

# Multi-level Monte Carlo Finite Volume methods for stochastic systems of hyperbolic conservation laws

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# Outline

## Conservation laws

- Examples

- Stochastic system

## Multilevel Monte Carlo FVM

- Error bounds

- Choosing samples

## Numerical experiments

- MHD

- Convergence

- Euler 3D

## Parallelization - ALSVID-UQ

- Adaptive load balancing

## Numerical experiments with many sources of uncertainty

- Shallow water equations

- Wave equation 2D + 3D

## Conclusions

Hyperbolic nonlinear  
conservation laws

# (Non)linear hyperbolic conservation laws

Conservation of the physical quantities (mass, momentum, energy):

$$\begin{cases} \partial_t \mathbf{U}(\mathbf{x}, t) + \operatorname{div} \mathbf{F}(\mathbf{U}, \mathbf{x}) = 0, \\ \mathbf{U}(\mathbf{x}, 0) = \mathbf{U}_0(\mathbf{x}), \end{cases} \quad \mathbf{x} \in \mathbb{R}^d, t > 0.$$

- ▶ **Hyperbolicity**: finite speed of propagation
- ▶ **Nonlinearity**: smooth initial data leads to solutions with **shocks**
- ▶ **Weak** solutions need to be considered (+ entropy conditions for uniqueness)
- ▶ **No explicit solutions** - numerical schemes

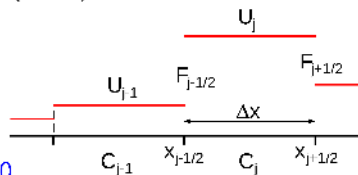
Numerical solution using **Finite Volume Method** (FVM):

- ▶ **Cell averages**:

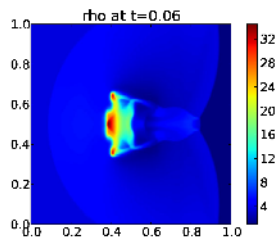
$$\mathbf{U}_j(t) \approx \frac{1}{|C_j|} \int_{C_j} \mathbf{U}(x, t) dx$$

- ▶ **ODE**:  $\partial_t \mathbf{U}_j(t) + \frac{1}{\Delta x} (\mathbf{F}_{j+\frac{1}{2}} - \mathbf{F}_{j-\frac{1}{2}}) = 0$

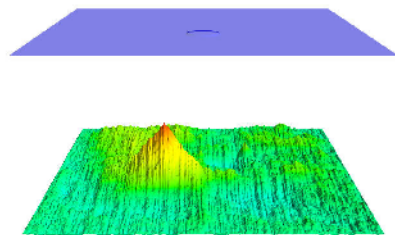
- ▶ **Approximate Riemann fluxes**: HLL, Godunov (Roe)
- ▶ **Explicit time stepping**: FE, SSP-RK2 with CFL:  $\Delta t < \Delta x / (\text{max wave speed})$



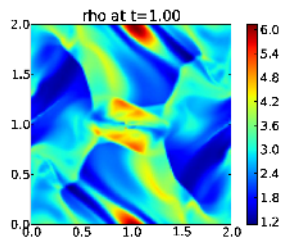
# Examples of (non)linear hyperbolic conservation laws



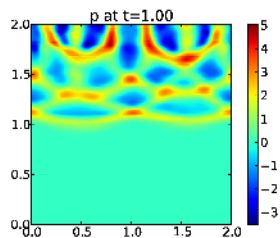
**Euler** cloud-shock interaction



**Shallow water** with varying topography



**MHD** Orszag-Tang vortex



**Wave** propagation in porous medium

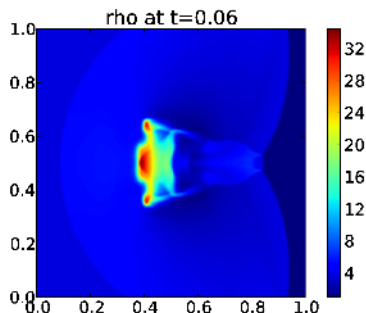
# Compressible Euler equations of gas dynamics

**Question:** What is the time evolution of density/pressure/velocity fields in compressible fluids?

$$\begin{cases} \rho_t + \operatorname{div}(\rho \mathbf{u}) = 0, \\ (\rho \mathbf{u})_t + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + p \mathbf{I}) = 0, \\ E_t + \operatorname{div}((E + p)\mathbf{u}) = 0. \end{cases}$$

$$E = \frac{p}{\gamma - 1} + \frac{\rho \mathbf{u}^2}{2}.$$

- ▶ design of aircraft profiles
- ▶ gas turbines
- ▶ internal combustion engines
- ▶ ...



Density in cloud-shock interaction

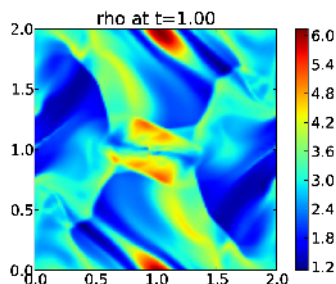
- ▶ **uncertain** cloud geometry/density
- ▶ **uncertain** shock size/location
- ▶ **uncertain** gas constant  $\gamma$

# Magnetohydrodynamics equations for plasma physics

Describes magnetic and density/pressure/velocity fields interaction in electrically conducting fluid.

