

Sparse methods in machine learning - II

Matrix Sparsity - Structured Sparsity



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Outline

1 Matrix Sparsity

- Learning on matrices
- Forms of sparsity for matrices
- Multivariate learning and row sparsity
- Sparse spectrum
- Sparse Principal Component Analysis
- Dictionary learning, image denoising and inpainting

2 Structured sparsity

- Overview
- Sparsity patterns stable by union
- Sparse Structured PCA
- Hierarchical Dictionary Learning

3 Conclusion

Learning on matrices - Collaborative Filtering (CF)

- Given n_x "movies" $\mathbf{x} \in \mathcal{X}$ and n_y "customers" $\mathbf{y} \in \mathcal{Y}$,
- predict the "rating" $z(\mathbf{x}, \mathbf{y}) \in \mathcal{Z}$ of customer \mathbf{y} for movie \mathbf{x}
- Training data: large $n_x \times n_y$ incomplete matrix Z that describes the known ratings of some customers for some movies
- Goal: complete the matrix.

1			1					2	
						2			1
2						3			3
			1		2			1	
	1		3			1			1
1		2						1	3
				3					

Learning on matrices - Multivariate problems

- Multivariate linear regression

$$\begin{array}{c} \mathbf{Y} \\ n \times K \end{array} = \begin{array}{c} \mathbf{X} \\ n \times p \end{array} \cdot \begin{array}{c} \mathbf{W}^* \\ p \times K \end{array} + \begin{array}{c} \boldsymbol{\epsilon} \\ n \times K \end{array}$$

K -variate output design matrix coefficient matrix noise

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- Multiclass classification

$$\min_W \sum_{i=1}^n \frac{1}{n} \ell(w_1^\top x^{(i)}, \dots, w_K^\top x^{(i)}, y^{(i)})$$

with

- $y^{(i)} \in \{0, 1\}^K$
- One parameter vector $w_k \in \mathbb{R}^p$ per class
- ℓ is e.g. the multiclass logistic loss

Learning on matrices - Multi-task learning

- k prediction tasks on same covariates $x \in \mathbb{R}^p$
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$$W = [w^1, \dots, w^K] = \begin{bmatrix} w_1^1 & \dots & w_1^K \\ \vdots & w_j^k & \vdots \\ w_p^1 & \dots & w_p^K \end{bmatrix} = \begin{bmatrix} w_1 \\ \vdots \\ w_p \end{bmatrix} \in \mathbb{R}^{p \times K}$$

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- Many applications
 - Multi-category classification (one task per class) (Amit et al., 2007)
- Share parameters between various tasks
 - similar to fixed effect/random effect models (Raudenbush and Bryk, 2002)

Learning on matrices - Image denoising

- Simultaneously denoise all patches of a given image
- Example from Mairal et al. (2009b)



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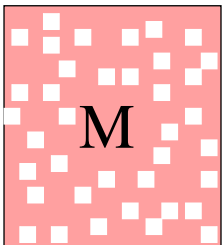
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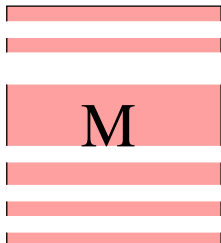
Two types of sparsity for matrices $M \in \mathbb{R}^{n \times p}$

I - Directly on the elements of M

Many zero elements: $M_{ij} = 0$



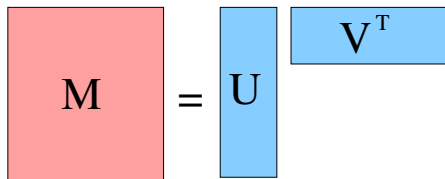
Many zero rows (or columns):
 $(M_{i1}, \dots, M_{ip}) = 0$



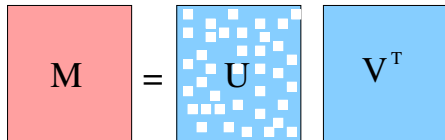
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II - Through a factorization of $M = UV^T$

- $M = UV^T$, $U \in \mathbb{R}^{n \times m}$ and $V \in \mathbb{R}^{n \times m}$
- **Low rank:** m small



- **Sparse decomposition:** U sparse



- Same as dictionary learning with notations $M = X$, $V = D$ and $A = U^T$.

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Joint variable selection (Obozinski et al., 2009)

$$\sum_{k=1}^K \frac{1}{n_k} \sum_{i=1}^{n_k} \ell_k((w^k)^\top x_k^{(i)}, y_k^{(i)}) + \lambda \Omega(W)$$

- Joint matrix of predictors $W = (w_1, \dots, w_k) \in \mathbb{R}^{p \times K}$:

$$W = [w^1, \dots, w^K] = \begin{bmatrix} w_1^1 & \dots & w_1^K \\ \vdots & w_j^k & \vdots \\ w_p^1 & \dots & w_p^K \end{bmatrix} = \begin{bmatrix} w_1 \\ \vdots \\ w_p \end{bmatrix} \in \mathbb{R}^{p \times K} \rightarrow$$



