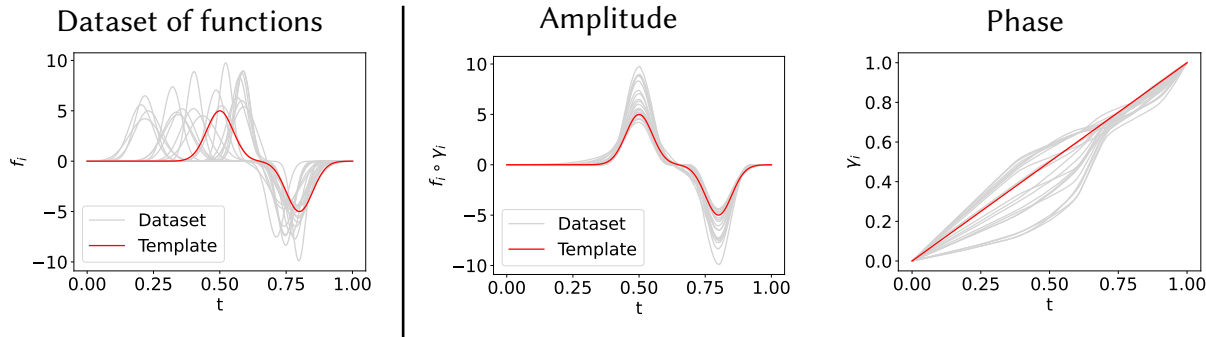
- We choose one function f_{ref} from the dataset
- For each function we compute, $\gamma_i = \arg \min_{\gamma \in \Gamma} E(f_{\text{ref}}, f_i \circ \gamma)$



Alignment of set of functions

For a set of functions f_i :

- We choose one function f_{ref} from the dataset
- For each function we compute, $\gamma_i = \arg \min_{\gamma \in \Gamma} E(f_{\text{ref}}, f_i \circ \gamma)$



[[Francom et al., 2025](#)] proposed performing the calibration in the Amplitude/Phase space rather than in the original space. We propose to adapt their method for partial elastic alignment.

The model [Francom et al., 2025] with final time

Step 1: Alignment on y_{ref} between functions with final time [Bryner and Srivastava, 2021]

$$(\gamma_i, t_f) = \arg \min_{\gamma \in \Gamma, t_f \in \mathbb{R}} E(y_{\text{ref}}, y_i \circ \gamma) \Big|_{[0, t_f]} + \text{pen}(t_f)$$

The model [Francom et al., 2025] with final time

Step 1: Alignment on y_{ref} between functions with final time [Bryner and Srivastava, 2021]

$$(\gamma_i, t_f) = \arg \min_{\gamma \in \Gamma, t_f \in \mathbb{R}} E(y_{\text{ref}}, y_i \circ \gamma) \Big|_{[0, t_f]} + \text{pen}(t_f)$$

Step 2: Transformation of the phase space Γ to a vector space [Francom et al., 2025]:

$$\psi = \sqrt{\dot{\gamma}} \text{ and } v = \exp_{\psi_{\text{id}}}^{-1}(\psi)$$

The model [Francom et al., 2025] with final time

Step 1: Alignment on y_{ref} between functions with final time [Bryner and Srivastava, 2021]

$$(\gamma_i, t_f) = \arg \min_{\gamma \in \Gamma, t_f \in \mathbb{R}} E(y_{\text{ref}}, y_i \circ \gamma) \Big|_{[0, t_f]} + \text{pen}(t_f)$$

Step 2: Transformation of the phase space Γ to a vector space [Francom et al., 2025]:

$$\psi = \sqrt{\dot{\gamma}} \text{ and } v = \exp_{\psi_{\text{id}}}^{-1}(\psi)$$

Step 3: Surrogate modeling (GPR) of v^{sim} , $f^{\text{sim}} = y_i^{\text{sim}} \circ \gamma_i$, and t^{sim} , denoted $\tilde{v}^{\text{sim}}$, $\tilde{f}^{\text{sim}}$, and $\tilde{t}^{\text{sim}}$.