$$\left\{ \begin{array}{l} \rho_t + \operatorname{div}(\rho \mathbf{u}) = 0, \\ (\rho \mathbf{u})_t + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + (p + \frac{1}{2} |\mathbf{B}|^2) \mathbf{I} - \mathbf{B} \otimes \mathbf{B}) = -\mathbf{B} \operatorname{div} \mathbf{B}, \\ \mathbf{B}_t + \operatorname{div}(\mathbf{u} \otimes \mathbf{B} - \mathbf{B} \otimes \mathbf{u}) = -\mathbf{u} \operatorname{div} \mathbf{B}, \\ E_t + \operatorname{div}((E + p + \frac{1}{2} |\mathbf{B}|^2) \mathbf{u} - (\mathbf{u} \cdot \mathbf{B}) \mathbf{B}) = -(\mathbf{u} \cdot \mathbf{B}) \operatorname{div} \mathbf{B}. \end{array} \right.$$

- ▶ plasmas (e.g. in the sun)
- ▶ liquid metals
- ▶ various electrolytes
- ▶ HLL 3-wave and 5-wave solvers
  - ▶ not strictly hyperbolic
  - ▶ non-convex fluxes
  - ▶ **div** constraint
- ▶ **Godunov-Powell source** term
- ▶ **positivity preserving** (W)ENO



Density in Orszag-Tang vortex

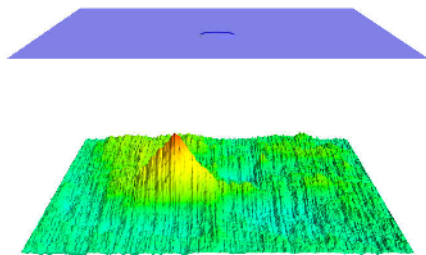
# Shallow water equation with varying bottom topography

**Question:** what is the time evolution of a tsunami wave caused by an earthquake?

$$\begin{cases} h_t + \operatorname{div}(hu) = 0 \\ (hu)_t + \operatorname{div}(hu \otimes \mathbf{u}) = -\nabla(ghb + \frac{1}{2}gh^2) \end{cases}$$

Important for:

- ▶ avalanche modeling
- ▶ debris slides
- ▶ atmospheric flows of weather prediction
- ▶ risk assessment of region flooding (due to tsunami or dam break)
- ▶ ...



Water level above bottom topography

- ▶ **uncertain** initial perturbation
- ▶ **uncertain** bottom topography
- ▶ ...



# Acoustic wave equation in heterogeneous medium

Question: What is the time evolution of the acoustic wave propagating through random medium?

$$p_{tt}(\mathbf{x}, t) - \nabla \cdot (c(\mathbf{x})\nabla p) = f(\mathbf{x})$$

$$\Downarrow \mathbf{U} = [p, \mathbf{u}]^T$$

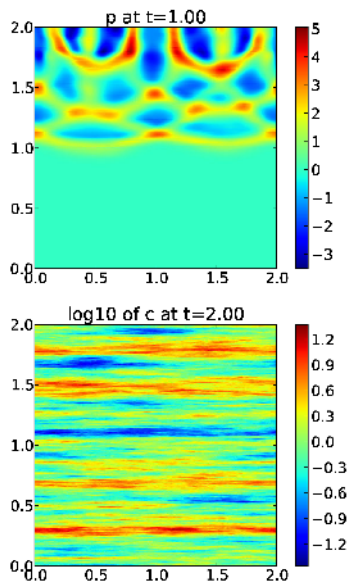
$$\begin{cases} p_t(\mathbf{x}, t) - \nabla \cdot (c(\mathbf{x})\mathbf{u}) = tf(\mathbf{x}), \\ \mathbf{u}_t(\mathbf{x}, t) - \nabla p(\mathbf{x}, t) = 0. \end{cases}$$

- ▶ sound/elastic wave propagation through geological layers
- ▶ structural mechanics



- ▶  $c(\mathbf{x})$  is often **uncertain**, e.g. **log-normal** with covariance  
$$\text{Cov}(\log c(\mathbf{x}), \log c(\mathbf{y})) = \sigma^2 e^{-\|\mathbf{x} - \mathbf{y}\|/\eta}$$
with **anisotropic** correlation lengths

$$\eta_1, \dots, \eta_2.$$



# Stochastic (non)linear systems of balance laws

$\mathbf{U}_0(\mathbf{x})$ ,  $\mathbf{c}(\mathbf{x})$ ,  $\mathbf{F}(\cdot, \cdot)$ ,  $\mathbf{S}(\mathbf{x}, t, \cdot)$  are **uncertain**  $\rightarrow$  solution  $\mathbf{U}(\mathbf{x}, t)$  is also **uncertain**:

$$\begin{cases} \frac{\partial}{\partial t} \mathbf{U}(\mathbf{x}, t, \omega) + \operatorname{div} \mathbf{F}(\mathbf{c}(\mathbf{x}, \omega), \mathbf{U}, \omega) = \mathbf{S}(\mathbf{x}, t, \mathbf{U}, \omega), \\ \mathbf{U}(\mathbf{x}, 0, \omega) = \mathbf{U}_0(\mathbf{x}, \omega), \end{cases} \quad \forall \omega \in \Omega, \quad (\Omega, \mathcal{F}, \mathbb{P}).$$

## Well-posedness

Determine required statistical regularity of **uncertain** input  $\mathbf{l} = \{\mathbf{U}_0, \mathbf{c}, \mathbf{F}, \mathbf{S}\}$  such that **random entropy solution**  $\mathbf{U}(\mathbf{x}, t, \omega)$  has **finite mean and variance**.