- Select all variables that are relevant to at least one task

$$\sum_{k=1}^K \frac{1}{n_k} \sum_{i=1}^{n_k} \ell_k((w^k)^\top x_k^{(i)}, y_k^{(i)}) + \lambda \sum_{j=1}^p \|w_j\|_2$$

- Can improve performance over ℓ_1 -regularization (Obozinski et al., 2008; Lounici et al., 2009)

Applications for simultaneous selection

Multi-class image classification (Quattoni et al., 2008)

- algorithms for the regularization by a sum of l_∞ -norm (l_1/l_∞).
- increase in performance

Multi-class tumor classification based on gene expression data (Obozinski et al., 2009)

- smaller gene signatures

Source localization in M/EEG inverse problems from several experiments (Gramfort, 2010)

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Rank constraints and sparsity of the spectrum

Rank

Given a matrix $M \in \mathbb{R}^{n \times p}$

- Singular value decomposition (SVD): $M = U \text{Diag}(s) V^T$
where U, V orthogonal, $s \in \mathbb{R}_+^m$ are singular values
- $\text{Rank}(M) = \|s\|_0$
- Rank of M is the minimum size m of **all** factorizations of M into $M = UV^T$, $U \in \mathbb{R}^{n \times m}$ and $V \in \mathbb{R}^{p \times m}$

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Rank constrained Learning

$$\min_{W \in \mathbb{R}^{p \times k}} L(W) \quad \text{s.t.} \quad \text{rank}(W) \leq m$$

Examples:

- Collaborative filtering
- Multi-task learning with task parameters assumed in a low dimensional subspace (Argyriou et al., 2009)

Low-rank via factorization

Reduced-rank multivariate regression

$$\min_W \|Y - XW\|_F^2 \quad \text{s.t. rank}(W) \leq k$$

- Well studied (Anderson, 1951; Izenman, 1975; Reinsel and Velu, 1998)
- Is solved directly using the SVD (by OLS + SVD + projection)

General factorization

$$\min_{U \in \mathbb{R}^{p \times m}, V \in \mathbb{R}^{k \times m}} L(UV^T)$$

- Still non-convex but convex w.r.t. U and V separately
- Optimization by alternating procedures

Trace norm relaxation

With SVD $W = U\text{Diag}(s)V^T$, $\text{rank}(W) = \|s\|_0 \xrightarrow{\text{Relax}} \|s\|_1$.

- $M \mapsto \|s\|_1$ is actually a *unitary invariant* norm: the trace norm, nuclear norm or unitary norm
- Write it $M \mapsto \|M\|_{\text{tr}}$
- Dual norm to the spectral norm $\|M\|_2 = \|s\|_\infty$

Trace norm regularization

- Convex problem $\min_{W \in \mathbb{R}^{p \times k}} L(W) + \lambda \|W\|_{\text{tr}}$
- Algorithms:
 - Proximal methods
 - Iterated Reweighted Least-Square (Argyriou et al., 2009)
 - Common bottleneck: require iterative SVD

Trace norm and collaborative filtering

$$\min_{M \in \mathbb{R}^{p \times n}} \sum_{(i,j) \in S} \|M_{ij} - M_{ij}^0\|_2^2 + \lambda \|M\|_{tr}$$

- semi-definite program (Fazel et al., 2001)
- see also max-margin approaches to CF (Srebro et al., 2005)
- Statistical results:
 - High-dimensional inference for noisy matrix completion (Srebro et al., 2005; Candès and Plan, 2009)
 - May recover entire matrix from slightly more entries than the minimum of the two dimensions

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Two different views of PCA

Given data matrix $X = (x_1^\top, \dots, x_n^\top)^\top \in \mathbb{R}^{n \times p}$,

Two different views of PCA

Given data matrix $X = (x_1^T, \dots, x_n^T)^T \in \mathbb{R}^{n \times p}$,

Analysis view

Find projection $v \in \mathbb{R}^p$ maximizing variance:

$$\begin{aligned} \max_{v \in \mathbb{R}^p} \quad & v^T X^T X v \\ \text{s.t.} \quad & \|v\|_2 \leq 1 \end{aligned}$$

→ deflate and iterate to obtain more components.

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Synthesis view

Find $V = [v_1, \dots, v_k]$ s.t. x_i have low reconstruction error on $\text{span}(V)$:

$$\min_{u_i, v_i \in \mathbb{R}^p} \left\| X - \sum_{i=1}^k u_i v_i^T \right\|_F^2$$

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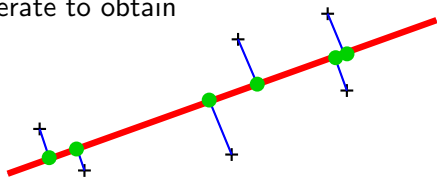
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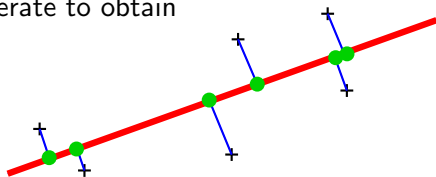
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- For regular PCA, the two views are **equivalent!**
- Not true if constraints on u, v change

