

# Global Sensitivity Analysis for the calibration of a fully-distributed hydrological model

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## 1) Motivation

- LISFLOOD [1] is a fully-distributed hydrological model used for flood forecasting at Pan-European scale within the European Flood Awareness System (EFAS, [www.efas.eu](http://www.efas.eu)), and for Climate Change studies in Europe.
- Model parameters are estimated through calibration [2]-[3], in order to constrain simulated discharges to the corresponding observed values.
- So far, **nine (9) parameters** of the model have been selected as sensitive, mostly through expert knowledge accumulated over years in the research group. However, for highly non-linear models that approach may not result in a proper identification of the most sensitive parameters for model calibration.

## 2) Aims

- To use **Global Sensitivity Analysis (GSA)** as a formal method to identify relevant parameters that contribute significantly to model performance.
- To elucidate if the model performance obtained by calibrating sensitive parameters identified by GSA is higher than the model performance obtained by calibrating parameters identified by prior expert knowledge.

## 3) Case Studies

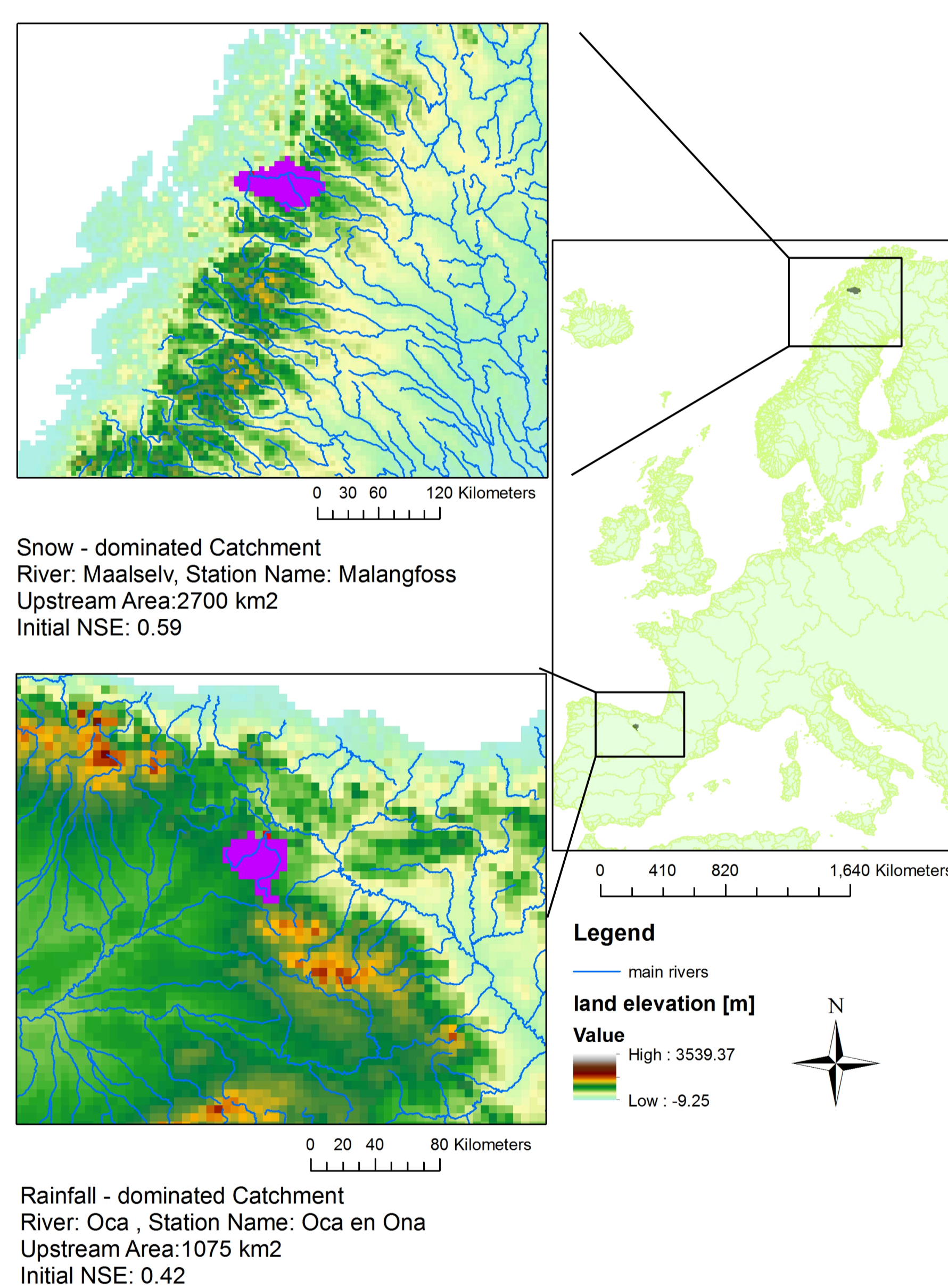


Fig 1. Location of the two case studies used in this work. In the snow-dominated catchment (Sweden) snow-related model parameters are expected to be found the most sensitive. In the rainfall-dominated catchment, model parameters related to infiltration and flow routing are expected to be found the most sensitive.

## 4) Hydrological model

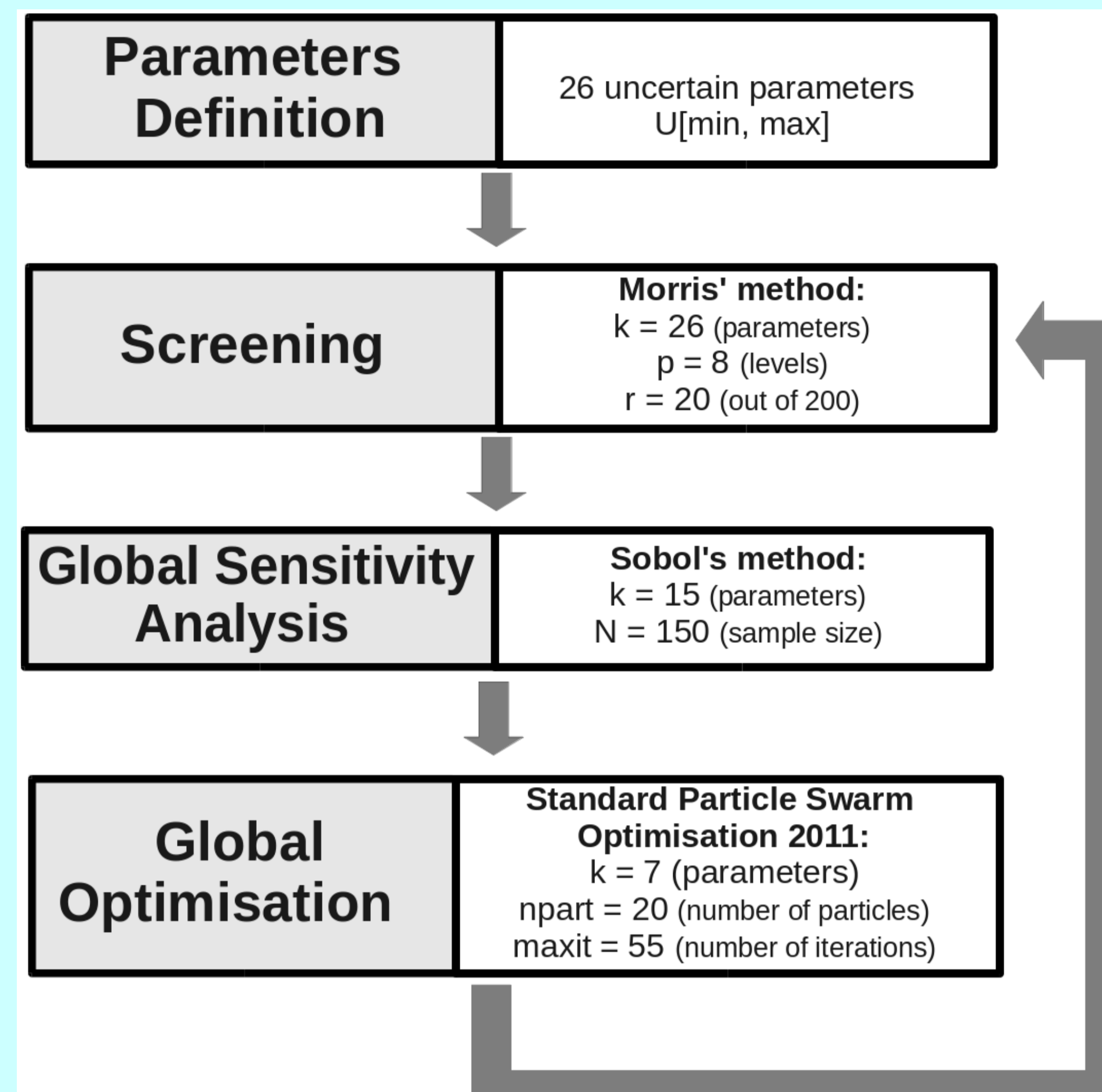
- The LISFLOOD model [1] has many parameters that may be calibrated.
- Based on prior expert knowledge on the research group, 26 parameters have been selected for sensitivity analysis. Remaining parameters were mostly GIS-related, so they were assumed to have already their best possible value.
- A single model run takes ~ 1 or 2 minutes → makes computationally unfeasible to run a large number of model runs.
- Model outputs (daily time series) were transformed into a real value by using the Nash-Sutcliffe efficiency as a measure of model performance:

