Discrete least squares polynomial approximations for high dimensional uncertainty propagation

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Acknowlegments: G. Migliorati (EPFL), R. Tempone (KAUST), A. Cohen, A. Chkifa (UPMC - Paris VI), E. von Schwerin (KTH),

MascotNum Workshop on Computer Experiments and Meta-models for Uncertainty Quantification, April 23-25, 2014, ETH Zürich,



Italian project FIRB-IDEAS ('09) Advanced Numerical Techniques for Uncertainty Quantification in Engineering and Life Science Problems



Center for Advanced Modeling and Science





#### Outline

- Introduction parametric / stochastic equations
- 2 Stochastic polynomial approximation
- Discrete least squares approx. using random evaluations
   Convergence analysis
   Numerical results
- 4 Adaptive algorithms
- 5 Conclusions



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find 
$$u: \quad \mathcal{F}(\mathbf{y}, u) = 0$$
 (1)

where **y** is a vector of *N* parameters:  $\mathbf{y} = (y_1, \ldots, y_N) \in \mathbb{R}^N$  $(N = \infty$  when dealing with distributed fields).

- Often in applications the parameters **y** are not perfectly known or are intrinsically variable. Examples are:
  - subsurface modeling: porous media flows; seismic waves; basin evolutions; ...
  - modeling of living tissues: mechanical response; growth models;
  - material science: properties of composite materials
- Probabilistic approach: y is a random vector with probability density function ρ : Γ ⊂ ℝ<sup>N</sup> → ℝ<sub>+</sub>.

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Assumption:  $\forall \mathbf{y} \in \Gamma$  the problem admits a unique solution  $u \in V$  in a suitable finite or infinite dimensional Hilbert space V. Moreover,

 $\forall \mathbf{y} \in \mathsf{\Gamma}, \ \exists C(\mathbf{y}) > 0; \qquad \|u(\mathbf{y})\|_{V} \leq C(\mathbf{y})$ 

Then, equation (1) induces a map u = u(y) : Γ → V.
if ∫<sub>Γ</sub> C(y)<sup>p</sup>ρ(y)dy < ∞, then u ∈ L<sup>p</sup><sub>ρ</sub>(Γ, V).

Goals:

• Construct a reduced model  $u_{\Lambda}(\mathbf{y}) \approx u(\mathbf{y})$ 

• Compute statistics of the solution

**Expected value**:  $\bar{u} \approx \mathbb{E}[u_{\Lambda}]$ **Variance**:  $Var[u] \approx \mathbb{E}[u_{\Lambda}^2] - \mathbb{E}[u_{\Lambda}]^2$ **two points corr.** (if *u* is a distributed field)

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#### Example: Elliptic PDE with random coefficients

$$\begin{cases} -\operatorname{div}(a(\mathbf{y}, x) \nabla u(\mathbf{y}, x)) = f(x) & x \in D, \ \mathbf{y} \in \Gamma, \\ u(\mathbf{y}, x) = 0 & x \in \partial D, \ \mathbf{y} \in \Gamma \end{cases}$$
  
with  $a_{\min}(\mathbf{y}) = \inf_{x \in D} a(\mathbf{y}, x) > 0$  for all  $\mathbf{y} \in \Gamma$  and  $f \in L^2(D)$ . Then  
 $\forall \mathbf{y} \in \Gamma, \quad u(\mathbf{y}) \in V \equiv H^1_0(D), \text{ and } \|u(\mathbf{y})\|_V \leq \frac{C_P}{a_{\min}(\mathbf{y})} \|f\|_{L^2(D)}.$ 

#### Inclusions problem

**y** describes the conductivitiy in each inclusion

$$a(\mathbf{y}, x) = a_0 + \sum_{n=N}^{N} y_n \mathbb{1}_{D_n}(x)$$



#### Random fields problem

 $a(\mathbf{y}, \mathbf{x})$  is a random field, e.g. lognormal:  $a(\mathbf{y}, \mathbf{x}) = e^{\gamma(\mathbf{y}, \mathbf{x})}$  with  $\gamma$ expanded e.g. in Karhunen-Loève series

$$y(\mathbf{y}, x) = \sum_{n=1}^{\infty} \sqrt{\lambda_n} y_n b_n(x)$$



 $y_n \sim N(0,1) \ i.i.d.$ 

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- The parameter-to-solution map u(y) : Γ → V is often smooth (even analytic for the elliptic diffusion model). It is therefore sound to approximate it by global multivariate polynomials.
- Let Λ ⊂ ℕ<sup>N</sup> be an index set of cardinality |Λ| = M, and consider the multivariate polynomial space

