



DE LA RECHERCHE À L'INDUSTRIE

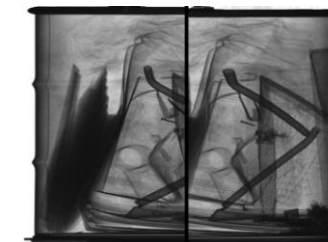
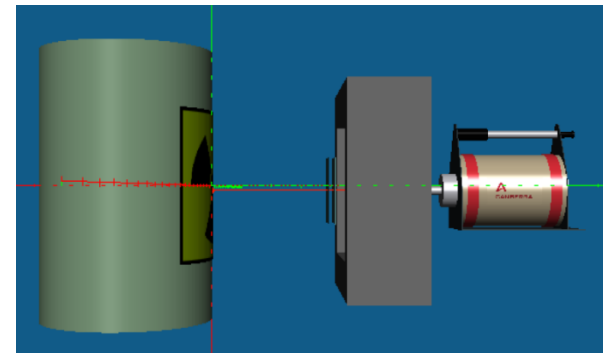
## **Bayesian Approach for Multigamma Radionuclide Quantification Applied on Weakly Attenuating Nuclear Waste Drums**

Workshop MASCOT-NUM, 21-22 November 2022

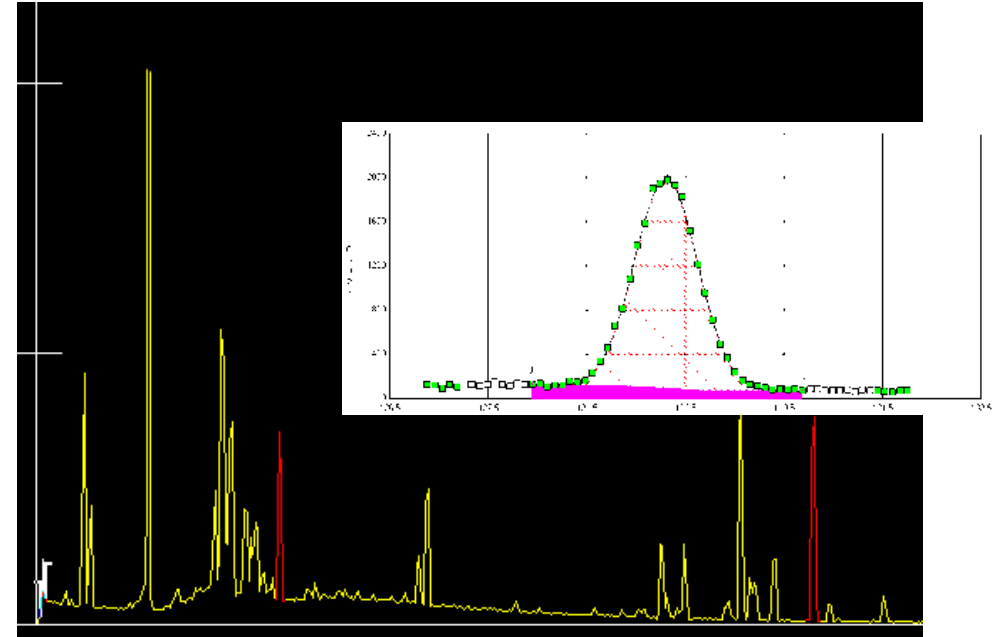
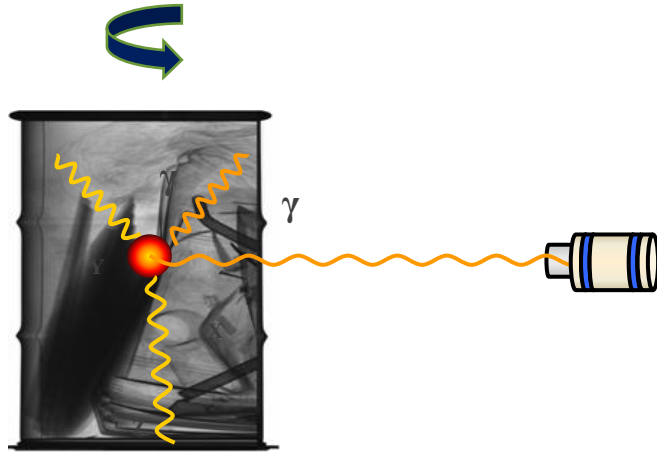
Aloïs CLEMENT

*I'm sorry, but I'm a nuclear physicist.*

- *In situ* nuclear measurement of radioactive items
- Gamma spectrometry : HPGe 30% (Canberra)
- Software : Génie 2000, ISOCS
- Waste drums : 100 et 200 L
- Actinides : U, Pu, Am, Np