The model [Francom et al., 2025] with final time

Step 1: Alignment on y_{ref} between functions with final time [Bryner and Srivastava, 2021]

$$(\gamma_i, t_f) = \arg \min_{\gamma \in \Gamma, t_f \in \mathbb{R}} E(y_{\text{ref}}, y_i \circ \gamma) \Big|_{[0, t_f]} + \text{pen}(t_f)$$

Step 2: Transformation of the phase space Γ to a vector space [Francom et al., 2025]:

$$\psi = \sqrt{\dot{\gamma}} \text{ and } v = \exp_{\psi_{\text{id}}}^{-1}(\psi)$$

Step 3: Surrogate modeling (GPR) of v^{sim} , $f^{\text{sim}} = y_i^{\text{sim}} \circ \gamma_i$, and t^{sim} , denoted $\tilde{v}^{\text{sim}}$, $\tilde{f}^{\text{sim}}$, and $\tilde{t}^{\text{sim}}$.

Step 4: Bayesian calibration

$$f^{\text{exp}}(x, t) = \tilde{f}^{\text{sim}}(x, t, \beta) + \varepsilon_f(x, t)$$

$$v^{\text{exp}}(x, t) = \tilde{v}^{\text{sim}}(x, t, \beta) + \varepsilon_v(x, t)$$

$$t_f^{\text{exp}}(x) = \tilde{t}^{\text{sim}}(x, \beta) + \varepsilon_t(x)$$

The model [Francom et al., 2025] with final time

Step 1: Alignment on y_{ref} between functions with final time [Bryner and Srivastava, 2021]

$$(\gamma_i, t_f) = \arg \min_{\gamma \in \Gamma, t_f \in \mathbb{R}} E(y_{\text{ref}}, y_i \circ \gamma) \Big|_{[0, t_f]} + \text{pen}(t_f)$$

Step 2: Transformation of the phase space Γ to a vector space [Francom et al., 2025]:

$$\psi = \sqrt{\dot{\gamma}} \text{ and } v = \exp_{\psi_{\text{id}}}^{-1}(\psi)$$

Step 3: Surrogate modeling (GPR) of v^{sim} , $f^{\text{sim}} = y_i^{\text{sim}} \circ \gamma_i$, and t^{sim} , denoted $\tilde{v}^{\text{sim}}$, $\tilde{f}^{\text{sim}}$, and $\tilde{t}^{\text{sim}}$.

Step 4: Bayesian calibration

$$f^{\text{exp}}(x, t) = \tilde{f}^{\text{sim}}(x, t, \beta) + \varepsilon_f(x, t)$$

$$v^{\text{exp}}(x, t) = \tilde{v}^{\text{sim}}(x, t, \beta) + \varepsilon_v(x, t)$$

$$t_f^{\text{exp}}(x) = \tilde{t}^{\text{sim}}(x, \beta) + \varepsilon_t(x)$$

If we denote, θ_f , θ_v and θ_t the hyperparameters of ε_f , ε_v and ε_t and $\pi(\theta)$ their priors :

$$P(\beta, \theta_y, \theta_v, \theta_t | y^{\text{exp}}) \propto P(f^{\text{exp}} | \beta, \theta_f) P(v^{\text{exp}} | \beta, \theta_v) P(t_f^{\text{exp}} | \beta, \theta_t) \pi(\beta) \pi(\theta_f) \pi(\theta_v) \pi(\theta_t)$$