Sparse PCA - Analysis view

Add sparsity constraint:

$$\max_{\|v\|_2=1, \|v\|_0 \leq k} v^T X^T X v$$

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Convex relaxation **DSPCA** (d'Aspremont et al., 2007)

relaxed into

$$\max_{\|v\|_2=1, \|v\|_1 \leq k^{1/2}} v^T X^T X v$$

then relaxed into

$$\max_{M \succeq 0, \text{tr}(M)=1, \mathbf{1}^T |M| \mathbf{1} \leq k} \text{tr}(X^T X M), \quad \text{using } M = vv^T.$$

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- Requires deflation for multiple components (Mackey, 2009)
- More refined convex relaxation (d'Aspremont et al., 2008)
- Analysis of non-convex formulation (Moghaddam et al., 2006)

Sparse PCA - Synthesis view

Find $V = [v_1, \dots, v_m] \in \mathbb{R}^{p \times n}$ **sparse** and $U = [u_1, \dots, u_m] \in \mathbb{R}^{n \times n}$ s.t.

$$\sum_{i=1}^n \left\| x_i - \sum_{j=1}^m u_{ij} v_j \right\|_2^2 \text{ is small} \Leftrightarrow \|X - UV^T\|_F^2, \text{ is small}$$

Sparse matrix factorization (Witten et al., 2009; Bach et al., 2008)

- Penalize columns v_i of V by the ℓ_1 -norm for sparsity
- Penalize columns u_i of U by the ℓ_2 -norm to avoid trivial solutions

$$\min_{U, V} \|X - UV^T\|_F^2 + \frac{\lambda}{2} \sum_{i=1}^m \{ \|u_i\|_2^2 + \|v_i\|_1^2 \}$$

$$\min_{U, V} \|X - UV^T\|_F^2 + \lambda \sum_i \|u_i\|_2 \|v_i\|_1$$

$$\min_{U, V} \|X - UV^T\|_F^2 + \lambda \sum_i \|v_i\|_1 \quad \text{s.t. } \|u_i\|_2 \leq 1$$

yield the same solutions for $u_j v_j^T$ (Bach et al., 2008).

Efficient algorithms for sparse matrix factorization

Focus on previous formulation:

$$\min_{U, V} \|X - UV^T\|_F^2 + \lambda \sum_i \|v_j\|_1 \quad \text{s.t. } \|u_j\|_2 \leq 1$$

- Problem is convex in U and V separately, but not jointly.
→ Alternating scheme: optimize U and V in turn.
- Even better: use simple column updates (Lee et al., 2007; Witten et al., 2009):

With $\tilde{X} = X - \sum_{j' \neq j} u_{j'} v_{j'}^T$, we have

$$\text{either } u_j \leftarrow \frac{\tilde{X} v_j}{\|\tilde{X} v_j\|} \quad \text{or} \quad v_j \leftarrow \operatorname{argmin}_v \|X^T u_j - v\|_2^2 + \lambda \|v\|_1$$

- requires no matrix inversion
- + can take advantage of efficient algorithms for Lasso
- can use warm start + active sets

Sparse PCA - Synthesis view II

“Sparse projector” (Zou et al., 2006)

Find $\tilde{V} = [\tilde{v}_1, \dots, \tilde{v}_m] \in \mathbb{R}^{p \times n}$ and $V = [v_1, \dots, v_m] \in \mathbb{R}^{p \times n}$ such that

$$\min_{\tilde{V}, V} \sum_{i=1}^n \|x_i - \tilde{V}V^T x_i\|_2^2 + \lambda_1 \|V\|_1 + \lambda_2 \|V\|_F^2$$

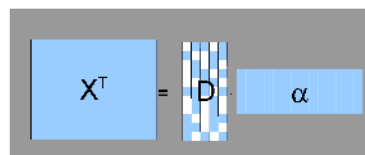
such that $\tilde{V}^T \tilde{V} = I_p$

- The data should be reconstructed from sparse projections
- Non-convex formulation \rightarrow alternating minimization

Sparse PCA vs Dictionary Learning a.k.a. Sparse Coding

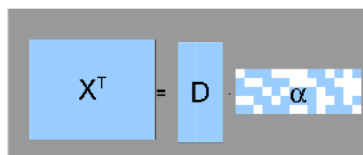
In signal processing $X^T = \underbrace{V}_{\text{dictionary } D} \underbrace{U^T}_{\text{decomposition coefficients } \alpha} = D\alpha$

Sparse PCA



- e.g. microarray data
- sparse dictionary
- (Witten et al., 2009; Bach et al., 2008)

Dictionary Learning



- e.g. overcomplete dictionaries for natural images
- sparse decomposition
- (Elad and Aharon, 2006)

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Dictionary Learning

$$\min_{\substack{\mathbf{A} \in \mathbb{R}^{k \times n} \\ \mathbf{D} \in \mathbb{R}^{p \times k}}} \sum_{i=1}^n (\|\mathbf{x}_i - \mathbf{D}\boldsymbol{\alpha}_i\|_2^2 + \lambda \|\boldsymbol{\alpha}_i\|_1) \quad \text{s.t.} \quad \forall j, \|\mathbf{d}_j\|_2 \leq 1.$$

- As before not jointly convex but convex in each \mathbf{d}_j and $\boldsymbol{\alpha}_j$
- Alternating scheme becomes slow for large signal databases ...