- Aims : identify and quantify actinides



$$A = \frac{S(E)}{\epsilon(E, env) t I_{\gamma}(E)}$$

$$m = \frac{A}{A_m}$$

Multi-gamma radionuclide :

$$\mathbf{E} = (E_1, \dots, E_N)$$

$$A = \frac{S(\mathbf{E})}{\epsilon(\mathbf{E}, env) t I_{\gamma}(\mathbf{E})}$$

Let suppose :

$$Y^{obs} = \frac{S(\mathbf{E})}{t I_{\gamma}(\mathbf{E}) A_m}$$

$$Y^{obs} = m \epsilon(\mathbf{E}, env)$$

Inverse problem to solve

$$\mathbf{Y}^{\text{obs}} = m\epsilon(\mathbf{E}, env) + \xi^{\text{obs}}$$

$$\xi^{\text{obs}} \sim N(\mathbf{0}, \Sigma^{\text{obs}})$$

Likelihood function

Priors

Bayes theorem :

$$\pi(m, env | \mathbf{Y}^{\text{obs}}) = \frac{\pi(\mathbf{Y}^{\text{obs}} | m, env) \pi(m | env) \pi(env)}{\int \pi(\mathbf{Y}^{\text{obs}} | m, env) \pi(m | env) \pi(env)}$$

**Posterior**

$$\pi(m, env | \mathbf{Y}^{\text{obs}}) \propto \pi(\mathbf{Y}^{\text{obs}} | m, env) \pi(m | env) \pi(env)$$

What I want

What I'll estimate

What I think I know

What about the « env » environment variable ?

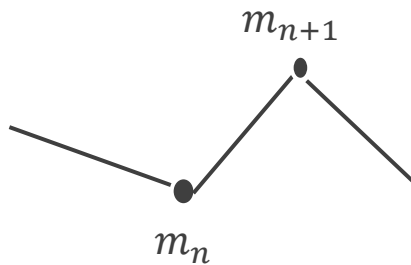
$$\pi(m, \mathbf{X} | \mathbf{Y}^{obs}) \propto \pi(\mathbf{Y}^{obs} | m, \mathbf{X}) \pi(m | \mathbf{X}) \pi(\mathbf{X})$$

Observation likelihood

Priors

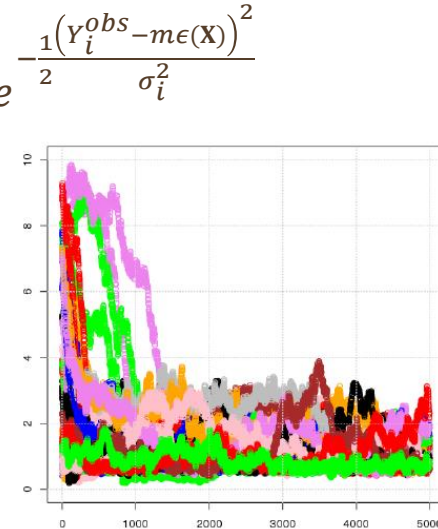
- Independent  $Y_i^{obs}$  :  $\pi(\mathbf{Y}^{obs} | m, \mathbf{X}) = \prod_{i=1}^N \pi(Y_i^{obs} | m, \mathbf{X}) = \prod_{i=1}^N \frac{1}{\sqrt{2\pi\sigma_i}} e^{-\frac{1}{2} \frac{(Y_i^{obs} - m\epsilon(\mathbf{X}))^2}{\sigma_i^2}}$
- Independent  $(m, X_i)$  :  $\pi(m | \mathbf{X}) \pi(\mathbf{X}) = \pi(m) \pi(\mathbf{X}) = \pi(m) \prod_{i=1}^D \pi(X_i)$

## MCMC : Metropolis-Hastings algorithm



$$m_{n+1} \leftarrow m_n + A \cdot \delta, \quad \delta \sim N(0, k_m)$$

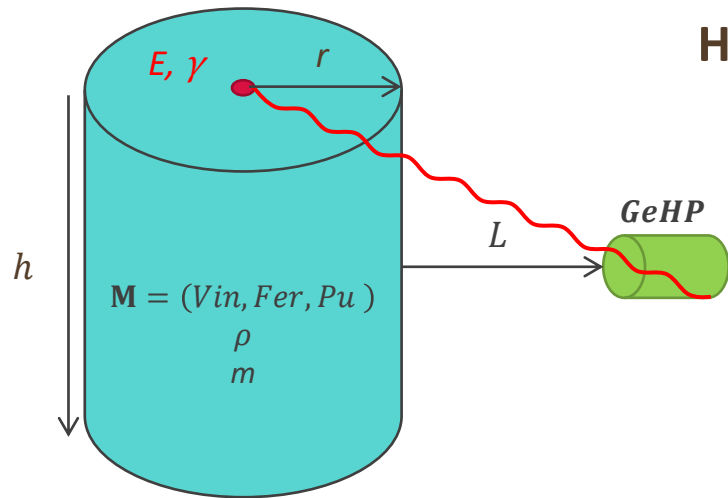
$$\rho = \min\left(\frac{\pi(m_{n+1}, \mathbf{X}_{n+1} | \mathbf{Y}^{obs})}{\pi(m_n, \mathbf{X}_n | \mathbf{Y}^{obs})}, 1\right)$$