3. ANHARMONIC OSCILLATOR

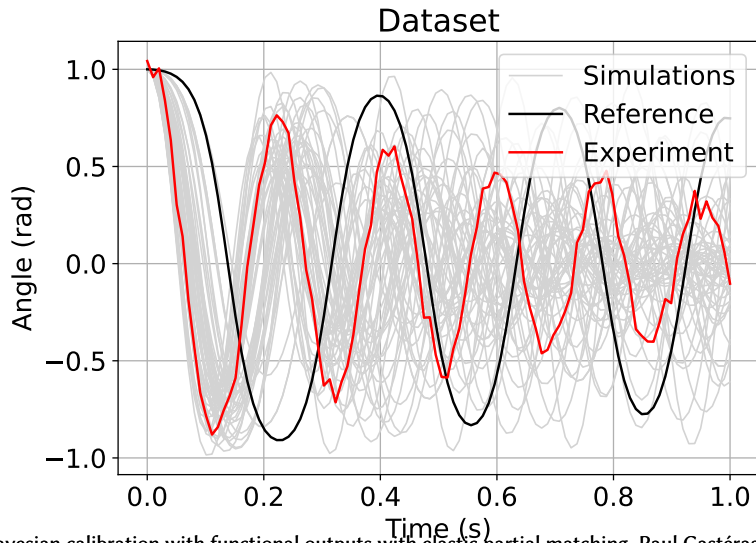
Anharmonic oscillator

Equation :

$$\frac{d^2\theta}{dt^2} + \alpha_1 \frac{d\theta}{dt} + \alpha_2(\theta - \alpha_0\theta^3) = 0.$$

Calibration of

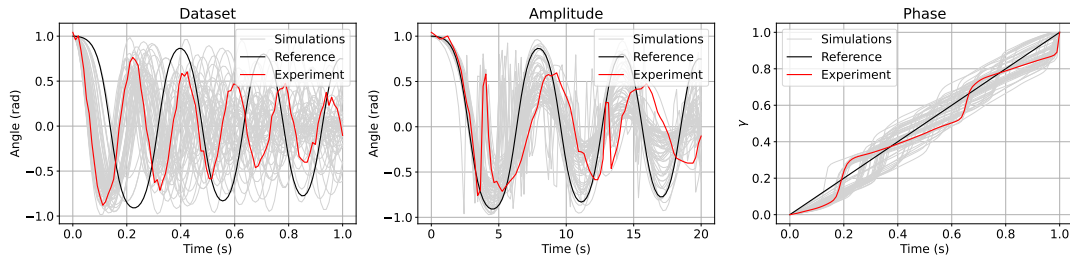
$$\beta \in [0, 1]^3 \text{ where } \alpha_0 = 0.48\beta_0 + 0.5, \alpha_1 = 0.3\beta_1, \alpha_2 = 2\beta_2 + 2$$



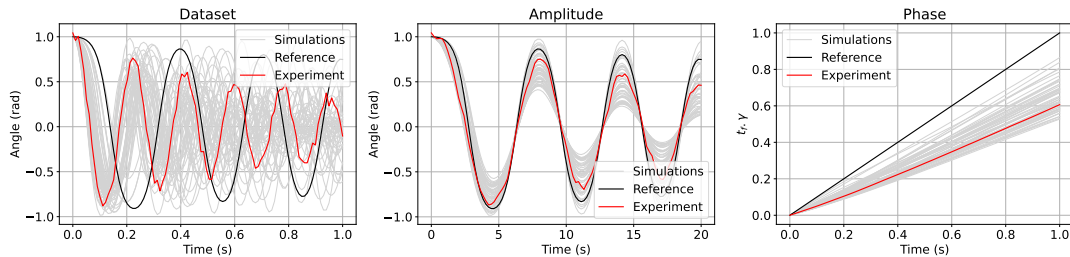
$$\begin{aligned}\beta_{exp} &= [0.5, 0.3, 0.8], \\ \sigma_{exp}^2 &= 0.05^2, \\ N_{sim} &= 50, \\ N_t &= 100.\end{aligned}$$

Anharmonic oscillator: Amplitude/Phase decomposition

Elastic decomposition



Partial elastic decomposition



Anharmonic oscillator : surrogate models

Prediction of the model :

$$Q^2 = 1 - \frac{\sum (y_i - \hat{y}_i)^2}{\sum (y_i - \bar{y})^2}$$

→ close to 1 = good prediction.

