



Transformations and Invariance in Global Sensitivity Analysis

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Motivation

- Power transformations, logarithmic transformations, rank transformations are widely used



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Transformations alter the input-factor model-response mapping



Setup

Model output of interest y computed through a complex code and is dependent on k uncertain input factors \mathbf{x} ,

$$g : \mathbf{x} \mapsto y, \quad \Omega_{\mathbf{x}} \subseteq \mathbb{R}^k \rightarrow \Omega_Y \subseteq \mathbb{R},$$

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Local methods

Properties around $\mathbf{x}^0 \in \Omega_{\mathbf{x}}$.

- Not responsive to uncertainty in the input factors
- Only a limited exploration of the input factor space

Global Methods: The Golden Standard

Probabilistic formulation

Input $\mathbf{x} = (x_1, \dots, x_k) \rightsquigarrow \mathbf{X} = (X_1, \dots, X_k)$, RVec on $(\Omega_{\mathbf{X}}, \mathcal{A}, \mathbb{P}_{\mathbf{X}})$

Output $Y = g(\mathbf{X})$ is RV on $(\Omega_Y, \mathcal{B}, \mathbb{P}_Y)$, $\mathbb{P}_Y(B) = \mathbb{P}_{\mathbf{X}}(g^{-1}[B])$

$F_{\mathbf{X}}(\mathbf{x}) = \mathbb{P}_{\mathbf{X}}(\bigcap_{i=1}^k [X_i \leq x_i])$ and $F_Y = \mathbb{P}_Y(Y \leq y)$ CDFs of \mathbf{X} and Y

$f_{\mathbf{X}}(\mathbf{x})$ and $f_Y(y)$ PDFs of \mathbf{X} and Y

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Input distributions are known!



Global Methods II: Categories

- Linear regression (also with rank and other transformations)
- Screening methods [5]
- Variance-based methods [8]
- Expected value of information-based methods [9]
- Distribution-based methods [2]

Variance-based methods have been the most widely studied both from the theoretical and numerical viewpoints: ANOVA decomposition

Variance-Based Method

Main effects and total effects

$$\eta_1^Y(X_i) = \frac{\text{Var}[E[Y|X_i]]}{\text{Var}[Y]}, \quad \eta_T^Y(X_i) = \frac{E[\text{Var}[Y|\mathbf{X}_{\sim i}]]}{\text{Var}[Y]}$$

Here $\mathbf{X}_{\sim i}$: Vector \mathbf{X} without i th component

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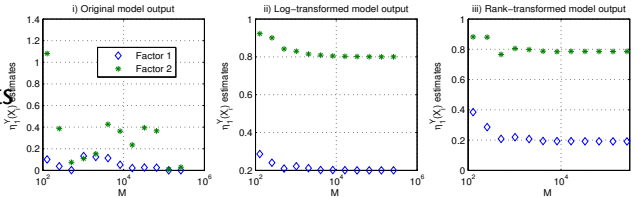
Example

$$Y = \exp(X_1 + 2 \cdot X_2) \quad \text{with} \quad X_1, X_2 \sim \mathcal{N}(0, 1) \quad \text{iid.}$$

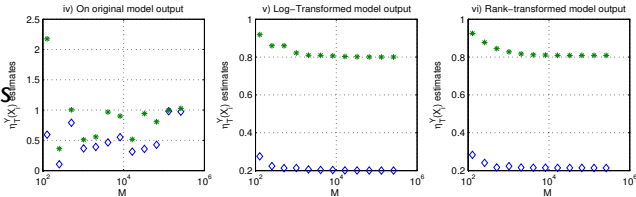
$\eta_1^Y(X_i)$ and $\eta_T^Y(X_i)$ ($i = 1, 2$) computed with [7]'s estimator varying the number of model evaluations M

Convergence Issues, Interpretation Problems

Main effects



Total effects



Raw Data

Log Trafo

Rank Trafo

Issues and Problems II

- No convergence on the raw data: Analytically

$$\eta_1^Y(X_1) = 0.012, \quad \eta_1^Y(X_2) = 0.364,$$

$$\eta_T^Y(X_1) = 0.637, \quad \eta_T^Y(X_2) = 0.988.$$

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Transformations: Model structure changes from multiplicative to

additive: $\hat{\eta}_1^{\log(Y)}(X_i) = \hat{\eta}_T^{\log(Y)}(X_i)$

Calculations do not readily translate back!



A Generalized Framework for GSA

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Sensitivity summarizes two states of knowledge

Before and after knowing that $X_i = x_i$

More on this idea: [3].

A Generalized Framework

Definition (Sensitivity Measure)

Let $d(\cdot, \cdot)$ measure a shift (discrepancy, distance) between the unconditional probability \mathbb{P}_Y and the probability $\mathbb{P}_{Y|X_i=x_i}$ conditional to a realization $X_i = x_i$.

The associated sensitivity measure is defined as an expected shift of the conditional probabilities,

$$\gamma_d^Y(X_i) = \mathbb{E} \left[d(\mathbb{P}_Y, \mathbb{P}_{Y|X_i}) \right] \quad (1)$$

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Approach allows for estimates: Analogously to Correlation Ratio estimation of first order effects



Monotonic Transformations

Consider a monotonic transformation of y ,

$$u : \Omega_Y \rightarrow \Omega_U \subseteq \mathbb{R}, y \mapsto u(y) \text{ and } u \circ g : \Omega_{\mathbf{x}} \rightarrow \mathbb{R}, \mathbf{x} \mapsto u(g(\mathbf{x}))$$

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When \mathbf{x} is uncertain, u becomes a random variable (denoted by U) induced by $\mathbb{P}_{\mathbf{X}}$ through the composition of u with g .