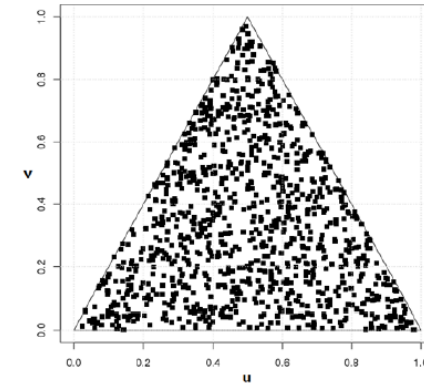
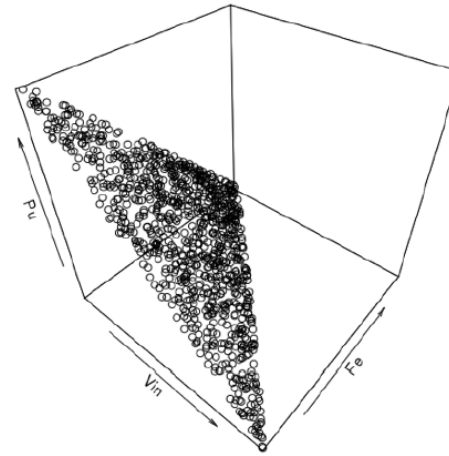
- High number of  $\epsilon(\mathbf{X})$  estimations ( $\approx 10^5$ ) by the simulation code MCNP6.2
- Time-consuming

Surrogate model  $f$  of the measurement efficiency

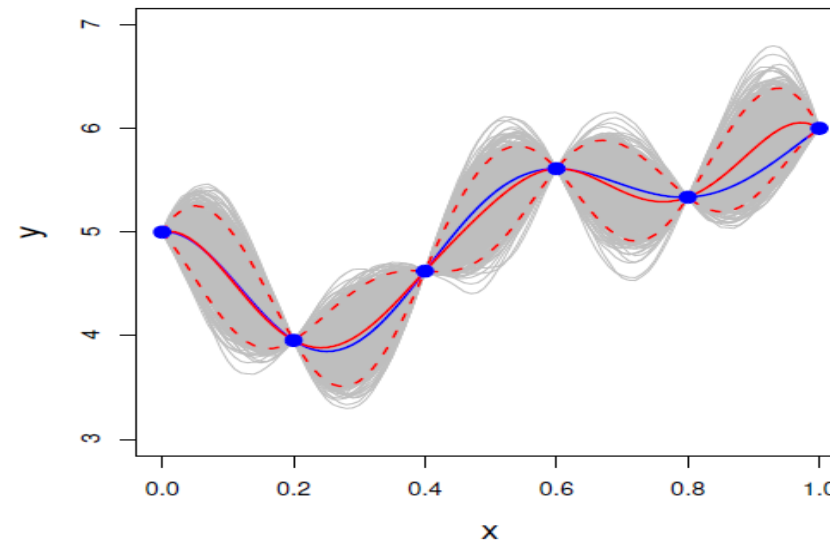
$$\epsilon = f(\mathbf{X})$$



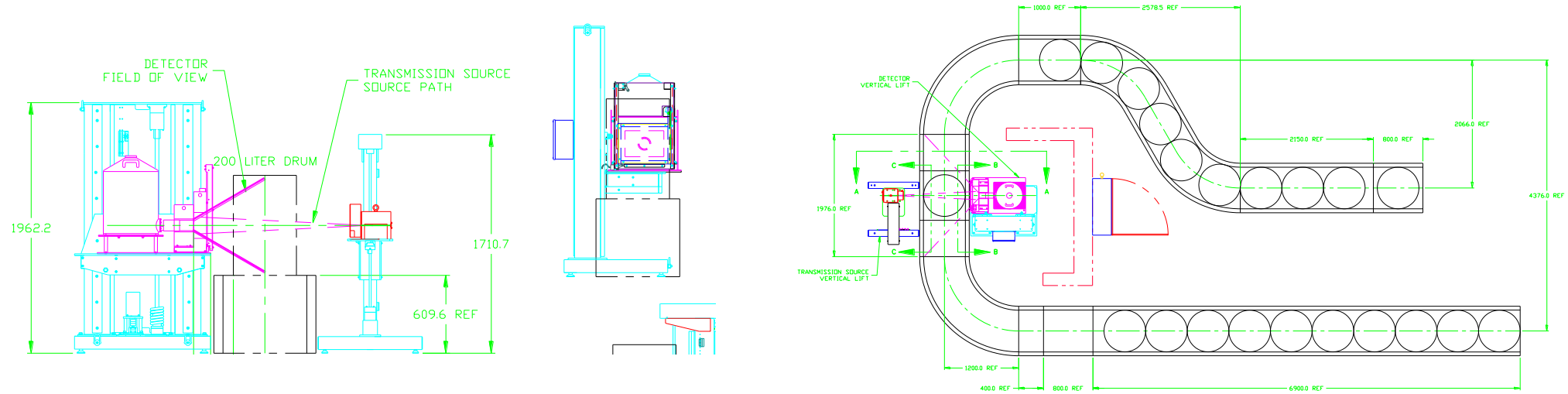
How could I estimate « env » and  $\epsilon(\mathbf{E}, env)$  ?