Credible intervals of the model :

IAE_α evaluates the quality of the quantiles of level α for different values α [[Marrel and looss, 2024](#)]

→ close to 0 = good credible intervals.

Anharmonic oscillator : surrogate models

Prediction of the model :

$$Q^2 = 1 - \frac{\sum (y_i - \hat{y}_i)^2}{\sum (y_i - \bar{y})^2}$$

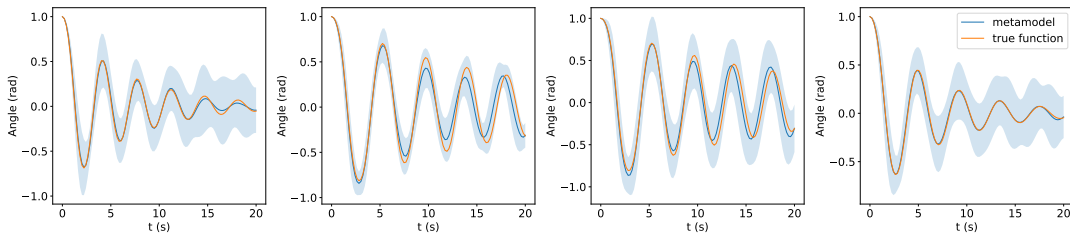
→ close to 1 = good prediction.

Credible intervals of the model :

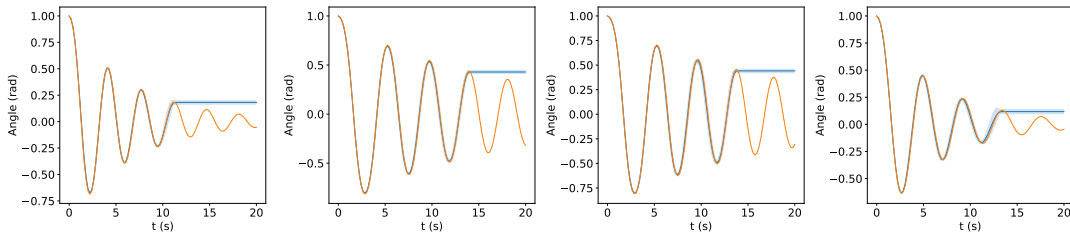
IAE_α evaluates the quality of the quantiles of level α for different values α [Marrel and looss, 2024]

→ close to 0 = good credible intervals.

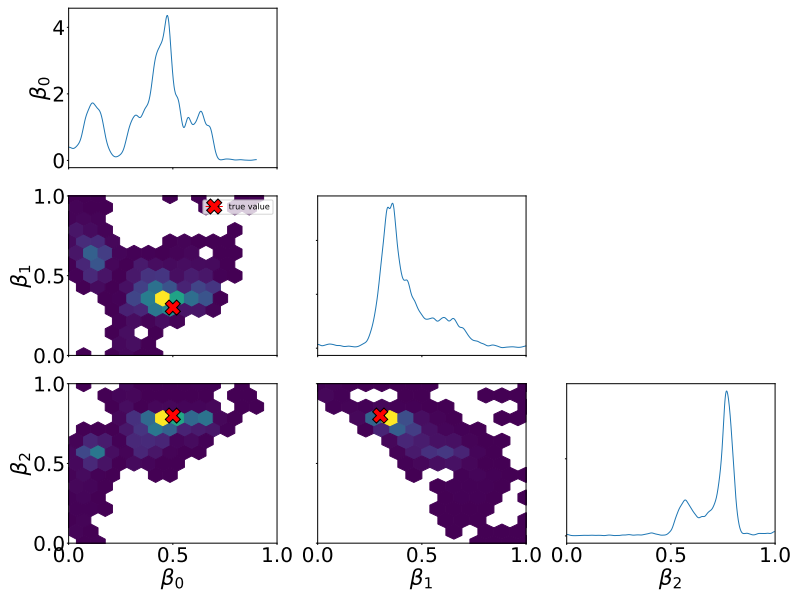
Without elastic decomposition: $Q^2 = 0.85$, $IAE_\alpha = 0.17$