$$NSE = 1 - \frac{\sum_{i=1}^N (O_i - M_i)^2}{\sum_{i=1}^N (O_i - \bar{O})^2}$$

$O_i$ : observed values, [m<sup>3</sup>/s]  
 $M_i$ : simulated values, [m<sup>3</sup>/s]

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## 5) Methodology



### 5.a) Screening (Morris' GSA)

- The screening method of Morris [8] aims to identify sensitivity parameters with a small number of sample points (model runs), i.e., with a **low computational cost**. The recommended number of simulations is  $C = r(k + 1)$ , where  $k$  is the number of parameters (input factors) and  $r$  is a user-defined number of elementary effects (usually  $r=10$ ).
- The method results in two sensitivity measures for each parameter:
  - $\mu^*$ : a high value indicates a parameter with an important overall effect on model output.
  - $\sigma$ : a high value indicates that either the parameter is interacting with other parameters or the parameter has non-linear effects on model output.

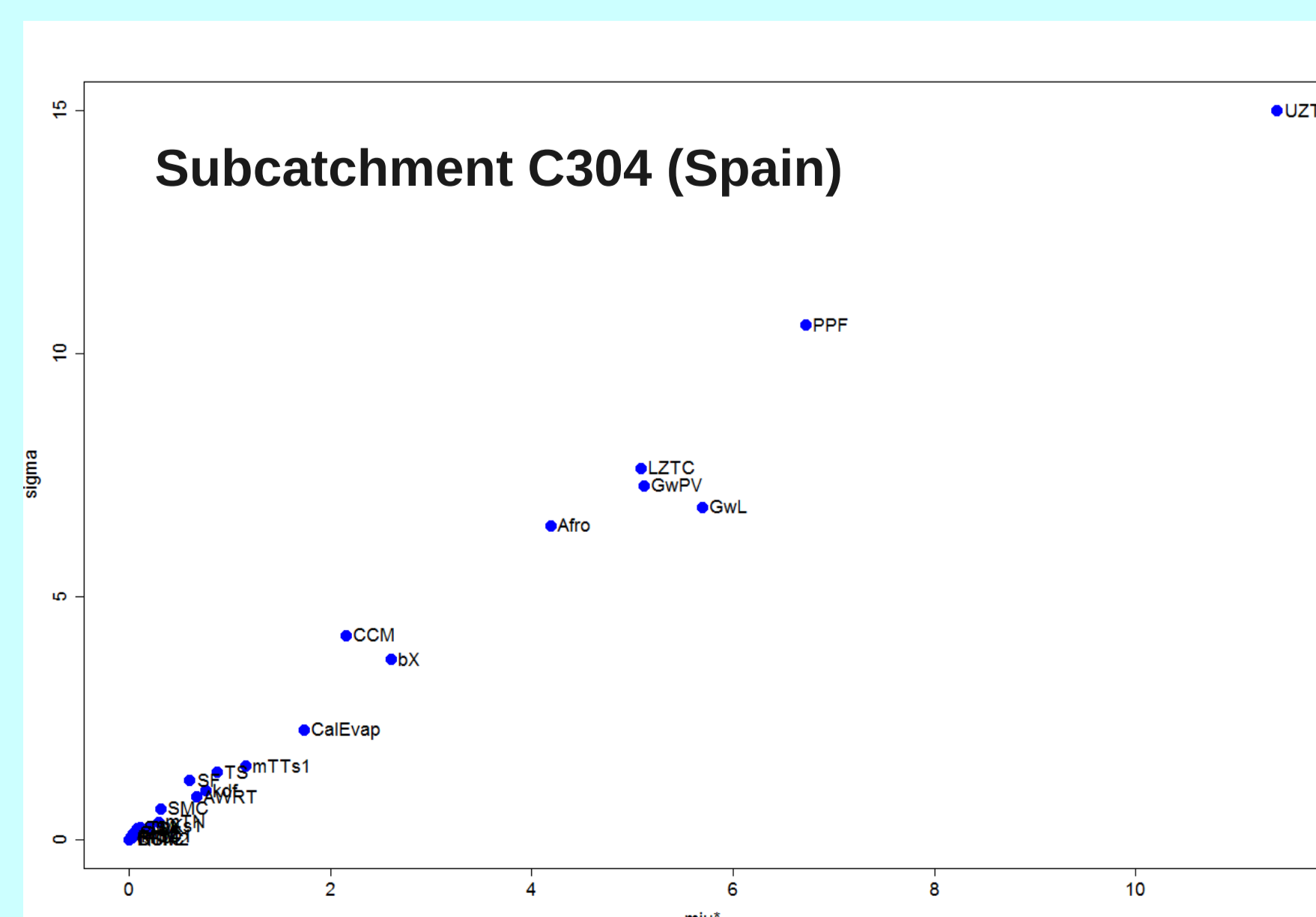
### 5.b) GSA (Sobol's method)