- Input:  $\mathbf{X} = \{ E, r, h, \mathbf{M}, L, \rho \}$  et  $m$  ( $\text{Card}(\mathbf{X}) = 8$ )
- DoE: Latin Hypercube Sampling ( $n = 500$ )
- Surrogate model: Kriging :
  - Universal Kriging (UK) :  $f(X) = \mu(X) + Z(X)$
  - Deterministic :  $\mu(X) = \sum_{j=1}^p \beta_j f_j(X)$
  - Stochastic :  $Z(X) : \text{Matérn } 5/2$
- $\epsilon(\mathbf{E}, env) \approx f(\mathbf{X}) = f(\mathbf{E}, r, h, \rho, L, \mathbf{M})$



## MADAGASCAR : Automatic Nuclear Waste Drum Measurement Device





### MADAGASCAR : Validity range

- Bulk density < 0.4
- Detection limit : 1 MBq
- Maximal activity: 200 GBq
- 100L and 200L drums
- Measurement distance :  $\approx 60$  cm
- Global uncertainties:  $\pm 42\%$

### MADAGASCAR : Database

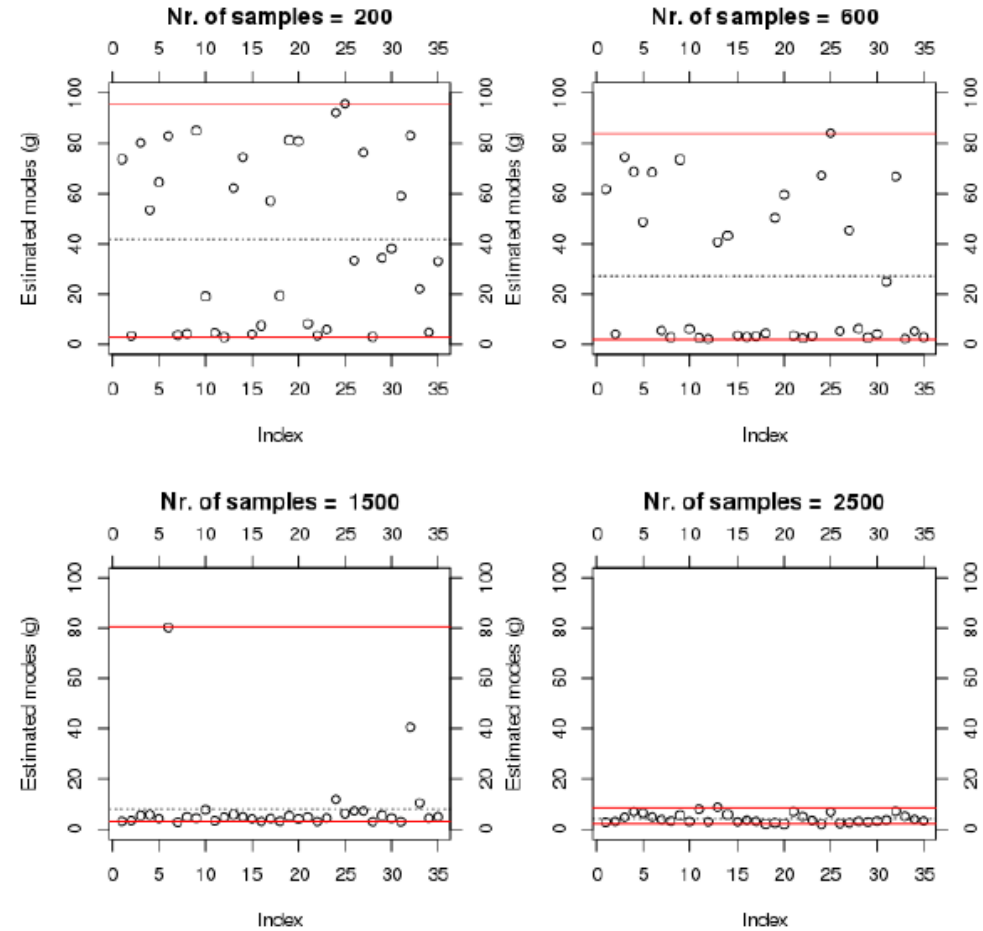
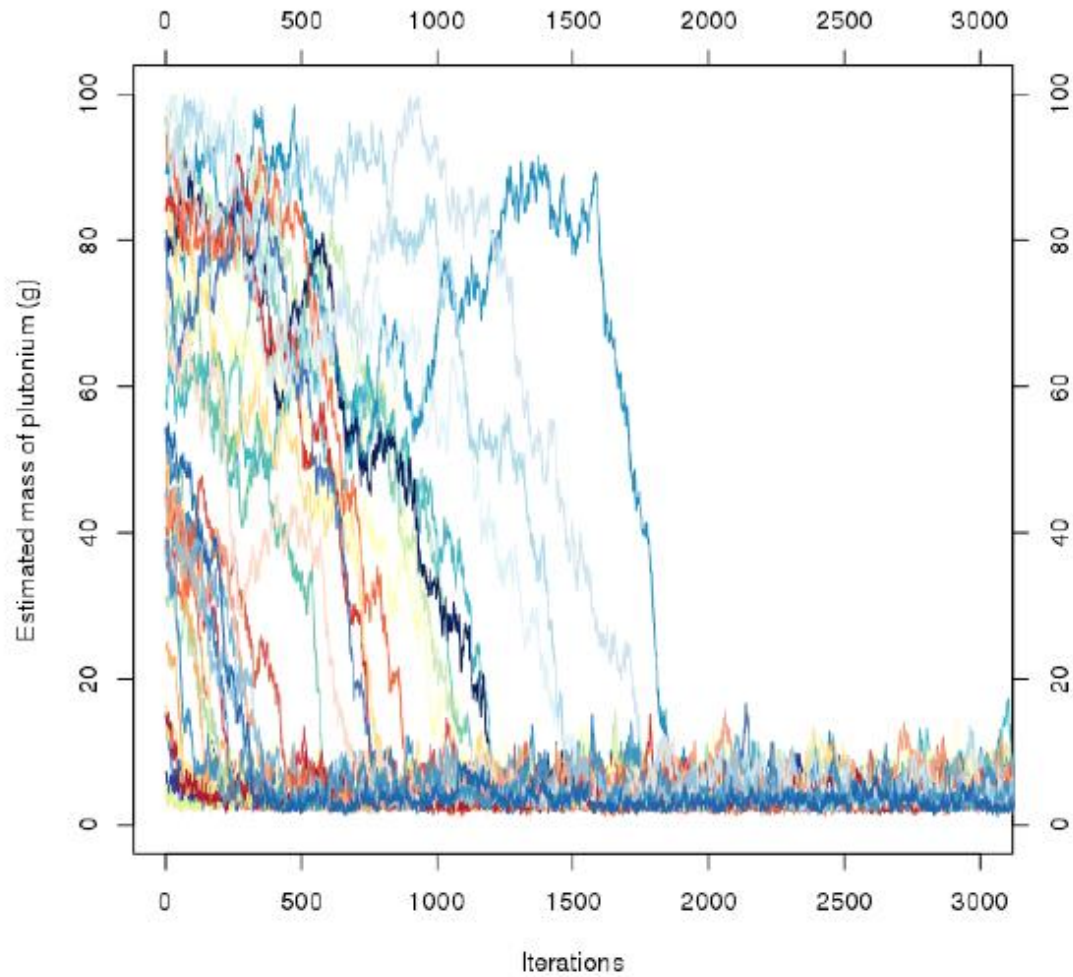
- 242 nuclear drums (100L)
- 6 plutonium standards : 0.4 to 60 grams
- Fixed measurement duration
  
- Fixed measurement distance :  $\approx 60$  cm
- Global uncertainties:  $\pm 42\%$

### Validation steps :

0. Convergence analysis
1. Linearity :  
*Assay on plutonium standards*
2. Reproducibility  
*Repetitions on 10 items (drums)*
3. Comparison  
*Comparison of results between MADAGASCAR and the Bayesian approach*