[\rightarrow] use *Stochastic Optimization / Online learning* (Mairal et al., 2009a)

- can handle potentially infinite datasets
- can adapt to dynamic training sets

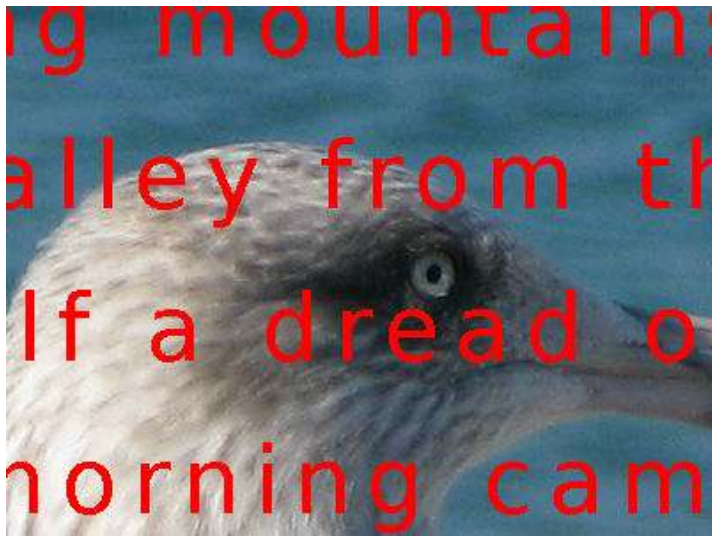
Inpainting a 12-Mpixel photograph



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Sparsity with Structure

Notion emerged very recently through the work of several authors: Yuan and Lin (2006), Zhao et al. (2009), Baraniuk et al. (2008), Bach (2008), Jacob et al. (2009), Jenatton et al. (2009), Jenatton et al. (2010b), He and Carin (2009), Huang et al. (2009).

The support is sparse but we have prior information about its structure.

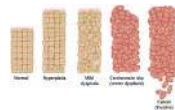
- The variables should be selected in groups.
- The variables lie in a hierarchy.
- The variables lie on a graph or network and the support should be localized or densely connected on the graph.
- The variables are pixels of an image and form rectangles or convex shapes.

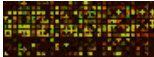
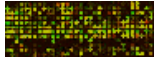

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Biological markers for cancer

Metastasis prognosis: Predict if a tumor will produce metastases.



Gene expression in tumor	Metastasis?
	✓
⋮	⋮
	✗
	?

- Can we predict metastasis and identify few predictive genes?

Biological pathways as relevant groups of genes

Predictive genes are naturally grouped in *biological pathways*

- Correspond to genes participating in same biological mechanisms
- Contain often very correlated genes
- The pathways form overlapping groups
- Ultimately relevant to the biologist

⇒ Instead of selecting genes individually, select entire pathways.

The support is a **union of overlapping groups**.

Sparsity patterns induced for $L(w) + \lambda \Omega(w)$

Lasso: $\Omega(w) = \sum_i |w_i|$



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Group Lasso (Yuan and Lin, 2006): $\Omega(w) = \sum_{g \in \mathcal{G}} \|w_g\|$



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Group Lasso when groups overlap: $\Omega(w) = \sum_{g \in \mathcal{G}} \|w_g\|$



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Sparsity patterns induced for $L(w) + \lambda \Omega(w)$

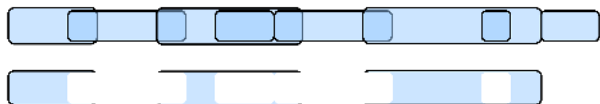
Lasso: $\Omega(w) = \sum_i |w_i|$



Group Lasso (Yuan and Lin, 2006): $\Omega(w) = \sum_{g \in \mathcal{G}} \|w_g\|$



Group Lasso when groups overlap: $\Omega(w) = \sum_{g \in \mathcal{G}} \|w_g\|$



Sparsity patterns induced for $L(w) + \lambda \Omega(w)$

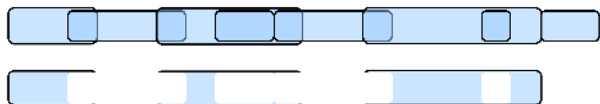
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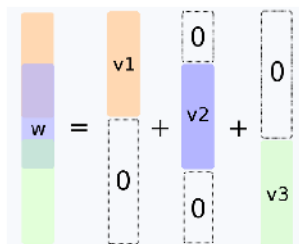


The support obtained is

- An intersection of the complements of the groups set to 0 (cf. Jenatton et al. (2009))
- Not a union of groups

Introducing latent variables v_g :

$$\begin{cases} \min_{w,v} L(w) + \lambda \sum_{g \in \mathcal{G}} \|v_g\|_2 \\ w = \sum_{g \in \mathcal{G}} v_g \\ \text{supp}(v_g) \subseteq g. \end{cases}$$



Properties

- Resulting support is a *union* of groups in \mathcal{G} .
- Possible to select one variable without selecting all the groups containing it.