With partial elastic decomposition $Q^2 = 0.97$, $IAE_\alpha = 0.02$



Anharmonic oscillator : Functional calibration



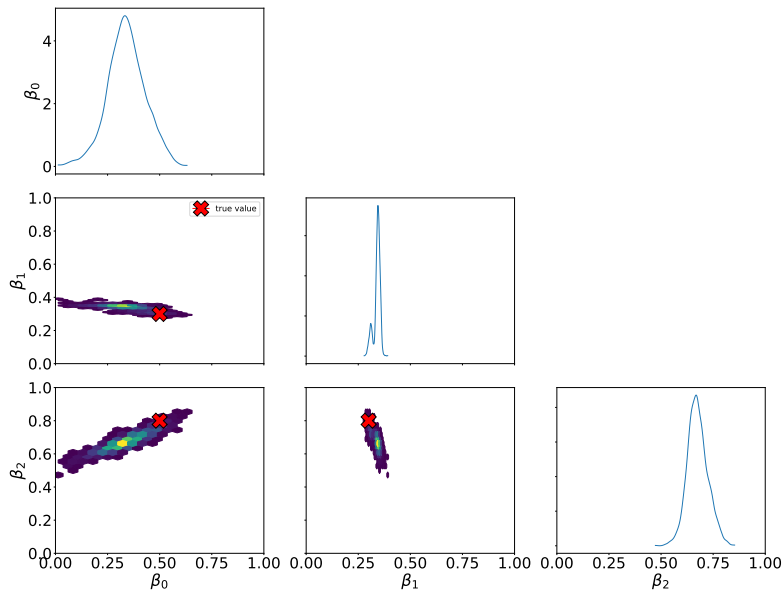
$$Y^{\text{exp}}(t) = \tilde{Y}^{\text{sim}}(\beta, t) + \epsilon^{\text{mes}}(t)$$

$$\epsilon^{\text{mes}}(t) \sim \mathcal{N}(0, \sigma_{\text{mes}}^2)$$

$$\beta \sim \mathcal{U}([0, 1]^3)$$

Sampling with Sequential Monte Carlo

Anharmonic oscillator : Partial elastic calibration



$$\begin{aligned} f^{\text{exp}}(t) &= \tilde{f}^{\text{sim}}(t, \beta) + \varepsilon^{\text{mes}}(t) \\ v^{\text{exp}}(t) &= \tilde{v}^{\text{sim}}(t, \beta) + \varepsilon^{\text{mod}}(t) \\ t_f^{\text{exp}} &= \tilde{t}^{\text{sim}}(\beta) \end{aligned}$$

$$\begin{aligned} \varepsilon^{\text{mes}}(x, t) &\sim \mathcal{N}(0, \sigma_{\text{mes}}^2) \\ \varepsilon^{\text{mod}}(x, t) &\sim \mathcal{GP}(0, \sigma_{\text{mod}}^2 k_l) \end{aligned}$$