## Goals

- ▶ Theory for the existence of  $\mathbf{U}(\mathbf{x}, t, \omega)$  and its statistical moments
- ▶ Numerical methods for approximation of statistical moments (e.g.  $\mathbb{E}[\mathbf{U}]$ )
- ▶ Massively parallel implementation using efficient load balancing

# Theory and numerical results on MLMC-FVM

for hyperbolic conservation laws

	Scalar stochastic PDE	System of stochastic PDE
Linear	<ul style="list-style-type: none"><li>▶ Linear advection</li></ul> Theory + numerical results <sup>1</sup>	<ul style="list-style-type: none"><li>▶ Acoustic wave</li><li>▶ Linear elasticity</li></ul> Theory + numerical results <sup>2</sup>
Nonlinear	<ul style="list-style-type: none"><li>▶ Burgers'</li><li>▶ Buckley-Leverett</li></ul> Theory + numerical results <sup>1</sup>	<ul style="list-style-type: none"><li>▶ Euler</li><li>▶ Magneto-hydrodynamics</li><li>▶ Shallow water <sup>3</sup></li></ul> Theory <sup>4</sup> , Numerical results <sup>5 6</sup>

<sup>1</sup>Mishra, Schwab (Math. Comp., 2012)

<sup>2</sup>Šukys, Mishra, Schwab (MCQMC 2012, Springer Proc. Math. Stat., 2013)

<sup>3</sup>Mishra, Schwab, Šukys (SIAM J. Sci. Comput., 2012)

<sup>4</sup>Fjordholm, Käppeli, Mishra, Tadmor. *Entropy Measure Valued Solutions* (arXiv, 2014)

<sup>5</sup>Mishra, Schwab, Šukys (J. Comput. Phys., 2012)

<sup>6</sup>Mishra, Schwab, Šukys (Springer LNCSE, 2013)

Short review of  
MC-FVM and MLMC-FVM

# Monte Carlo FVM algorithm (MC-FVM)

We are interested in  $\mathbb{E}[\mathbf{U}(\mathbf{x}, t)]$  and  $\mathbb{V}[\mathbf{U}(\mathbf{x}, t)]$  with  $(\mathbf{x}, t) \in \mathbf{D} \times \mathbf{T} \subset \mathbb{R}^d \times \mathbb{R}_+$ .

1. **Draw**  $M$  **i.i.d.** samples of random quantities (input data)

$$\mathbf{I}^i = \{\mathbf{U}_0^i(\cdot), \mathbf{c}^i(\cdot), \mathbf{F}^i(\cdot), \mathbf{S}^i(\cdot)\}, \quad i = 1, \dots, M.$$

2. For each draw, **solve** for approximate (FVM with  $\Delta x$ ) **entropy solutions**

$$\mathbf{I}^i \longrightarrow \mathbf{U}_{\Delta x}^i(\mathbf{x}, t^n) = (\mathbf{U}_j^n)^i, \quad \forall \mathbf{x} \in \mathcal{C}_j.$$

3. **Estimate statistics** of  $\mathbb{E}[\mathbf{U}]$  with

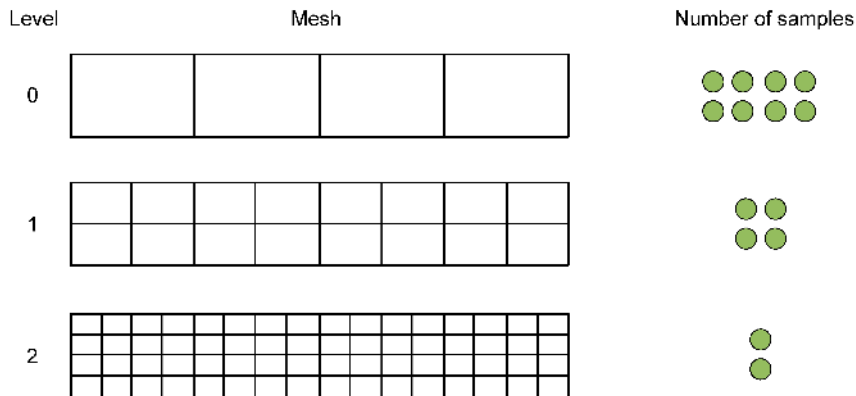
$$\mathbb{E}[\mathbf{U}] \approx E_M[\mathbf{U}_{\Delta x}] := \frac{1}{M} \sum_{i=1}^M \mathbf{U}_{\Delta x}^i.$$

**Drawback:** **slow** convergence + **costly** FVM  $\longrightarrow$  **extremely expensive** for  $d > 1$ .

# Multi-Level Monte Carlo<sup>7</sup> FVM method (MLMC-FVM)

- ▶ **Nested levels** of resolution

$$\Delta x_\ell = \mathcal{O}(2^{-\ell} \Delta x_0), \quad \ell \in \mathbb{N}_0.$$



<sup>7</sup>Introduced by Heinrich (1999); Giles (2008); Barth, Schwab, Zollinger (2011).

# Multi-Level Monte Carlo FVM method (MLMC-FVM)

1. Draw  $M_\ell$  i.i.d. samples of random quantities (input data) for each level  $\ell$

$$\mathbf{I}_\ell^i = \{\mathbf{U}_{0,\ell}^i(\cdot), \mathbf{c}_\ell^i(\cdot), \mathbf{F}_\ell^i(\cdot), \mathbf{S}_\ell^i(\cdot)\}, \quad i = 1, \dots, M.$$

2. For each draw  $i$  and level  $\ell$ , solve for approximate (FVM with  $\Delta x_\ell$ ) solutions

$$\mathbf{I}_\ell^i \longrightarrow \mathbf{U}_{\Delta x_\ell}^i.$$

3. Estimate statistics:

$$\mathbb{E}[\mathbf{U}] \approx \mathbb{E}[\mathbf{U}_{\Delta x_L}] = \mathbb{E}[\mathbf{U}_{\Delta x_0}] + \sum_{\ell=1}^L \mathbb{E}[\mathbf{U}_{\Delta x_\ell} - \mathbf{U}_{\Delta x_{\ell-1}}].$$

