## Kernel ANOVA Decomposition for Gaussian process modeling

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MASCOT NUM 2011 workshop
Villard de Lans, the $23^{\text {th }}$ of March

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## Gaussian process models

Let $f: D \subset R^{d} \rightarrow R$ be a function which value is known on a DoE $X=\left(x^{1}, \ldots, x^{n}\right)$.

## The kriging model relies on the choice of the kernel $K$

$$
m(x)=k(x)^{T} \mathrm{~K}^{-1} Y \quad \text { and } \quad v(x)=K(x, x)-k(x)^{T} \mathrm{~K}^{-1} k(x)
$$





## Gaussian process models

When the dimension of the input space increases, the kriging model really becomes a black-box.

$$
m(x)=k(x)^{\top} \mathrm{K}^{-1} Y
$$

## Major drawbacks for usual kernels :

- The models cannot easily be interpreted.
- Without computation, what is the effect of $x^{1}$ on $m(x)$ ?
- The importance of the variables $x^{i}$ is supposed to be similar.
- What if the variance is not the same in each direction?


## outline

We present here a method inspired from the ANOVA decomposition that allows to tackle those issues.

The talk is organized as follow :

- Kernel ANOVA Decomposition (KAD)
- Selection of relevant terms : the HKL method.
- Example of application : The MARTHE benchmark.


## Kernel ANOVA Decomposition

Any square integrable function $f: D \rightarrow \mathbb{R}$ may be written

## ANOVA Decomposition

$$
f(x)=f_{0}+\sum_{i=1}^{d} f_{i}\left(x_{i}\right)+\sum_{1 \leq i<j \leq d} f_{i, j}\left(x_{i}, x_{j}\right)+\cdots+f_{1, \ldots, d}\left(x_{1}, \ldots, x_{d}\right)
$$

where :

- Any two terms of the decomposition are $\perp$ in $L^{2}(D)$,
- the integral of $f_{\alpha_{1}, \ldots, \alpha_{p}}(x)$ with respect to any $x_{\alpha_{i}}$ is null.


## Kernel ANOVA Decomposition

For $D \subset \mathbb{R}$, the space $L^{2}(D)$ may be decomposed as follows :

$$
\begin{aligned}
f(x) & =\int_{D} f(s) \mathrm{d} s+\left(f(x)-\int_{D} f(s) \mathrm{d} s\right) \\
L^{2}(D) & =\mathcal{L}_{0} \stackrel{\perp}{\oplus} \mathcal{L}_{1}
\end{aligned}
$$

where $\mathcal{L}_{0}$ is the space of the functions equal to a constant and $\mathcal{L}_{1}$ the space of function with zero mean.

For $\mathcal{D}=D_{1} \times \cdots \times D_{d} \subset \mathbb{R}^{d}$, we obtain

$$
L^{2}(\mathcal{D})=\prod_{i=1}^{d} L^{2}\left(D_{i}\right)=\prod_{i=1}^{d}\left(\mathcal{L}_{0}^{i} \stackrel{\perp}{\oplus} \mathcal{L}_{1}^{i}\right)=\sum_{I \in\{0,1\}^{d}} \mathcal{L}_{l}
$$

## Kernel ANOVA Decomposition

Similarly, let $\mathcal{H}$ be a one-dimensional RKHS with kernel $k$. We call $\mathcal{H}_{1}$ the subspace of $\mathcal{H}$ with zero mean functions :

$$
g \in \mathcal{H}_{1} \Leftrightarrow \int_{D} g(s) \mathrm{d} s=0
$$

The Riesz theorem gives

$$
\exists!R \in \mathcal{H} \text { such that } \forall g \in \mathcal{H}, \int_{D} g(s) \mathrm{d} s=\langle R, g\rangle_{\mathcal{H}}
$$

We have an orthogonal decomposition of $\mathcal{H}$ :

$$
\mathcal{H}=\mathcal{H}_{0} \stackrel{\perp}{\oplus} \mathcal{H}_{1}
$$



## Kernel ANOVA Decomposition

Using the reproducing property of $k$, we get the expression of $R(x)$ :

$$
R(x)=\langle R, k(x, .)\rangle_{\mathcal{H}}=\int_{D} k(x, s) \mathrm{d} s
$$



## proposed ANOVA-Iike decomposition

Let $k_{0}$ and $k_{1}$ be the reproducing kernels of $\mathcal{H}_{0}$ and $\mathcal{H}_{1}$. As $\mathcal{H}=\mathcal{H}_{0}+\mathcal{H}_{1}$, we have :

$$
k(x, y)=k_{0}(x, y)+k_{1}(x, y)
$$

Using the orthogonal projection on $\mathcal{H}_{0}$ one can calculate :

$$
\begin{aligned}
& k_{0}(x, y)=\frac{\int_{D} k(x, s) \mathrm{d} s \int_{D} k(y, s) \mathrm{d} s}{\int_{D \times D} k(s, t) \mathrm{d} s \mathrm{~d} t} \\
& k_{1}(x, y)=k(x, y)-\frac{\int_{D} k(x, s) \mathrm{d} s \int_{D} k(y, s) \mathrm{d} s}{\int_{D \times D} k(s, t) \mathrm{d} s \mathrm{~d} t}
\end{aligned}
$$