$\gamma^U(X_i)$: sensitivity statistics of X_i with respect to $U = u(Y)$.



Monotonic Invariance

A sensitivity measure is monotonic invariant, if $\gamma^U(X_i) = \gamma^Y(X_i)$ for all suitable models $Y = g(\mathbf{X})$ and transformations $U = u: g(\mathbf{X})$



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Theorem

A sensitivity measure γ_d is monotonic invariant if its shift d is monotonic invariant.

Decision Theory: Sensitivity measure independent under choice of utility function [1]

Invariant shifts

Definition

Let \mathbb{P} and \mathbb{Q} be probability measures on (Ω, \mathcal{A}) . Let $h : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$ be a continuous and non-decreasing function with $h(0) = 0$ and $\sup_t \frac{h(2t)}{h(t)} < \infty$ (Orlicz condition for generalized triangle inequality). Then, we define

$$d(\mathbb{P}, \mathbb{Q}) = \sup_{A \in \mathcal{A}} h(|\mathbb{P}(A) - \mathbb{Q}(A)|) \quad (2)$$

Theorem

Such a $d(\cdot, \cdot)$ is monotonic invariant.

Invariant shifts: PDF based

Example

For $h(t) = t$ and f and g PDFs of \mathbb{P} and \mathbb{Q} : From (2)

$$\begin{aligned}\sup_{A \in \mathcal{A}} |\mathbb{P}(A) - \mathbb{Q}(A)| &= \sup_{A \in \mathcal{A}} \left| \int_A (f(y) - g(y)) dy \right| \\ &= \frac{1}{2} \int_{\mathcal{Y}} |f(y) - g(y)| dy\end{aligned}$$

(Consider $A = \{y : f(y) \geq g(y)\}$)

Hence: Borgonovo importance measure is transformation invariant,

$$\delta^Y(X_i) = \frac{1}{2} \int_{\mathcal{X}_i} f_{X_i}(x_i) \int_{\mathcal{Y}} |f_Y(y) - f_{Y|X_i=x_i}(y)| dy dx_i$$

Monotonic invariant shifts: CDF based

Consider only half-rays $A(y) = \{z \leq y\}$ in (2):

$$d(\mathbb{P}, \mathbb{Q}) = \sup_{y \in \mathbb{R}} h(|F(y) - G(y)|) \quad (3)$$

where $F(y) = \mathbb{P}(z \leq y)$ and $G(y) = \mathbb{Q}(z \leq y)$ are the CDFs.

Transformation invariance: Birnbaum-Orlicz family of metrics

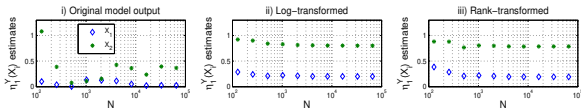
$h(t) = t$: Kolmogorov-Smirnov distance,

$$\beta^Y(X_i) = \int_{\mathcal{X}} f_{X_i}(x_i) \sup_{y \in \mathcal{Y}} |F_Y(y) - F_{Y|X_i=x_i}(y)| dx_i$$

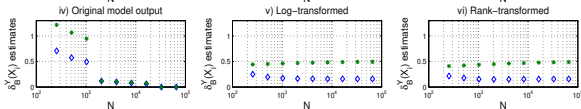
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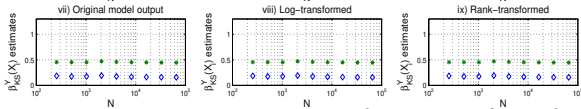
Main effects



Borgonovo



Kolmogorov-Smirnov



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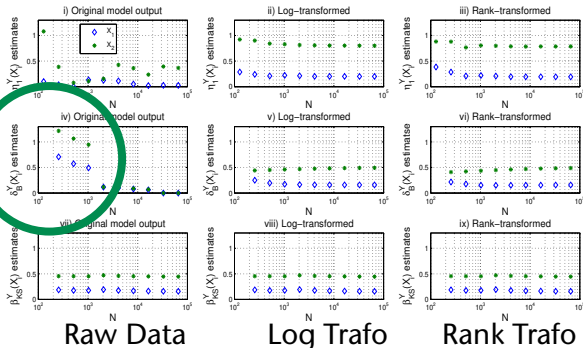
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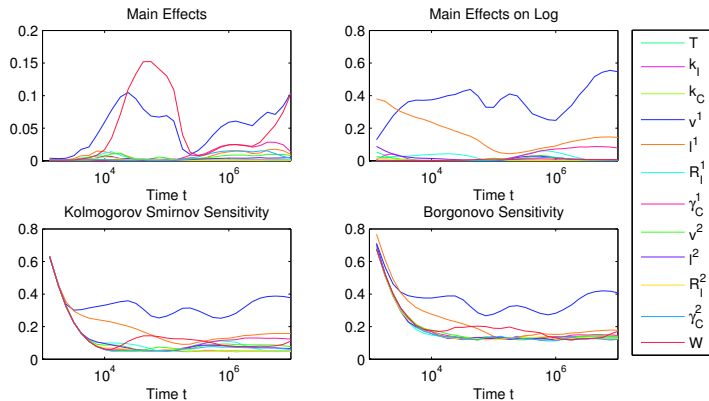
Kolmogorov-Smirnov



Kernel density estimator fails!

Level E Geosphere Transport Model

Sensitivity of total dose over time: QMC sample, size 8192:





Conclusions

- Uncertainty is coded in the probability in general, not only in the variance: Need for stronger sensitivity measures



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- Uncertainty is coded in the probability in general, not only in the variance: Need for stronger sensitivity measures
- General Framework: Estimators from given data are available
- Transformation invariance: no change of interpretation
- Suitable domain for estimation: gain in numerical precision



Thank you!

Any questions?

More details: [4]

Estimation from given data: [6]

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