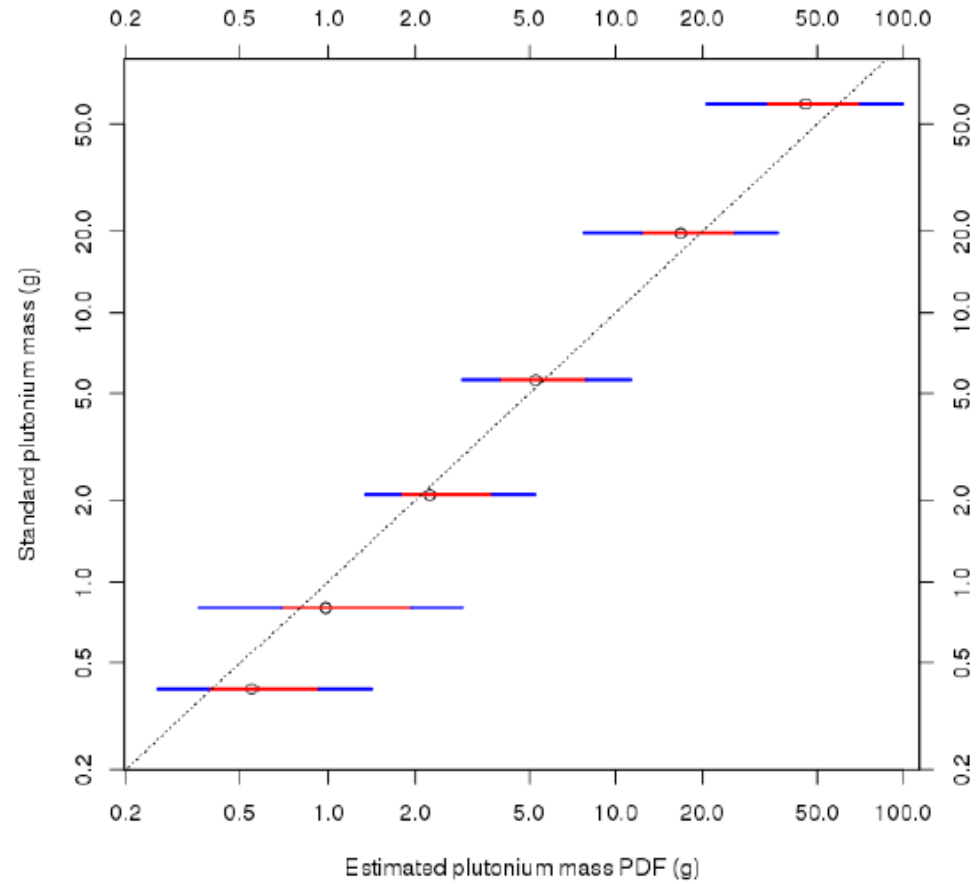
### Hardware :

- 72 cores (35 Markov chains)