A new “overlap” norm

Equivalent reformulation

$$\left\{ \begin{array}{l} \min_{w, v} L(w) + \lambda \sum_{g \in \mathcal{G}} \|v_g\|_2 \\ w = \sum_{g \in \mathcal{G}} v_g \\ \text{supp}(v_g) \subseteq g. \end{array} \right. = \min_w L(w) + \lambda \Omega_{\text{overlap}}(w)$$

with

$$\Omega_{\text{overlap}}(w) \triangleq \left\{ \begin{array}{l} \min_v \sum_{g \in \mathcal{G}} \|v_g\|_2 \\ w = \sum_{g \in \mathcal{G}} v_g \\ \text{supp}(v_g) \subseteq g. \end{array} \right. \quad (*)$$

A new “overlap” norm

Equivalent reformulation

$$\left\{ \begin{array}{l} \min_{w, v} L(w) + \lambda \sum_{g \in \mathcal{G}} \|v_g\|_2 \\ w = \sum_{g \in \mathcal{G}} v_g \\ \text{supp}(v_g) \subseteq g. \end{array} \right. = \min_w L(w) + \lambda \Omega_{\text{overlap}}(w)$$

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- $\Omega_{\text{overlap}}(w)$ is a norm of w .

A new “overlap” norm

Equivalent reformulation

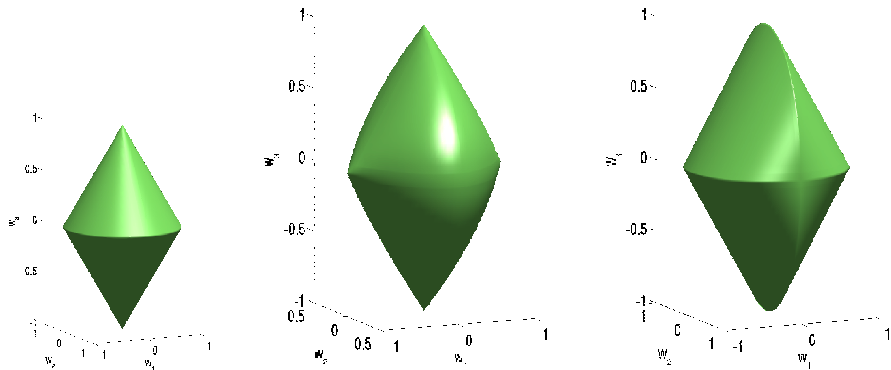
$$\left\{ \begin{array}{l} \min_{w, v} L(w) + \lambda \sum_{g \in \mathcal{G}} \|v_g\|_2 \\ w = \sum_{g \in \mathcal{G}} v_g \\ \text{supp}(v_g) \subseteq g. \end{array} \right. = \min_w L(w) + \lambda \Omega_{\text{overlap}}(w)$$

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- $\Omega_{\text{overlap}}(w)$ is a norm of w .

Overlap and group unity balls



Balls for $\Omega_{\text{group}}^{\mathcal{G}}(\cdot)$ (middle) and $\Omega_{\text{overlap}}^{\mathcal{G}}(\cdot)$ (right) for the groups $\mathcal{G} = \{\{1, 2\}, \{2, 3\}\}$ where w_2 is represented as the vertical coordinate. Left: group-lasso ($\mathcal{G} = \{\{1, 2\}, \{3\}\}$), for comparison.

Results

Breast cancer data

- Gene expression data for 8,141 genes in 295 breast cancer tumors.
- Canonical pathways from MSigDB containing 639 groups of genes, 637 of which involve genes from our study.

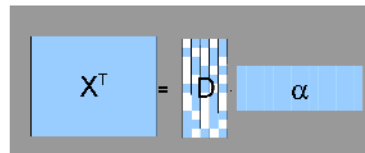
Method	ℓ_1	$\Omega_{\text{overlap}}^G(\cdot)$
Misclassification error	0.38 ± 0.04	0.36 ± 0.03
Number of pathways involved	148, 58, 183	6, 5, 78

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- 2 Structured sparsity
 - Overview
 - Sparsity patterns stable by union
 - **Sparse Structured PCA**
 - Hierarchical Dictionary Learning
- 3 Conclusion

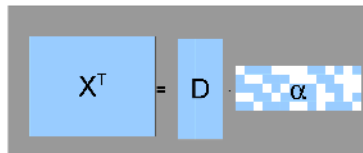
Sparse PCA / Dictionary Learning

Sparse PCA



- e.g. microarray data
- sparse dictionary
- (Witten et al., 2009; Bach et al., 2008)

Dictionary Learning



- e.g. overcomplete dictionaries for natural images
- sparse decomposition
- (Elad and Aharon, 2006)