 $\mathbb{P}_{\Lambda}(\Gamma) = span\left\{\prod_{n=1}^{N} y_n^{p_n}, \text{ with } \mathbf{p} = (p_1, \dots, p_N) \in \Lambda\right\}$ 

We seek an approximation  $P_{\Lambda} u \in \mathbb{P}_{\Lambda}(\Gamma) \otimes V$ .

• The optimal choice of  $\Lambda$  depends heavily on the problem at hand and the "structure" of the map  $u(\mathbf{y})$ .





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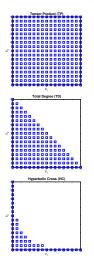
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$$\mathbf{p} \in \Lambda$$
 and  $\mathbf{q} \leq \mathbf{p} \implies \mathbf{q} \in \Lambda$ 

Stochastic polynomial approximation

#### Common choices of polynomial spaces



tensor product (TP)  $\Lambda(w) = \{\mathbf{p} : \max_n p_n \le w\}$ 

total degree (TD)  $\Lambda(w) = \{\mathbf{p} : \sum_{n=1}^{N} p_n \leq w\}$ 

hyperbolic cross (HC)  $\Lambda(w) = \{\mathbf{p}: \prod_{n=1}^{N} (p_n + 1) \le w + 1\}$ 

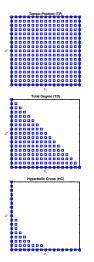
Anisotropic versions are also possible.
All these index sets are all downward closed, and an and all downward closed.



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#### Approximation using random evaluations

**Goal**: construct a polynomial approximation using random evaluations (Monte Carlo sampling):

- **(**) Generate *M* random i.i.d. samples  $\mathbf{y}^{(k)} \sim \rho(\mathbf{y}) d\mathbf{y}$ , k = 1, ..., M
- **2** Compute the corresponding solutions  $u^{(k)} = u(\mathbf{y}^{(k)})$
- Source of the construct a suitable approximation  $P^{M,\omega}_{\Lambda} u \in \mathbb{P}_{\Lambda}(\Gamma) \otimes V$



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#### Notation

given two functions  $u, v \in L^2_{\rho}(\Gamma; V)$ 

- Continuous inner product:  $\mathbb{E}[(u, v)_V] = \int_{\Gamma} (u(\mathbf{y}), v(\mathbf{y}))_V \rho(\mathbf{y}) d\mathbf{y}$
- Continuous norm:  $\|v\|_{L^2_{\rho}(\Gamma;V)}^2 = \mathbb{E}[(v,v)_V].$
- Discrete inner product:  $\mathbb{E}_M[(u, v)_V] = \frac{1}{M} \sum_{i=1}^M (u(\mathbf{y}^{(i)}), v(\mathbf{y}^{(i)}))_V$
- Discrete norm:  $\|v\|_{M,V}^2 = \mathbb{E}_M[(v,v)_V]$

Let  $\{\psi_{\mathbf{p}}\}_{\mathbf{p}\in\Lambda}$  be an orthonormal basis of  $\mathbb{P}_{\Lambda}$  w.r.t the weight  $\rho$ . Then, the best approximation of u in  $\mathbb{P}_{\Lambda}(\Gamma) \otimes V$  (exact  $L^2$  projection) is

$$P_{\Lambda} u = \operatorname*{argmin}_{v \in \mathbb{P}_{\Lambda}(\Gamma) \otimes V} \mathbb{E}[\|u - v\|_{V}^{2}] = \sum_{\mathbf{p} \in \Lambda} \mathbb{E}[u\psi_{\mathbf{p}}]\psi_{\mathbf{p}}$$

How to compute an approx. projection using the random sample Replace the exact expectation  $\mathbb{E}[\cdot]$  with the sample average  $\underline{F}_{\mathcal{M}}[\underline{e}]$ .