## proposed ANOVA-Iike decomposition

## Probabilistic interpretation

Let $Z_{0}$ and $Z_{1}$ be centered GP with kernels $k_{0}$ and $k_{1}$

## ANOVA Decomposition for GP

$$
Z(x)=Z_{0}(x)+Z_{1}(x)
$$

with

- $Z_{0}$ and $Z_{1}$ independent
- $\int_{D} Z_{1}(x) \mathrm{d} x=0 \quad$ (with proba. 1)


## proposed ANOVA-Iike decomposition

## Probabilistic interpretation

$Z_{0}$ and $Z_{1}$ may also be defined as:

$$
\begin{aligned}
& Z_{0}(x)=\mathrm{E}\left[Z(x) \mid \int_{D} Z(s) \mathrm{d} s\right]=\frac{\int_{D} k(x, s) \mathrm{d} s}{\int_{D \times D} k(s, t) \mathrm{d} s \mathrm{~d} t} \int_{D} Z(s) \mathrm{d} s \\
& Z_{1}(x)=Z(x)-Z_{0}(x)
\end{aligned}
$$

Then $Z_{0}$ and $Z_{1}$ have kernel $k_{0}$ and $k_{1}$.

## proposed ANOVA-Iike decomposition

Given $Z$, we can decompose any path $Z(\omega)$ as $Z_{0}(\omega)+Z_{1}(\omega)$


Reciprocally, given $K_{0}$ and $K_{1}$ we can build paths of $Z$ by summing $Z_{0}(\omega)$ and $Z_{1}(\omega)$.

## proposed ANOVA-Iike decomposition

## What happens for the multi-dimensional case?

If K is a tensor product kernel, the generalization is straightforward :

$$
\begin{aligned}
K & =k \times k=\left(k_{0}+k_{1}\right) \times\left(k_{0}+k_{1}\right) \\
& =k_{0} k_{0}+k_{1} k_{0}+k_{0} k_{1}+k_{1} k_{1} \\
& =K_{00}+K_{10}+K_{01}+K_{11}
\end{aligned}
$$

Or similarly

$$
\begin{aligned}
\mathcal{H}_{K} & =\mathcal{H} \otimes \mathcal{H} \\
& =\left(\mathcal{H}_{0} \stackrel{\perp}{\oplus} \mathcal{H}_{1}\right) \otimes\left(\mathcal{H}_{0} \oplus \mathcal{H}_{1}\right) \\
& =\mathcal{H}_{0} \otimes \mathcal{H}_{0} \stackrel{\perp}{\oplus} \mathcal{H}_{1} \otimes \mathcal{H}_{0} \stackrel{\perp}{\oplus} \mathcal{H}_{0} \otimes \mathcal{H}_{1} \stackrel{\perp}{\oplus} \mathcal{H}_{1} \otimes \mathcal{H}_{1}
\end{aligned}
$$

## proposed ANOVA-like decomposition

We use those kernels to simulates paths of $Z_{00}, Z_{10}, Z_{01}$ and
$Z_{11}$ :


As previously, the paths have original properties.

## KAD $\neq$ ANOVA kernels

Link with usual ANOVA kernels ${ }^{4}$ :

$$
K_{A N O V A}(x, y)=\prod_{i}\left(1+k\left(x_{i}, y_{i}\right)\right)
$$

For this decomposition, we have

- $\mathcal{H}_{0}$ is a space of constant functions.
- $\mathcal{H}_{1}$ is not the space of zero-mean functions.
- We do not have anymore $\mathcal{H}_{0} \perp \mathcal{H}_{1}$

4. Stitson et AI, Support vector regression with ANOVA decomposition kernels. Technical report, Royal Holloway, University of London, 1997.

## Kernel ANOVA Decomposition

This decomposition may be used for many tasks :

- visualize main effects without computation.
- modify the weight of the sub-kernels :

$$
K^{*}=\lambda_{00} K_{00}+\lambda_{10} K_{10}+\lambda_{01} K_{01}+\lambda_{11} K_{11}
$$

or built sparse models

$$
K^{*}=K_{00}+K_{10}+K_{01}+K_{11}
$$

We will now consider those two points on two test functions.