Other constraints

Structured matrix factorizations - Many instances

- $M = UV^T$, $U \in \mathbb{R}^{n \times m}$ and $V \in \mathbb{R}^{p \times m}$
- **Structure on U and/or V**
 - Low-rank: U and V have few columns
 - Dictionary learning / sparse PCA: U or V has many zeros
 - Clustering (k -means): $U \in \{0, 1\}^{n \times m}$, $U1 = 1$
 - Pointwise positivity: non negative matrix factorization (NMF)
 - Specific patterns of zeros
 - etc.
- **Many applications**
 - e.g., source separation (Févotte et al., 2009), exploratory data analysis

From SPCA to SSPCA

Sparse PCA:

$$\min_{\substack{\mathbf{A} \in \mathbb{R}^{k \times n} \\ \mathbf{D} \in \mathbb{R}^{p \times k}}} \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{D}\boldsymbol{\alpha}_i\|_2^2 + \lambda \sum_{j=1}^k \|\mathbf{d}_j\|_1 \quad \text{s.t.} \quad \forall j, \|\boldsymbol{\alpha}_j\|_2 \leq 1.$$

Sparse structured PCA

$$\min_{\substack{\mathbf{A} \in \mathbb{R}^{k \times n} \\ \mathbf{D} \in \mathbb{R}^{p \times k}}} \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{D}\boldsymbol{\alpha}_i\|_2^2 + \lambda \sum_{j=1}^k \Omega(\mathbf{d}_j) \quad \text{s.t.} \quad \forall j, \|\boldsymbol{\alpha}_j\|_2 \leq 1.$$

- No orthogonality
- Not jointly convex but convex in each \mathbf{d}_j and $\boldsymbol{\alpha}_j$
- \Rightarrow efficient block-coordinate descent algorithms

Faces



Faces

- A basis to decompose faces?
- Eigenfaces
- Find parts?
- Localized components
- NMF (Lee and Seung, 1999)

Faces



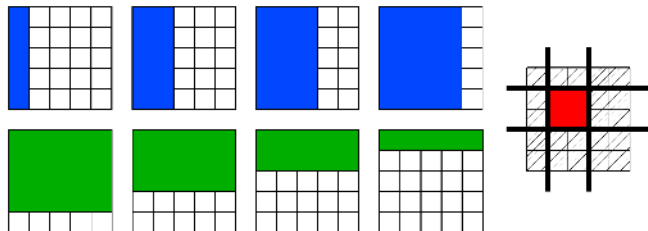
Faces



NMF

Rectangular supports

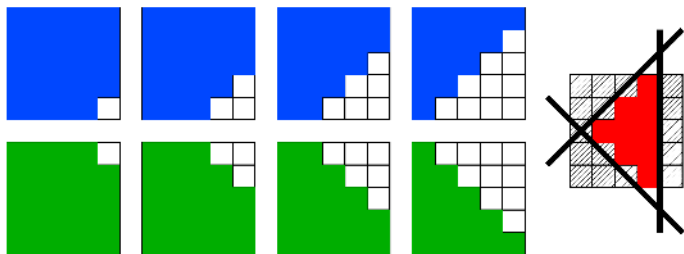
- $\Omega(\mathbf{d}) = \sum_{g \in \mathcal{G}} \|\mathbf{d}_g\|_2$: Selection of rectangles on the 2D-grid.



- \mathcal{G} is the set of blue/green groups (with their not displayed complements)
- Any union of blue/green groups set to zero leads to the selection of a rectangle

General “convex” supports

- $\Omega(\mathbf{d}) = \sum_{g \in \mathcal{G}} \|\mathbf{d}_g\|_2$: Selection of “convex” patterns on a 2-D grids.



- It is possible to extend such settings to 3-D space, or more complex topologies

- Learning **sparse and structured dictionary elements**:

$$\min_{\substack{\mathbf{A} \in \mathbb{R}^{k \times n} \\ \mathbf{D} \in \mathbb{R}^{p \times k}}} \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{D}\boldsymbol{\alpha}_i\|_2^2 + \lambda \sum_{j=1}^p \Omega(\mathbf{d}_j) \text{ s.t. } \forall i, \|\boldsymbol{\alpha}_i\|_2 \leq 1$$

- Structure of the dictionary elements determined by the choice of \mathcal{G} (and thus Ω)
- Efficient learning procedures through *variational formulation*.

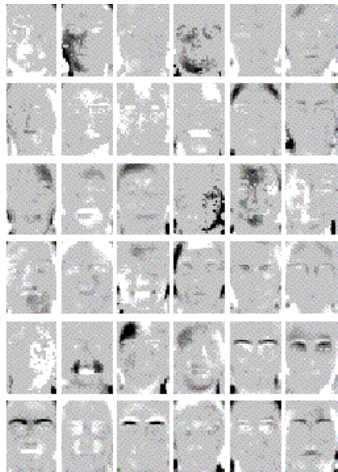
- Reweighted ℓ_2 :
$$\sum_{g \in \mathcal{G}} \|\mathbf{y}_g\|_2 = \min_{\eta_g \geq 0, g \in \mathcal{G}} \frac{1}{2} \sum_{g \in \mathcal{G}} \left\{ \frac{\|\mathbf{y}_g\|_2^2}{\eta_g} + \eta_g \right\}$$