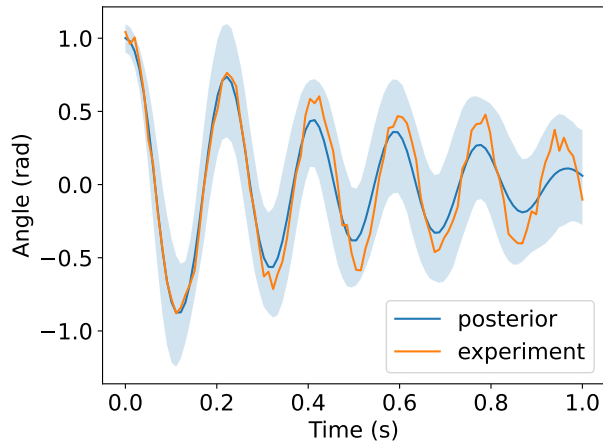
$$\begin{aligned} \sigma_{\text{mod}}^2 &\sim \mathcal{N}(0, 1) \mathbf{1}_{\sigma_{\text{mod}}^2 > 0} \\ l &\sim \Gamma(1, 1) \\ \beta &\sim \mathcal{U}([0, 1]^3) \end{aligned}$$

Sampling with Sequential Monte Carlo

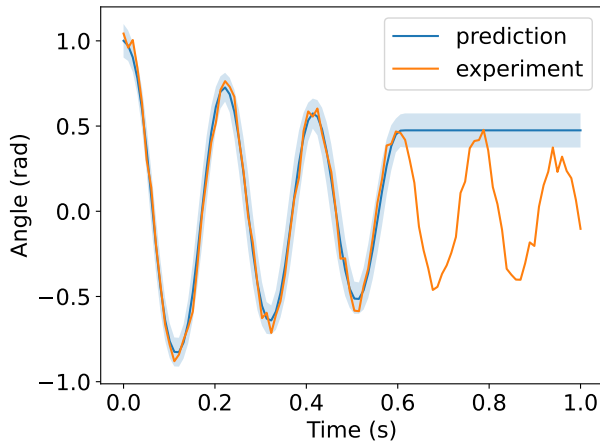
Anharmonic oscillator : Comparison of the predictions



Without elastic decomposition



With partial elastic decomposition



Conclusion

We introduced a new calibration method based on the Bayesian elastic calibration framework [[Francom et al., 2025](#)] and on partial elastic matching [[Bryner and Srivastava, 2021](#)]. It enables:

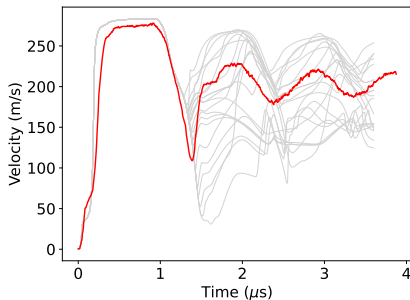
- Comparison of patterns that do not occur at the same time,
- Model discrepancy in phase,
- Partial elastic surrogate model.

Conclusion

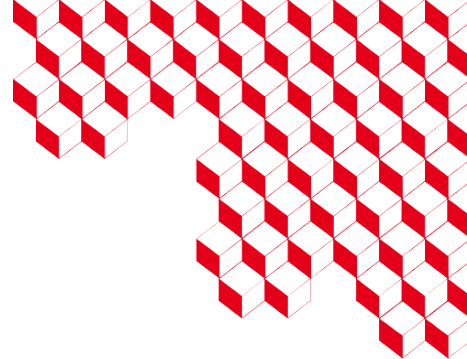
We introduced a new calibration method based on the Bayesian elastic calibration framework [Francom et al., 2025] and on partial elastic matching [Bryner and Srivastava, 2021]. It enables:

- Comparison of patterns that do not occur at the same time,
- Model discrepancy in phase,
- Partial elastic surrogate model.

Future work



- The alignment transform is not continuous. How to build surrogate models in those cases ?
- Investigate other representation that combine phases and final times.