## Application 1 ：interpretation

We consider a test function ${ }^{5}$ with observation＇s noise $\mathcal{N}(0,1)$ ：

$$
\begin{aligned}
f: & {[0,1]^{10} \rightarrow \mathbb{R} } \\
x & \mapsto 10 \sin \left(\pi x_{1} x_{2}\right)+20\left(x_{3}-0.5\right)^{2}+10 x_{4}+5 x_{5}
\end{aligned}
$$

The steps for approximating $f$ with a GP model are ：
1 Learn $f$ on a DoE（here LHS maximin with 180 points）
2 estimate the kernel parameters $\psi$（MLE），
3 build the kriging mean predictor $\hat{f}$ based on $K^{\psi}$
As $\hat{f}$ is a function of 10 variables，the model can not easily be represented ：it is usually considered as a black－box．

5．S．R．Gunn and J．S．Kandola．Structural modelling with sparse kernels．Machine learning， 2002

## Application 1 : interpretation

with KAD, $\hat{f}$ can be written as the sum of sub-models

$$
K^{\psi}(x, y)=\sum_{l \in\{0,1\}^{d}} K_{l}(x, y)
$$

$\Downarrow$

$$
\begin{aligned}
\hat{f}(x) & =k(x)^{T}\left(\mathrm{~K}+\tau^{2} \mathrm{I} \mathrm{I}\right)^{-1} Y \\
& =\left(\sum_{l \in\{0,1\}^{d}} k_{l}(x)\right)^{T}\left(\mathrm{~K}+\tau^{2} \mathrm{Id}\right)^{-1} Y \\
& =\sum_{l \in\{0,1\}^{d}}\left(k_{l}(x)^{T}\left(\mathrm{~K}+\tau^{2} \mathrm{Id}\right)^{-1} Y\right)=\sum_{l \in\{0,1\}^{d}} \hat{f}_{l}(x)
\end{aligned}
$$

## Application 1 : interpretation

## The univariate sub-models are :











(we had $f(x)=10 \sin \left(\pi x_{1} x_{2}\right)+20\left(x_{3}-0.5\right)^{2}+10 x_{4}+5 x_{5}$ )

## Application 2 : HKL

In order to

- Construct parsimonious models,
- Change the weights of the sub-kernels, we will use a method called Hierarchical Kernel Learning (HKL) developed by F. Bach in 2009.


## Application 2 : HKL

## Hierarchical kernel Learning

Given a set of kernel $\left\{K_{1}, \ldots, K_{n}\right\}$ the point is to select a limited number of them adapted to the data :

$$
\left\{K_{1}, \ldots, K_{n}\right\} \rightarrow K^{*}=\lambda_{1} K_{1}+\lambda_{2} K_{2}+\lambda_{3} K_{3}+\cdots+\lambda_{n} K_{n}
$$

Like other methods (COSSO, SUPANOVA), the sparsity and the coefficients are obtained by minimizing a trade off between 2 norms :

$$
\text { criterion }="\|f-\hat{f}\|_{2}+c| | \hat{f} \|_{1} "
$$

## Application 2 : HKL

Let us combine KAD and HKL to model the test function $f$.
The steps for modeling $f$ are :
1 Construct a DoE $X$, and calculate the response $Y=f(X)$
2 Estimate the kernels parameter $\psi$ (MLE),
3 Decompose $K_{\psi}$ using KAD.
4 Apply HKL.
5 Get the final GP model.

## Application 2 : HKL

Here, the total number of kernels is $\mathbf{2}^{\mathrm{d}}=\mathbf{1 0 2 4}$.
As $f(x)=10 \sin \left(\pi x_{1} x_{2}\right)+20\left(x_{3}-0.5\right)^{2}+10 x_{4}+5 x_{5}+\varepsilon(x)$, we could expect HKL to find 7 active kernels.

The algorithm gives 84 active kernels but the weight associated to the unexpected ones is around 0 .

To evaluate the quality of the model, we compare it to a usual GP on 2000 test points. We compute

$$
Q_{2}=1-\frac{\sum\left(\hat{f}_{i}-f_{i}\right)^{2}}{\sum\left(f_{i}-\bar{f}\right)^{2}}
$$

## Application 2 : HKL

Varying X, we finally obtain :


On this example, KAD-HKL performs significantly better.

## The Marthe case study

The MARTHE case study is part of the GDR-mascotnum benchmark.

Objective : estimation of an environmental impact

- Radioactive waste storage on a Russian site from 1943 to 1974
- Upper groundwater contamination in ${ }^{90} \mathrm{Sr}$.

The aim is to model the evolution of the radioactive plume.

## The Marthe case study

The MARTHE computer code has

- 20 input variables ( 7 permeabilities, 1 porosity, ... )
- 10 output variables (locations to predict the ${ }^{90} \mathrm{Sr}$ concentration)

We know the concentration for 2002, we want to predict it for 2010.



MARTHE


## The Marthe case study

The design is composed of 300 points. 250 are used for training and 50 for external validation.

## Results



1 Regression
2 Boosting Trees
3 Marrel and looss
4 KAD-HKL

## Conclusion

## Advantages of the proposed Kernel Anova Decomposition

- Interpretation of High dimensional GP models
- Allows to set various variance parameters
- Allows to split multi-dimensional problems into low-dimensional ones
- Well designed for HKL


## Applications

- Model accuracy improvement
- Calculation of Sobol indices.
- Can be coupled with any kriging software


## Conclusion

## Thank you for your attention

F. Bach, High-Dimensional Non-Linear Variable Selection through Hierarchical Kernel Learning, hal-00413473, 2009. B. Iooss and A. Marrel, Benchmark of GdR MASCOT NUM Données MARTHE, 2008.