Faces

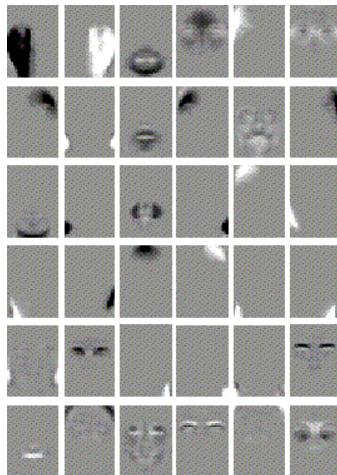


- AR Face database
- 100 individuals (50 W/50 M)
- For each
 - 14 non-occluded
 - 12 occluded
 - lateral illuminations
 - reduced resolution to 38×27 pixels

Decomposition of faces

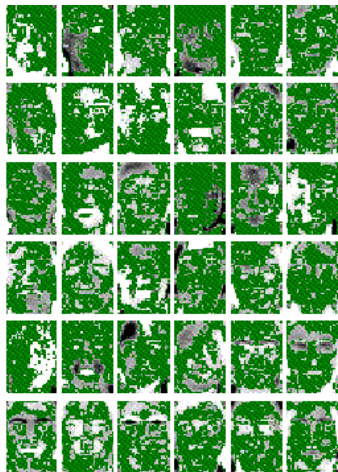


SPCA

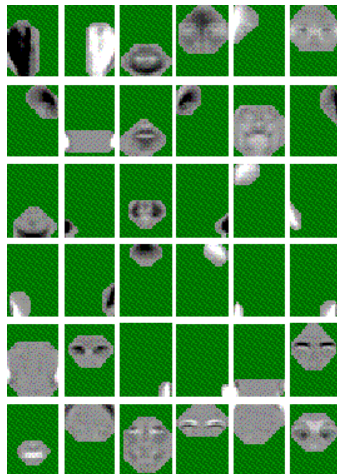


SSPCA

Decomposition of faces II

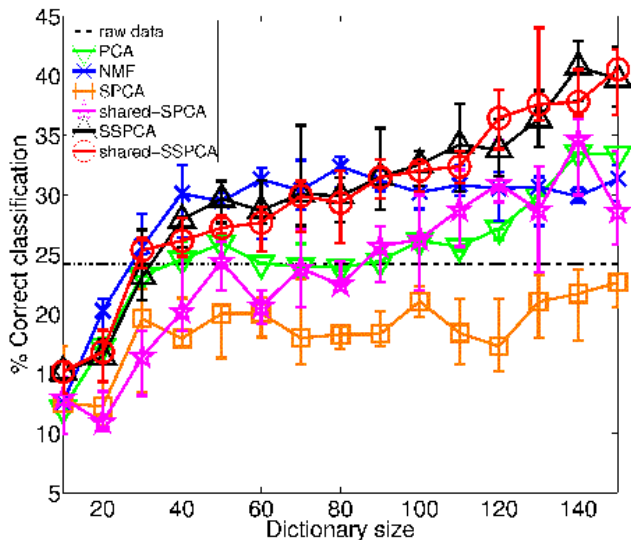


SPCA



SSPCA

k-NN classification based on decompositions



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Hierarchical Topic Models for text corpora

Flat Topic Model

Each document x_j is modeled through word counts:

x_{ij} = nb of occurrences of word i in document j , $x_j^\top \mathbf{1} = n_j$,

θ =topic proportions, D =topic word frequencies

Model x_j as. $x_j \sim \mathcal{M}(D\theta, n_j)$

- Low-rank matrix factorization of word-document matrix
- Multinomial PCA (Buntine and Perttu, 2003)
- Bayesian approach: Latent Dirichlet Allocation (Blei et al., 2003)

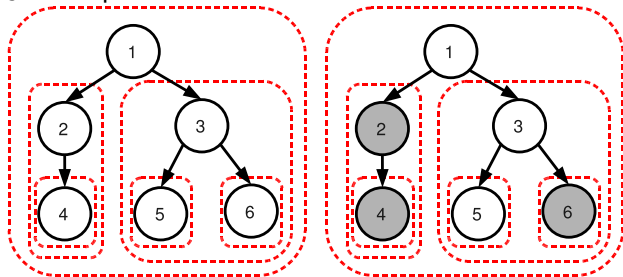
Hierarchical Model: Organise the topics in a tree ?

- Previous approaches: non-parametric Bayesian methods (Hierarchical Chinese Restaurant Process and nested Dirichlet Process): Blei et al. (2004)
- Can we obtain a similar model with **structured** matrix factorization?