THANK YOU

Paul Castéras
CEA DAM Île-de-France
Bruyères-le-Châtel
91297 Arpajon cedex



4. REFERENCES

References I

- 
-  Bryner, D. and Srivastava, A. (2021).
Shape analysis of functional data with elastic partial matching.
IEEE transactions on pattern analysis and machine intelligence, 44(12):9589–9602.
-  Francom, D., Tucker, J. D., Huerta, G., Shuler, K., and Ries, D. (2025).
Elastic bayesian model calibration.
SIAM/ASA Journal on Uncertainty Quantification, 13(1):195–227.
-  Higdon, D., Gattiker, J., Williams, B., and Rightley, M. (2008).
Computer model calibration using high-dimensional output.
Journal of the American Statistical Association, 103(482):570–583.
-  Kennedy, M. C. and O’Hagan, A. (2001).
Bayesian calibration of computer models.
Journal of the Royal Statistical Society: Series B (Statistical Methodology), 63(3):425–464.
-  Marrel, A. and Iooss, B. (2024).
Probabilistic surrogate modeling by Gaussian process: A review on recent insights in estimation and validation.
Reliability Engineering and System Safety, 247:110094.
-  Perrin, G. (2020).
Adaptive calibration of a computer code with time-series output.
Reliability engineering & system safety, 196:106728.
-  Srivastava, A. and Klassen, E. P. (2016).
Functional and shape data analysis, volume 1.
Springer.
-  Srivastava, A., Wu, W., Kurtek, S., Klassen, E., and Marron, J. S. (2011).
Registration of functional data using fisher-rao metric.
arXiv preprint arXiv:1103.3817.

References II



Williams, C. K. and Rasmussen, C. E. (2006).
Gaussian processes for machine learning, volume 2.
MIT press Cambridge, MA.

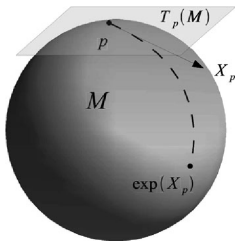
Transformation of the phase space

$$\gamma \in \Gamma = \left\{ \gamma : [0, 1] \rightarrow [0, 1] \mid \begin{array}{l} \gamma(0) = 0, \gamma(1) = 1 \\ \gamma, \gamma^{-1} \text{ increasing and differentiable} \end{array} \right\}$$

First transformation: $\psi = Q(\gamma) = \sqrt{\dot{\gamma}} \in \Psi$

$$\Rightarrow \|\psi\|_2^2 = \int_0^1 \psi(t)^2 dt = 1 \Rightarrow \Psi \subset S_\infty$$

Second transformation:

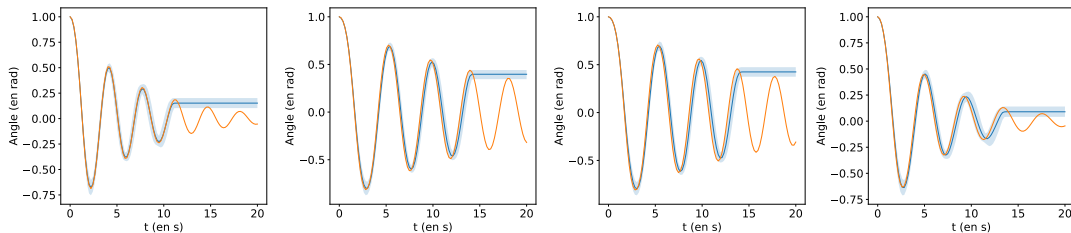


$$\begin{aligned} T_\psi(\Psi) &= \left\{ v \in L^2 \mid \int_0^1 v(t) \psi(t) dt = 0 \right\} \\ \exp_\psi^{-1}(\psi_1) &= \frac{\kappa}{\sin(\kappa)} (\psi_1 - \cos(\kappa)\psi) \\ \text{where } \kappa &= d_p(\psi, \psi_1) = \cos^{-1}(\int_0^1 \psi \psi_1) \end{aligned}$$