- The variance-based method of Sobol [9] quantifies the amount of variance that each parameter contributes with on the unconditional variance of the model output.
- The total cost of the Sobol analysis proposed in [10] is:  $C = N(k + 2)$ , where  $k$  is the number of parameters (input factors) and  $N$  is a user-defined large number (usually  $N \geq 500$ , if computationally feasible).
- The method results in two sensitivity measures:
  - $S_i$ : fraction of the total model variance explained by each parameter.  $S_i = V_i/V$ , where:  $V_i$  is the variance due to parameter  $i$ , and  $V$  is the total variance.
  - $St_i$ : total effect of parameter  $i$  (including interactions).
- The difference  $St_i - S_i$  is a measure of interactions of parameter  $i$ .

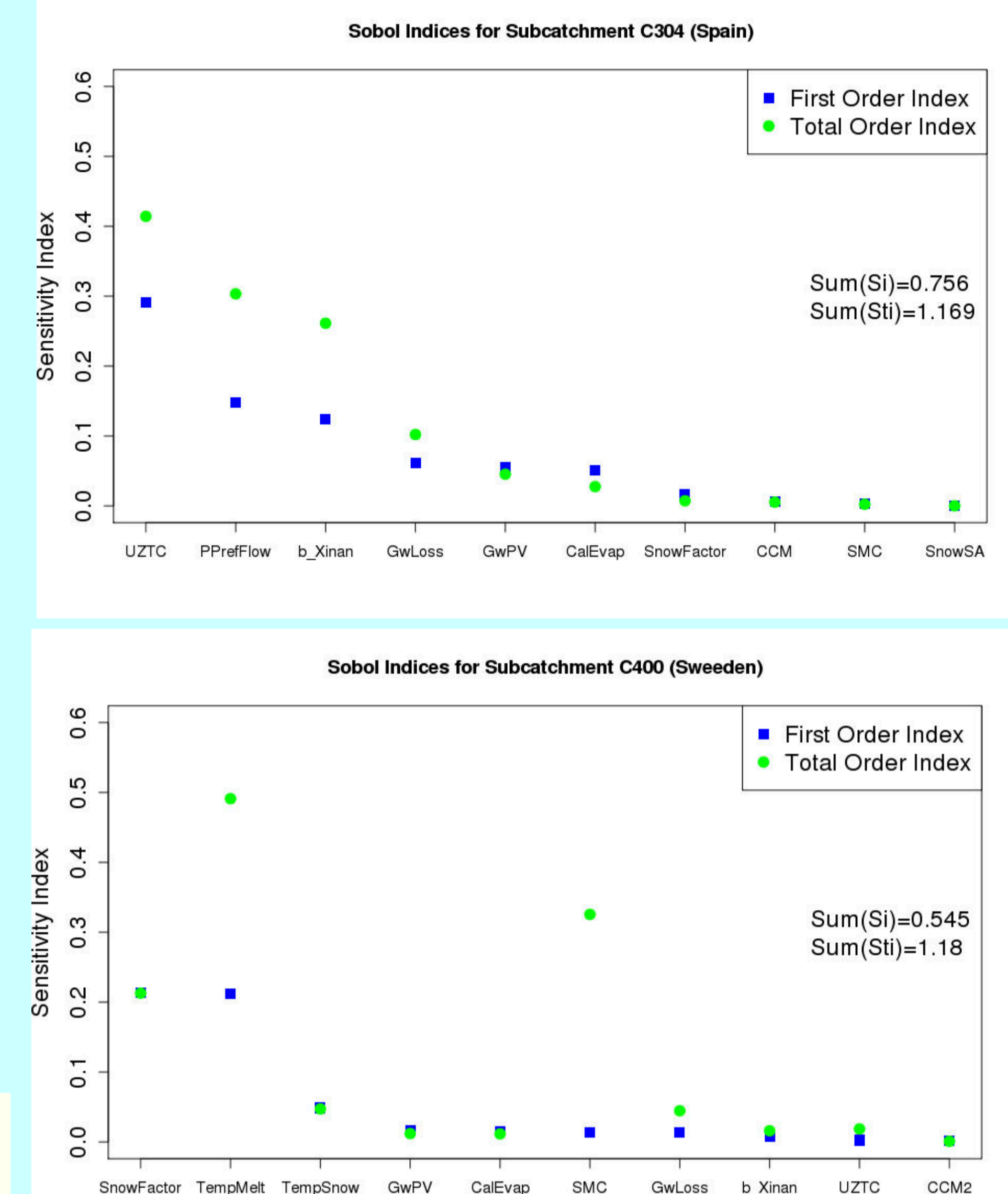
### 5.c) Global Optimisation (SPSO-2011)

- The Standard Particle Swarm Optimisation 2011 (SPSO-2011) [2-3] was used as global optimisation algorithm for calibrating the LISFLOOD model. SPSO is a recent population-based stochastic evolutionary algorithm inspired by the social behavior of a bird flock looking for food [4]. It has been benchmarked against state-of-the-art global optimisation algorithms [3], where proved to be both efficient and effective. More details: [2-4].
- The LISFLOOD model was calibrated in each catchment using a daily time step, during the period 1995-2003, using the first year as a warming up period.