Hierarchical Norm

(Jenatton, Mairal, Obozinski and Bach, 2010)

- Structure on codes α (not on dictionary \mathbf{D})
- Hierarchical penalization: $\Omega(\alpha) = \sum_{g \in \mathcal{G}} \|\alpha_g\|_2$ where groups g in \mathcal{G} are equal to **set of descendants** of some nodes in a tree



- Variable selected after its ancestors (Zhao et al., 2009; Bach, 2008)

Hierarchical Dictionary Learning

Efficient Optimization

$$\min_{\substack{\mathbf{A} \in \mathbb{R}^{k \times n} \\ \mathbf{D} \in \mathbb{R}^{p \times k}}} \sum_{i=1}^n \|\mathbf{x}_i - \mathbf{D}\boldsymbol{\alpha}_i\|_2^2 + \lambda \Omega(\boldsymbol{\alpha}_i) \text{ s.t. } \forall j, \|\mathbf{d}_j\|_2 \leq 1.$$

- Proximal methods
- Requires solving $\min_{\boldsymbol{\alpha} \in \mathbb{R}^p} \frac{1}{2} \|\mathbf{y} - \boldsymbol{\alpha}\|_2^2 + \lambda \Omega(\boldsymbol{\alpha})$
- Can we do this for tree-structured norms?

Tree-structured groups

Proposition (Jenatton et al., 2010a)

- If \mathcal{G} is a *tree-structured* set of groups, i.e.,

$$g \cap g' \neq \emptyset \Rightarrow g \subset g' \text{ or } g' \subset g,$$

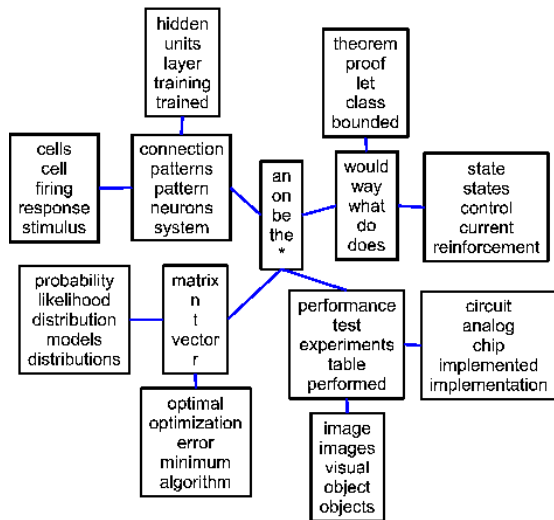
- If the groups are sorted from the leaves to the root,
- If Π_g is
 - the proximal operator $w_g \mapsto \text{Prox}_{\mu \|\cdot\|_q}(w_g)$ on the subspace corresponding to group g and
 - the identity on the orthogonal

Then the proximal operator for Ω is the composition of all operators from the leaves to the root.

$$\text{Prox}_{\mu\Omega} = \Pi_{g_m} \circ \dots \circ \Pi_{g_1}. \quad (1)$$

→ **Tree-structured regularization** : Efficient linear time algorithm

Tree of Topics



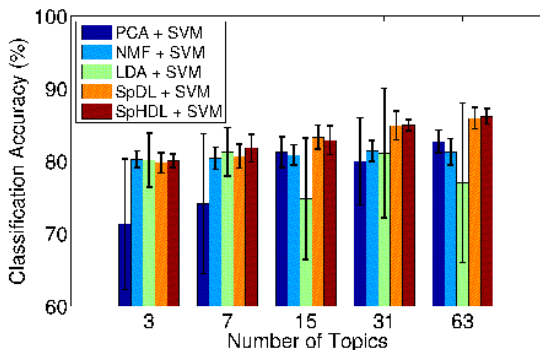
NIPS abstracts

- 1714 documents
- 8274 words

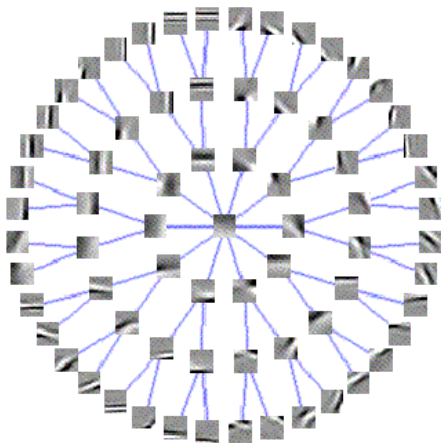
Classification based on topics

Comparison on predicting newsgroup article subjects

- 20 newsgroup articles (1425 documents, 13312 words)



Hierarchical dictionary for image patches



Summary

Sparse linear estimation with ℓ_1 -regularization

- Convex optimization and algorithms
- Theoretical results

Group sparsity

- Block norm
- Multiple Kernel Learning

Matrix Sparsity

- Row sparsity for Multivariate Learning
- Low rank, SPCA and Dictionary Learning

Structured Sparsity

- Overlapping groups and supports stable by union or intersection
- SSPCA and Hierarchical Dictionary Learning

Conclusions

Sparse methods are not limited to regression

High-dimension

- Sparse methods performs well with very many predictors:
- Can algorithms tackle $\log(p) = o(n)$ for $n > 100$?

Performance

- Inducing sparsity does not always improve predictive performance
- Sparsity is a prior
- “Problems are sparse if you look at them the right way”

Capture structure

- Structured sparsity enhances interpretability
- Norm design: make the right norm for your problem

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