Estimate each term in the telescoping sum using MC-FVM

$$E^L[\mathbf{U}_{\Delta x_L}] = E_{M_0}[\mathbf{U}_{\Delta x_0}] + \sum_{\ell=1}^L E_{M_\ell}[\underbrace{\mathbf{U}_{\Delta x_\ell} - \mathbf{U}_{\Delta x_{\ell-1}}}_{\text{variance} \rightarrow 0 \text{ as } \ell \rightarrow \infty}].$$

# Error vs. Work for Multi-Level Monte Carlo FVM

## Theorem <sup>8</sup>

- ▶ **scalar** conservation laws:  $\mathbf{I} = \{\mathbf{U}_0\}$ ,  $E = L^1 \cap L^\infty(\mathbf{D})$ ,  $H = TV(\mathbf{D})$ .  
 $\mathbf{U}_0 \in L^2 \cap L^\infty(\Omega, E \cap H)$ ,  $\mathbf{F} \in L^\infty(\Omega, \mathbf{C}^1(-\|\mathbf{U}_0\|_\infty, \|\mathbf{U}_0\|_\infty))$ .
- ▶ **linear hyperbolic systems**:  $\mathbf{I} = \{K, \mathbf{U}_0, \mathbf{S}\}$ ,  $E = \mathbf{L}^2 \cap \mathbf{L}^\infty(\mathbf{D})$ ,  $H = \mathbf{H}^s(\mathbf{D})$ .  
 $\mathbf{U}_0, \mathbf{S} \in L^2(\Omega, E \cap H)$ ,  $\mathbf{A}_r \in L^0(\Omega, \mathbf{C}^1(\mathbf{D})^{m \times m})$ :  $K \in L^2(\Omega)$ .

Denoting FVM convergence rate by  $s$ ,

$$\|\mathbb{E}[\mathbf{U}] - E^L[\mathbf{U}_{\Delta x_L}]\|_{L^2(\Omega, E)} \leq C_1 \Delta x_L^s + C_2 \sum_{\ell=1}^L M_\ell^{-\frac{1}{2}} \Delta x_\ell^s + C_3 M_0^{-\frac{1}{2}}.$$

Constants  $C_{1,2,3}$  depend on  $\mathbf{D} \times \mathbf{T}$ ,  $s$ ,  $\mathbf{U}_0, \mathbf{A}_r, \mathbf{F}, \mathbf{S}$ , but not on  $L, \Delta x_\ell, M_\ell$ .

<sup>8</sup>Mishra, Schwab (Math. Comp., 2012); Šukys, Mishra, Schwab (MCQMC 2012 Proc., 2013)



## Choosing number of samples

Asymptotic MLMC-FVM error (denoting  $\|\mathbf{I}\|_V = K(\|\mathbf{U}_0\|_V + T\|\mathbf{S}\|_V)$ ):

$$C_1 \Delta x_L^s \|\mathbf{I}\|_{L^1(\Omega, H)} + C_2 \sum_{\ell=1}^L M_\ell^{-\frac{1}{2}} \Delta x_\ell^s \|\mathbf{I}\|_{L^2(\Omega, H)} + C_3 M_0^{-\frac{1}{2}} \|\mathbf{I}\|_{L^2(\Omega, E)}$$

Equilibrate MC and FVM errors:

$$M_\ell = M_L \cdot 2^{2(L-\ell)s}$$

Optimize<sup>9</sup> MC and FVM errors for  $M_\ell$ :

$$M_\ell = M_L \cdot 2^{\frac{2}{3}(L-\ell)(s+d+1)}$$

Error  $\lesssim \mathbb{E}[\text{Work}]^{-s/(d+1)} \log(\mathbb{E}[\text{Work}])$

Error  $\lesssim \mathbb{E}[\text{Work}]^{-s/(d+1)}$

**!** Same complexity as a single FVM solve. Constants differ by  $\sqrt{M_L}$ .

To find  $M_L$ , equilibrate first error term with error terms in the sum:

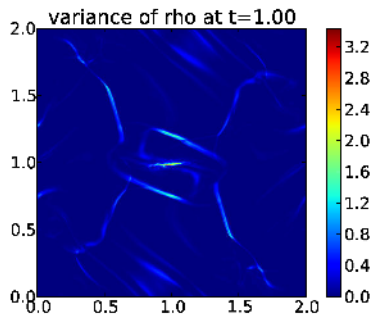
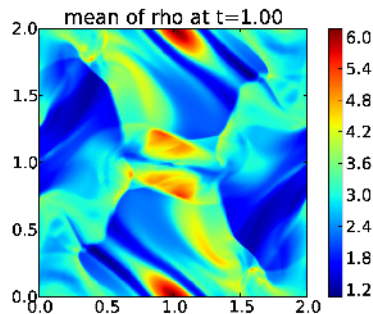
$$M_L = \left( \frac{C_2 \|\mathbf{I}\|_{L^2(\Omega, H)}}{C_1 \|\mathbf{I}\|_{L^1(\Omega, E)}} \right)^2 \approx \left( \frac{C_2}{C_1} \right)^2 = \begin{cases} 16 & \text{scalar } (C_1 = 1, C_2 = 4) \\ 4 & \text{linear systems } (C_1 = 1, C_2 = 2) \end{cases}$$

<sup>9</sup>Giles (Oper. Res., 2008); Pauli and Arbenz (2014)

Numerical experiments  
and  
error convergence

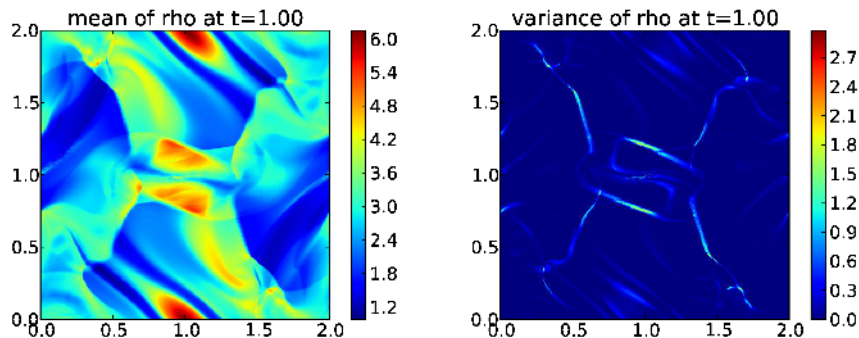
# MHD: MLMC-FVM for Orszag-Tang vortex

with uncertain initial magnetic field (2 sources of uncertainty)