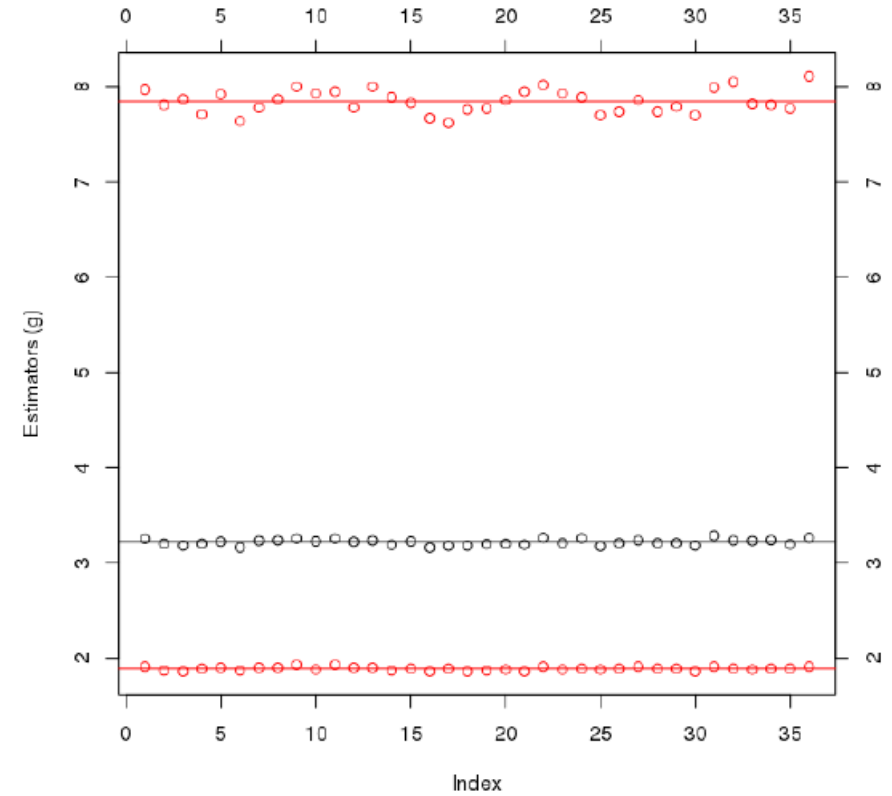
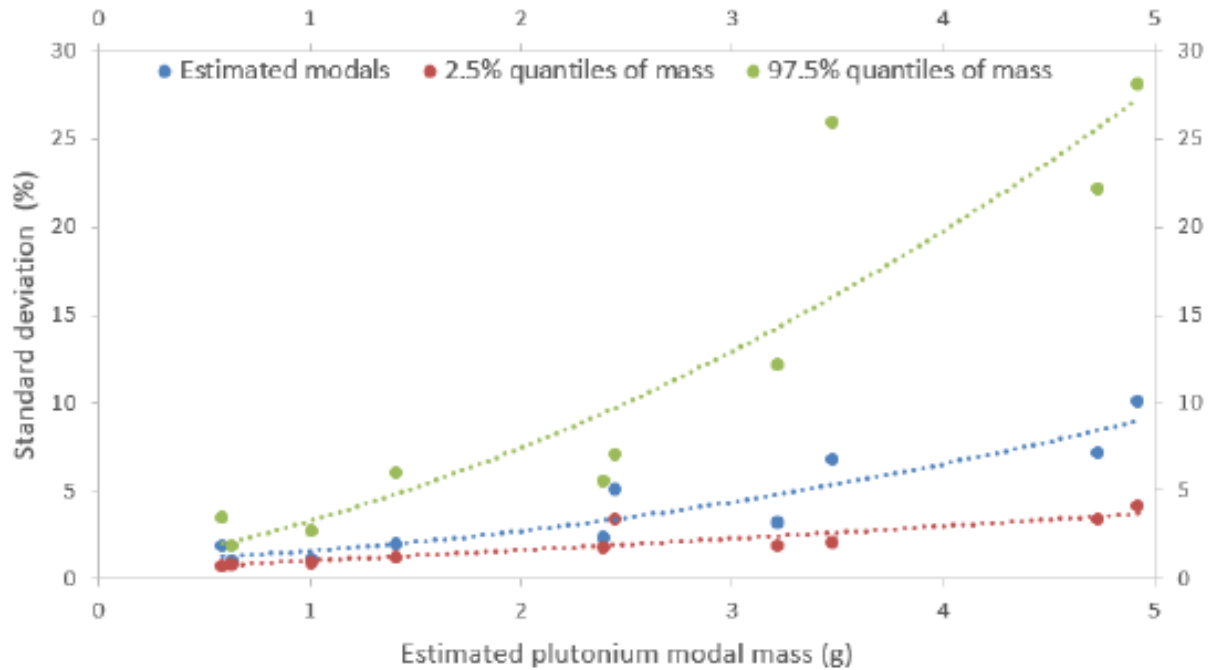
## 6 plutonium standards: 0.4 to 60 grams

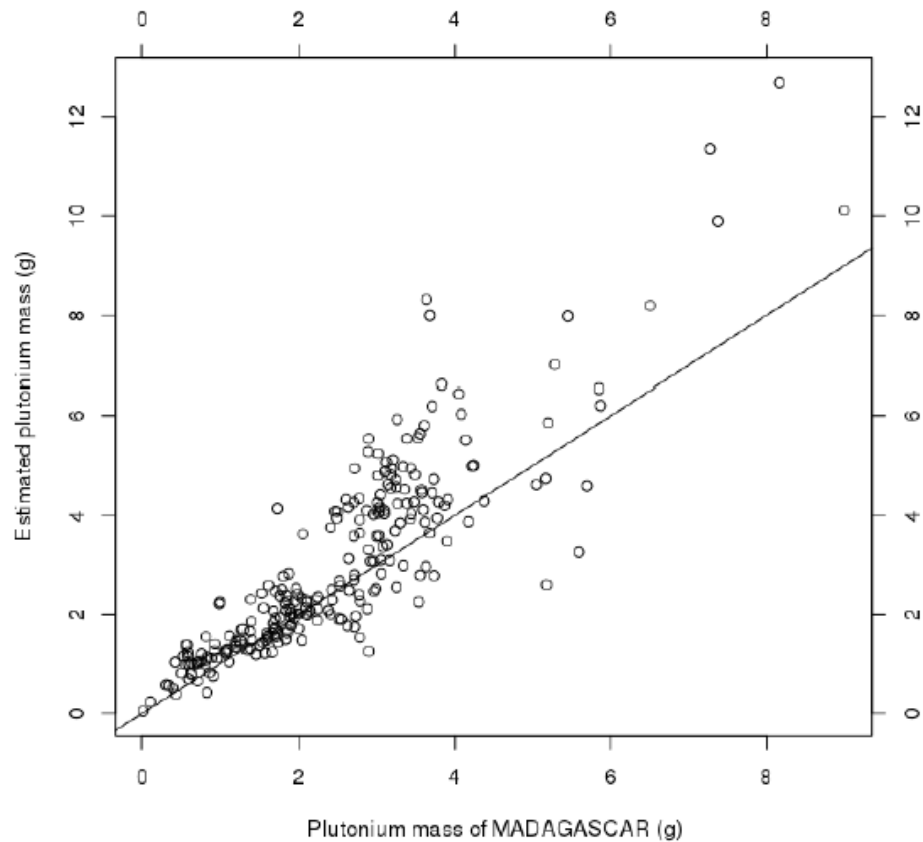
Item	$M_{Pu}(g)$	$M_{Q1}(g)$	$M_{Q2}(g)$	$M_{Mod}(g)$	$M_{Q3}(g)$	$M_{Q4}(g)$
1.	0.400	0.26	0.39	0.55	0.93	1.42
2.	0.800	0.36	0.69	0.98	1.95	2.94
3.	2.104	1.35	1.79	2.26	3.72	5.22
4.	5.619	2.93	3.94	5.27	7.91	11.3
5.	19.731	7.71	12.2	16.9	26.0	36.4
6.	59.541	20.8	33.3	45.6	71.0	99.8



