
Optimization under Uncertainty Workshop

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In order to break the ice ...

An incomplete statement of the « optimization under uncertainty » problematic.

Uncertainties and optimization : example

Models and working conditions are partially unknown → uncertainties.
These uncertainties need to be taken into account during design.

Ex : a +/- 1mm dispersion in the manufacturing of the air admission line can degrade the engine's performance (g CO₂/km) by +20% (worst case).



Optimization terminology (1)

Formulation of the deterministic optimization problem

$$\left\{ \begin{array}{l} \min_{x \in S} f(x) \\ g(x) \leq 0 \end{array} \right.$$

x : optimization variables
 f : objective functions
 g : optimization constraints
 f, g : optimization (performance) criteria

Optimization terminology (2) : the double (x,u) parameterization for uncertainties

x is a vector of deterministic optimization (controlled) variables.
 $x \in S$, the search space.

Introduce $u \in U$, a vector of uncertain parameters that affect the optimization criteria,

$$f(x) , g(x) \rightarrow f(x,u) , g(x,u)$$

u used to describe

- aleatoric uncertainties, e.g., noise in measurements
- systematic or epistemic uncertainties, e.g., lack of model knowledge.

Steps in optimization under uncertainties

- **Uncertainty representation.**
- **Formulation of the optimization problem under uncertainty.**
- **Mathematical approximations, numerical solving.**

Uncertainty representation

- As random variables. But which distribution ? Do we have sufficient data for inferring a distribution ?
- Using possibility or evidence theory (as a solution to lack of data). But uncertainty propagation is costly.
- Using a finite set of well-chosen values (against numerical difficulties and to fall back on deterministic methods). But how to choose these values ?

Formulation of optimization with uncertainties (example using random variables)

Replace the noisy optimization criteria by statistical measures (mean, standard deviations, quantiles, probabilities).

Example :

$OK(x)$ is the random event "all constraints are satisfied" ,
$$OK(x) = \bigcap_i \{g_i(x, U) \leq 0\}$$

$\min_{x \in S} q_\alpha^c(x)$ (conditional α -quantile)

such that $P(OK(x)) \geq 1 - \varepsilon$

where $P(f(x, U) \leq q_\alpha^c(x) \mid OK(x)) = \alpha$

$\varepsilon > 0$, small

(an « ideal » formulation, aka chance constrained prob., that is never addressed because of the associated computational challenge)

Formulation of optimization with uncertainties (example using discrete deterministic variables)

$$U = \{u^1, u^2, \dots, u^n\}$$

$$\min_{x \in S} \left(\sup_{u \in U} f(x, u) \right)$$

such that $g(x, u) \leq 0$, $\forall u \in U$

how to choose the u 's in such a worst case formulation (e.g., control the failure probability) ?

Mathematical approximation, numerical solving

Often, when the optimization criteria are based on complex numerical simulation, the numerical cost of optimization under uncertainty is a bottle neck (curse of the double loop).

Typical approaches :

Safety factors

$$u = u^{\text{ref}}$$

$$\min_{x \in S} f(x, u^{\text{ref}})$$

$$\text{such that } g(x, u^{\text{ref}}) + S \leq 0, \quad S > 0$$

FOSM, FORM, SORM

$$\min_{x \in S} f(x)$$

$$\text{such that } \text{distance}(u^{\text{ref}}, u^{\text{MPF}}) > \text{safe_dist}$$

$$\text{where } u^{\text{MPF}} = \arg \max_{u | \hat{g}(x, u) = 0} P(u)$$

Approaches based on **surrogates** of f , g , mean, variance, quantiles, probabilities, ...

Now : 2 round tables, 2 questions

- 1) In order to know each other :
what have you done in the past related to optimization under uncertainty ?
(presentations by Younes Aoues and Victor Picheny and everyone)
- 2) Look ahead :
what are the next challenges and the main research directions in optimization under uncertainty ?