# MHD: MLMC-FVM for Orszag-Tang vortex

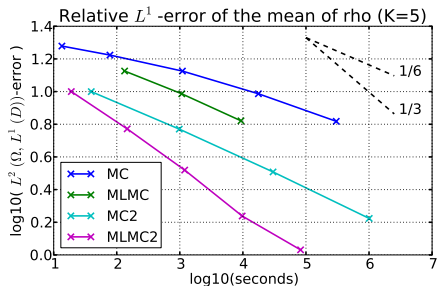
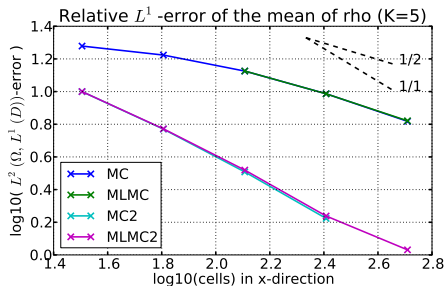
with uncertain initial magnetic field (2 sources of uncertainty)



$L$	$M_L$	grid size	CFL	cores	runtime	efficiency
7	4	2048x2048	0.475	128	5:02:14	98.4%

# MHD: Orszag-Tang vortex - convergence for mean

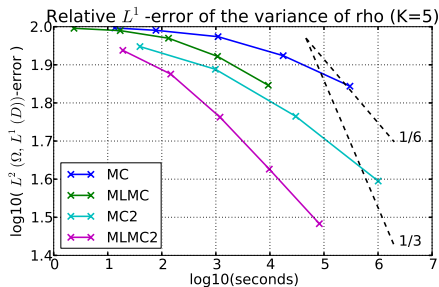
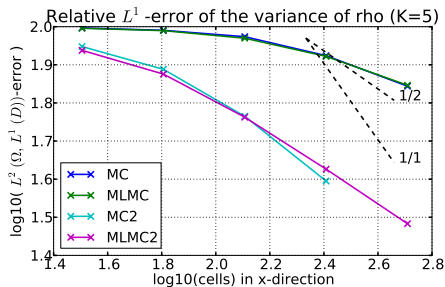
with 2 sources of uncertainty



Convergence rates coincide with the rigorous theory for **SCL**!

# MHD: Orszag-Tang vortex - convergence for variance

with 2 sources of uncertainty

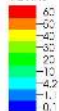


# Euler: FVM for cloud shock - one sample

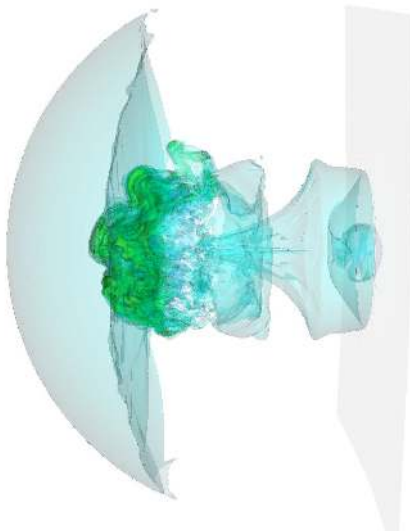
with uncertain shock location/magnitude and geometry of the cloud

DB: rho at time 0.06

Contour  
Var: rho



Max: 64.23  
Min: 0.4322



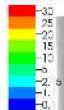
$L$	0
$M_L$	1
cells	1 Billion
CFL	0.475
cores	4096
runtime	4:29:44
eff.	95.7%

# Euler: MLMC-FVM for cloud shock - mean and variance

with uncertain shock location/magnitude and geometry of the cloud

DB: mean of rho at time 0

Contour  
Var: mean of rho

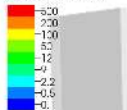


Max: 14.17  
Min: 0.020



DB: variance of rho at time 0

Contour  
Var: variance of rho



Max: 79.75  
Min: 0.020



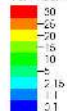


# Euler: MLMC-FVM for cloud shock - mean and variance

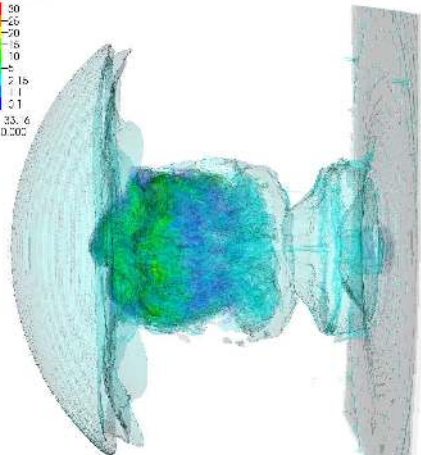
with uncertain shock location/magnitude and geometry of the cloud