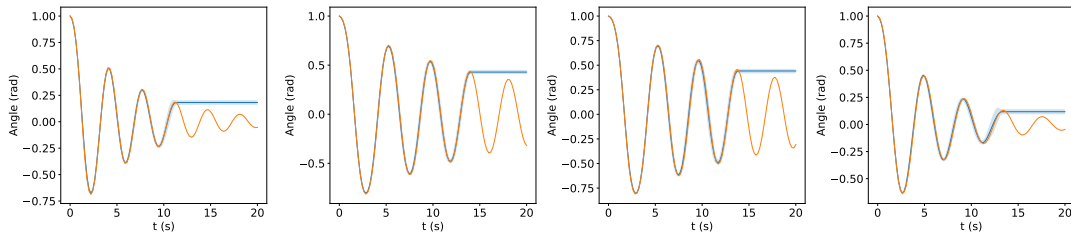
Figure of [Srivastava and Klassen, 2016]

Anharmonic oscillator : surrogate models

Final time but no elasticity: $Q^2 = 0.95$, $IAE_\alpha = 0.06$



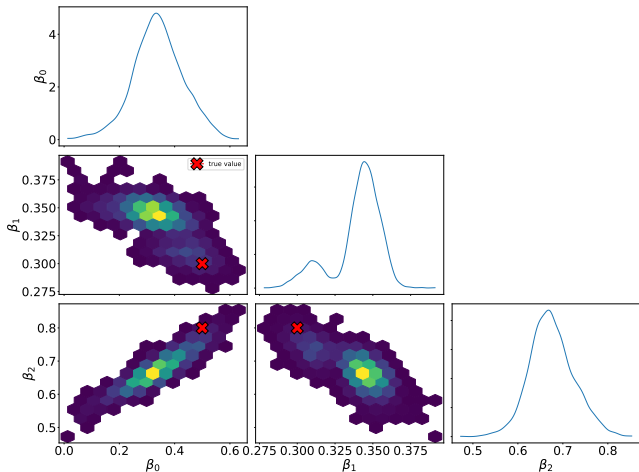
With partial elastic decomposition: $Q^2 = 0.97$, $IAE_\alpha = 0.02$



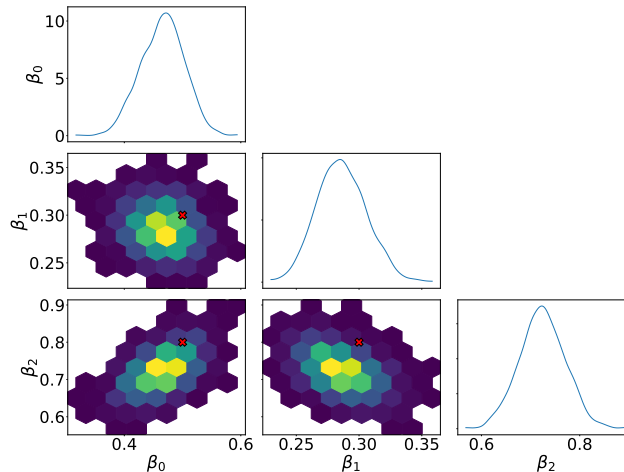
Anharmonic oscillator : Calibration



With partial elastic decomposition:



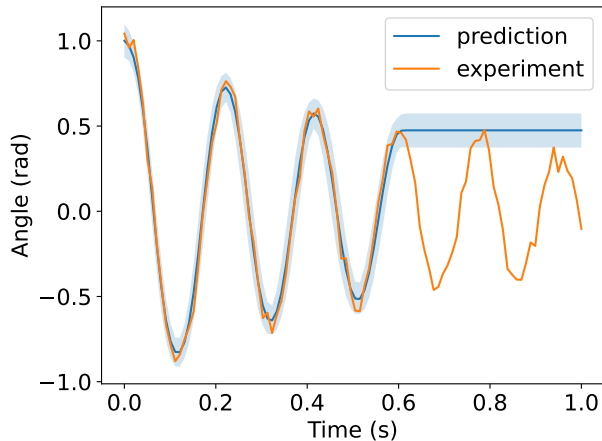
Final time but no elasticity:



Anharmonic oscillator : Comparison of the predictions



With partial elastic decomposition



Final time but no elasticity