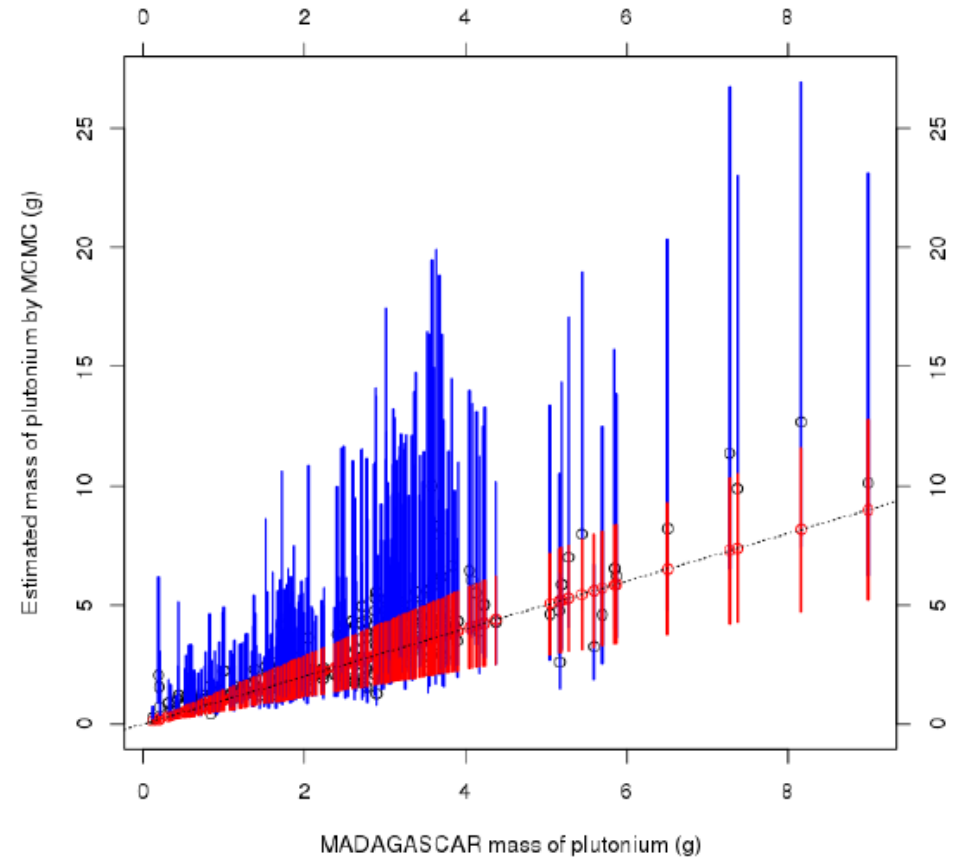
< 30 repetitions on 10 items (drums)

Calculation duration: 15 min





91% of estimated masses  $\in$  CI95% of MADAGASCAR



92,3% of estimated mass PDF overlap 50% of the MADAGASCAR CI95% ( $\pm 42\%$ )

- Validation : good results on plutonium standards
  - Comparison : good results on simple cases : low bulk density ( $< 0,4 \text{ g.cm}^3$ )
  - Useful priors for physicists : bulk density, compositions, Gaussian, Uniform, etc.
  - Easy to code (Python) and possibilities to use specific libraries
  - Breaking point with classical approach : scalars vs PDF
  - Available to other RN (Am, FP, activated)
- 
- Multigamma RN only
  - Increasing uncertainties



**Thanks for your attention**