DB: mean of rho at time 0.06

Contour  
Var. mean of rho

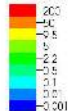


Max: 33.6  
Min: 0.002

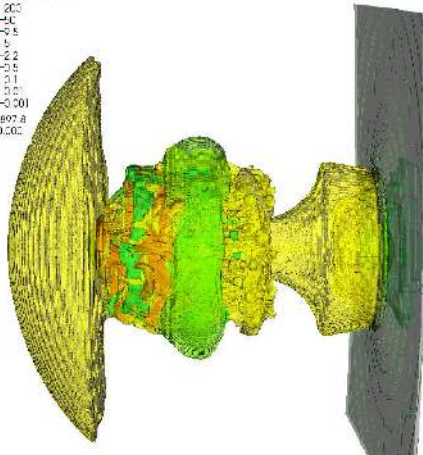


DB: variance of rho at time 0.06

Contour  
Var. variance of rho



Max: 897.8  
Min: 0.002



$L$	$M_L$	grid size	CFL	cores	runtime	efficiency
6	4	1024x1024x1024	0.475	21844	4:49:42	93.9%

MLMC algorithm is **non-intrusive**



Parallelization

# MLMC: Distributions of random run-times across levels

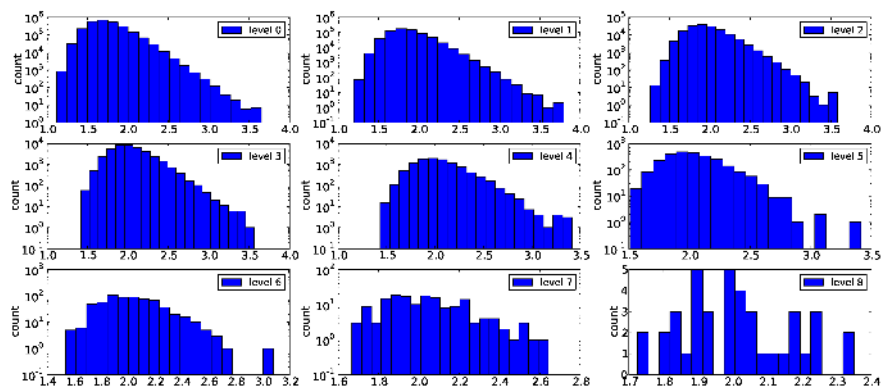


Figure : Distributions of random wave speeds for all resolution levels

# Adaptive load balancing algorithm

Generalization of "greedy" algorithm for "workers" with non-uniform speed of execution

**Setup:** "Workers"  $\mathcal{G}_m^s$  (blue) with "computing capacities"  $C_m$  (green):



**Loads:** (pre-FVM step, computed in parallel)

$$\text{Load}_\ell^i = \lambda_\ell^i \Delta x_\ell^{(d+1)} \sim \mathcal{O}(N_{\text{cells}} N_t), \quad \ell = 0, \dots, L, \quad i = 1, \dots, M_\ell.$$

**Recursive rule:**

Assign the **largest**  $\text{Load}_\ell^i$  to the worker  $\mathcal{G}_m^s$  for which the total load is **minimized**.

## Pseudocode

$$\mathcal{L} = \{\text{Load}_\ell^i : \ell = 0, \dots, L, i = 1, \dots, M_\ell\}$$

**while**  $\mathcal{L} \neq \emptyset$  **do**

$$\text{Load}_\ell^i = \max \mathcal{L}$$

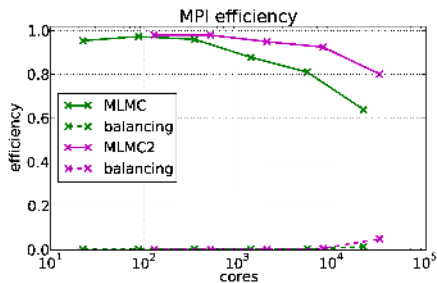
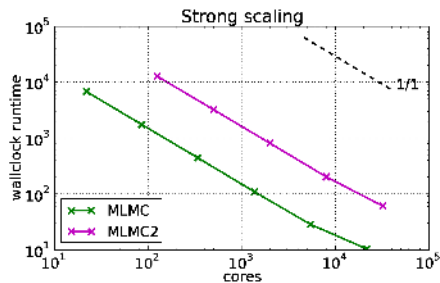
$$\mathcal{G}_m^s = \arg \min \sum \left\{ \text{Load} / C_m : \text{Load} \in \mathcal{G}_m^s \cup \text{Load}_\ell^i \right\}$$

$$\mathcal{G}_m^s = \mathcal{G}_m^s \cup \text{Load}_\ell^i$$

$$\mathcal{L} = \mathcal{L} \setminus \text{Load}_\ell^i$$

# Linear (strong) scaling of adaptive load balancing

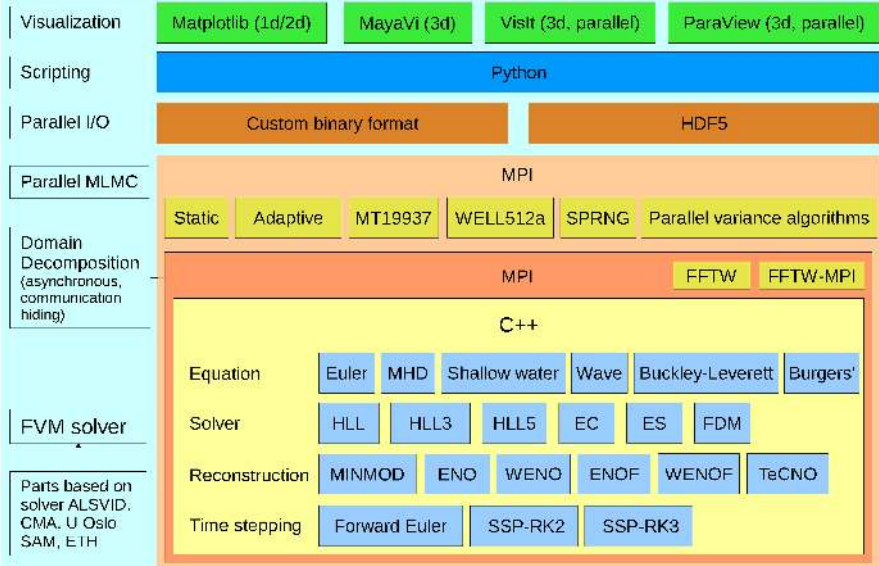
(with domain decomposition)



**Strong and weak scaling up to 40 000 cores with high efficiency.**  
(Cray XE6, CSCS)

# Parallel MLMC-FVM implementation: ALSVID-UQ

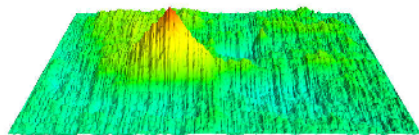
## ALSVID-UQ



Do we ever need more than  
10 or even 100 sources of uncertainty?