### 6.a) Results (Screening with Morris' method)



### 6.b) Results (GSA with Sobol's method)



## 8) Conclusions

- Sensitive parameters identified by GSA corresponded to the **dominant hydrological processes** in each catchment → LISFLOOD works as expected by the modellers.
- Qualitative ranking provided by the screening method of Morris were in general **agreement** with those provided by the more computationally-intensive Sobol's method.
- In the rainfall-dominated catchment (C304), the 4 most sensitive parameters were related to **groundwater** and **infiltration** processes. Those 4 sensitive parameters presented **large interactions** among themselves.
- Sensitive parameters for C304 were a **subset** of the original set defined by prior expert knowledge. New calibration results were slightly **worse** (NSE=0.45) than those of the original calibration (NSE=0.47).
- In the snow-dominated catchment (C400), the 3 most sensitive parameters were related to **snowfall** and **snowmelt** processes. Those 3 sensitive parameters presented very small interactions among themselves.
- Sensitive parameters for C400 were **different** from those identified by prior expert knowledge. New calibration results were much **better** (NSE=0.72) than those of the original calibration (NSE=0.59).
- Initial uncertainty ranges defined for threshold-like parameters proved to have a large influence in the identification of sensitive parameters (both Morris' and Sobol's method) (not shown here).
- Sensitivity indices may change when a different goodness-of-fit measure is used for assessing model's performance.

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