If yes, does MLMC-FVM still work?

# Shallow water equations



Flows in rivers, lakes and oceans; atmospheric flows for weather prediction, etc.

$$\mathbf{U} = \begin{bmatrix} h \\ hu \\ hv \end{bmatrix}, \quad \mathbf{F} = \begin{bmatrix} hu \\ hu^2 + \frac{1}{2}gh^2 \\ huv \end{bmatrix}, \quad \mathbf{G} = \begin{bmatrix} hv \\ huv \\ hv^2 + \frac{1}{2}gh^2 \end{bmatrix}, \quad \mathbf{S} = \begin{bmatrix} 0 \\ -ghb_x(\omega) \\ -ghb_y(\omega) \end{bmatrix},$$

with bottom topography  $b \in L^2(\Omega, W^{1,\infty}(\mathbf{D}))$ .

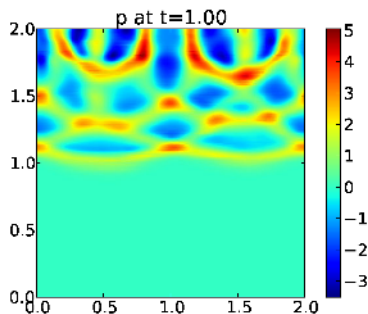
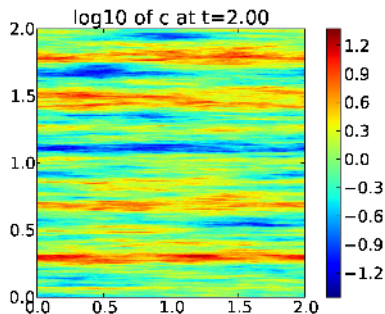
$$\begin{cases} \mathbf{U}_t + \mathbf{F}(\mathbf{U})_x + \mathbf{G}(\mathbf{U})_y = \mathbf{S}(\mathbf{U}, x, y, \omega), \\ \mathbf{U}(x, y, 0) = \mathbf{U}_0(x, y, \omega). \end{cases} \quad (x, y) \in \mathbf{D}, \quad t > 0, \quad \forall \omega \in \Omega.$$



# Wave equation: log-normal material coefficient

One realization - 16 384 sources of uncertainty

$$p_{tt}(\mathbf{x}, t, \omega) - \nabla \cdot (c(\mathbf{x}, \omega) \nabla p(\mathbf{x}, t, \omega)) = 0$$



Coefficient  $c(\mathbf{x}, \omega)$  is assumed to be **log-normal**, determined by its covariance

$$\text{Cov}(\log c(\mathbf{x}, \cdot), \log c(\mathbf{y}, \cdot)) = k(\|\mathbf{x} - \mathbf{y}\|_{\eta}) = \sigma^2 \exp \left( -\sqrt{\sum_{r=1}^d \frac{|\mathbf{x}_r - \mathbf{y}_r|^2}{\eta_r^2}} \right)$$

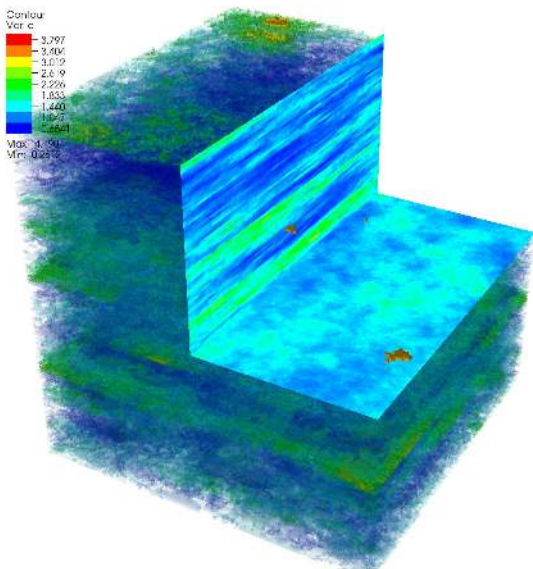
where

- ▶ **covariance kernel**  $k : \mathbb{R} \rightarrow \mathbb{R}_+$
- ▶ **correlation lengths** in each direction  $\eta = \{\eta_1, \dots, \eta_d\} \in \mathbb{R}_+^d$  (**anisotropy**)

# Log-normal anisotropically correlated coefficient in 3d

One realization - 2 million sources of uncertainty

DB: c at time 1



$L$	0
$M_L$	1
grid size	$1024^3$
CFL	0.475
cores	4096
runtime	2:45:36
efficiency	99.9%

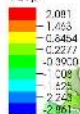
# Wave equation with log-normal coefficient in 3d

One realization, reflecting/periodic b.c.

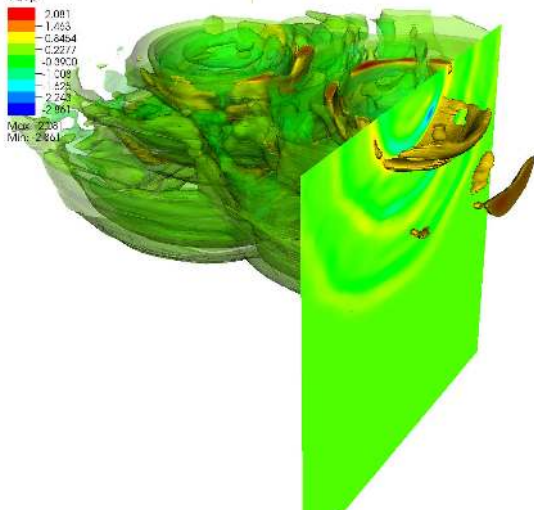
DB: p at time 1

Contour

Var: p



Max: 2.08  
Min: -2.961

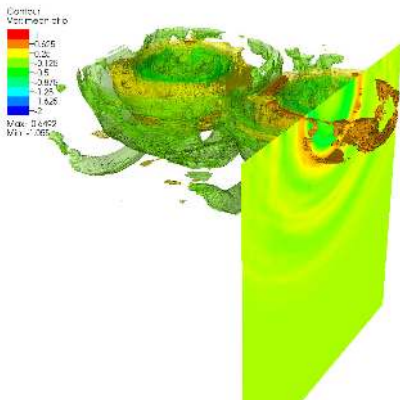


$L$	0
$M_L$	1
grid size	$1024^3$
CFL	0.475
cores	4096
runtime	2:45:36
efficiency	99.9%

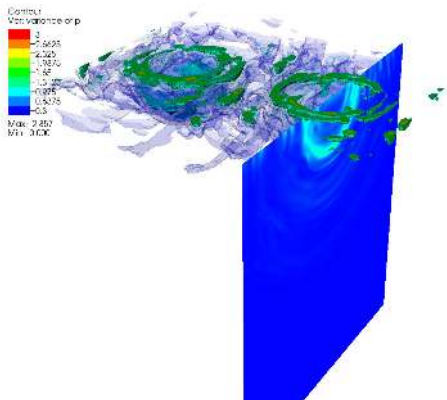
# Wave equation with log-normal coefficient in 3d

MLMC-FVM, reflecting/periodic b.c., adaptive load balancing

DB: mean of  $p$  at time 1



DB: variance of  $p$  at time 1



$L$	$M_L$	grid size	CFL	cores	runtime	efficiency
6	8	1024x1024x1024	0.475	43680	2:48:50	98.1%

Figure : Solution of wave equation using MLMC-FVM and reflecting/periodic b.c.

## Summary for MLMC-FVM method

- ▶ notion of random weak entropy solution is formulated
- ▶ the resulting stochastic hyperbolic system of CLs is shown to be well-posed
- ▶ applications: **Euler, MHD, shallow water, Buckley-Leverett, wave, etc.**
- ▶ flexible w.r.t. the origin of the uncertainty:  $\mathbf{U}_0, \mathbf{S}, c, \mathbf{F}$
- ▶ optimal computational complexity (same as for **deterministic** systems)
- ▶ 2-3 orders of magnitude **speed-up** of MLMC-FVM vs. MC-FVM
- ▶ **linear** complexity w.r.t. **stochastic dimension** (unlike in gPC)
- ▶ low **regularity** requirements
- ▶ **non-intrusive** - deterministic FVM solvers can be reused
- ▶ **easily** parallelizable and **scalable** (tested up to 40 000 cores)
- ▶ algorithmic **fault tolerant** parallelization: <sup>10</sup>
  - ▶ **lost** samples (due to node failures) are **dropped** (NO checkpoint/restore)
  - ▶ MLMC-FVM error bound is still **valid**, in the sense of **expected accuracy**

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<sup>10</sup>Pauli, Arbenz and Schwab (SAM Report No. 2012-24, PARCO 2013)

## Joint work in progress with

- ▶ Siddhartha Mishra
  - ▶ SAM, ETH Zürich, Switzerland
- ▶ Christoph Schwab
  - ▶ SAM, ETH Zürich, Switzerland
  
- ▶ Other collaborators:
  - ▶ Florian Müller
  - ▶ Stefan Pauli
  - ▶ Svetlana Tokareva
  - ▶ Luc Grosheintz
  - ▶ Manuel Kohler
  - ▶ Franziska Weber
  
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  - ▶ CH1-03 10-1
  
- ▶ Grant from the Swiss National Supercomputing Centre (CSCS)
  - ▶ Project ID S366

# Publications (JŠ, S. Mishra, Ch. Schwab, A. Barth)

List available at: <http://pub.sukys.lt>

- ▶ **ALSVID-UQ:** <http://www.sam.math.ethz.ch/alsvid-uv>.
- ▶ *MLMC approximations of statistical solutions to the Navier-Stokes equation.* In review, 2014.
- ▶ *MLMC-FVM: uncertainty quantification in nonlinear systems of balance laws.* **Springer LNCSE (92)**, 225–294, 2013.
- ▶ *MLMC-FVM for stochastic linear hyperbolic systems.* **MCQMC 2012, Springer Proc. Math. Stat. (65)**, 649–666, 2013.
- ▶ *Adaptive load balancing for massively parallel multi-level Monte Carlo solvers.* **PPAM 2013** (to appear).
- ▶ *MLMC-FVM for shallow water equations with uncertain topography.* **SIAM J. Sci. Comput.**, **34(6)**, B761–B784, 2012.
- ▶ *MLMC-FVM for nonlinear systems of conservation laws in multi-dimensions.* **J. Comp. Phys.**, **231(8)**, 3365–3388, 2012.
- ▶ *Sparse tensor MLMC-FVM for conservation laws with random initial data.* **Math. Comp.**, **280**, 1979–2018, 2012.
- ▶ *Static load balancing for multi-level Monte Carlo finite volume solvers.* **PPAM 2011, Part I, LNCS 7203**, 245–254. Springer, Heidelberg 2012.