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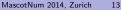
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Discrete least squares polynomial appro»

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Even for smooth functions the convergence is  $O(\sqrt{M})!$ 



# Second idea (good): Discrete least squares approximation

(see e.g. [Hosder-Walters et al. 2010, Blatman-Sudret 2008, Burkardt-Eldred 2009, Eldred 2011, Yan-Guo-Xiu 2012, Cohen-Davenport-Leviatan 2013, Migliorati etal 2011-2014])

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#### Two relevant questions

- What is the accuracy of the random discrete least square approximation?
- For a given set Λ, how many samples should one use?



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## Algebraic formulation

- Let  $V_h \subset V$  be a finite dimensional subspace (e.g. finite elements) and  $\{\phi_j\}_{j=1}^{N_h}$  a basis; mass matrix  $\mathcal{M}_{ij} = (\phi_j, \phi_i)_V$ .
- Let  $\{\psi_{\mathbf{p}}\}_{\mathbf{p}\in\Lambda}$  be an orthonormal basis of  $\mathbb{P}_{\Lambda}$  w.r.t the weight  $\rho$ ; define the design matrix  $D_{i\mathbf{p}} = \frac{1}{\sqrt{M}}\psi_{\mathbf{p}}(\mathbf{y}^{(i)})$ .

Then  $P_{\Lambda}^{M,\omega}u(x,\mathbf{y}) = \sum_{\mathbf{p}\in\Lambda} \sum_{j=1}^{N_{h}} c_{\mathbf{p}j}\phi_{j}(x)\psi_{\mathbf{p}}(\mathbf{y})$  and the tensor  $C = \{c_{\mathbf{p}j}\}$  satisfies the normal equations

 $(D^T D \otimes \mathcal{M})C = (D^T \otimes \mathcal{M})U$ 

with  $u(\mathbf{y}^{(i)}) = \sum_{j=1}^{N_h} u_j(\mathbf{y}^{(i)})\phi_j$  and  $U_{ij} = \frac{1}{\sqrt{M}} u_j(\mathbf{y}^{(i)})$ .

Since the matrix  $\mathcal{M}$  is invertible, the previous problem decouples in  $N_h$  least square problems, one for each spatial dof.

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Then  $P_{\Lambda}^{M,\omega}u(x,\mathbf{y}) = \sum_{\mathbf{p}\in\Lambda} \sum_{j=1}^{N_h} c_{\mathbf{p}j}\phi_j(x)\psi_{\mathbf{p}}(\mathbf{y})$  and the tensor  $C = \{c_{\mathbf{p}j}\}$  satisfies the normal equations

 $(D^T D \otimes \mathcal{M})C = (D^T \otimes \mathcal{M})U$ 

with  $u(\mathbf{y}^{(i)}) = \sum_{j=1}^{N_h} u_j(\mathbf{y}^{(i)})\phi_j$  and  $U_{ij} = \frac{1}{\sqrt{M}}u_j(\mathbf{y}^{(i)})$ .

Since the matrix  $\mathcal{M}$  is invertible, the previous problem decouples in  $N_h$  least square problems, one for each spatial dof.

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# Algebraic formulation

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#### Error analysis

The error analysis goes through the *equivalence of norms* on the polynomial space. Remind:

- continuous norm:  $\|v\|_{L^2_o(\Gamma;V)}^2 = \int_{\Gamma} \|v(\mathbf{y})\|_V^2 \rho(\mathbf{y}) d\mathbf{y}$
- discrete norm:  $\|v\|_{M,V}^2 = \frac{1}{M} \sum_{i=1}^{M} \|v(\mathbf{y}^{(i)})\|_V^2$

Define the random variable

$$\delta:=\sup_{v\in\mathbb{P}_{\Lambda}(\Gamma)\otimes V}\left|rac{\|v\|_{M,V}^2}{\|v\|_{L^2_{
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Whenever  $\delta < 1$ , we have norm equivalence

 $(1-\delta)\|v\|_{L^2_\rho(\Gamma,V)}^2 \leq \|v\|_{M,V}^2 \leq (1+\delta)\|v\|_{L^2_\rho(\Gamma,V)}^2, \quad \forall v \in \mathbb{P}_{\Lambda}(\Gamma) \otimes V$ 

(analogous to RIP in compressed sensing, see [Candès-Tao 2006 Rahout-Ward 2012, ...])

F. Nobile (EPFL)

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F. Nobile (EPFL)

Discrete least squares approx. using random evaluations

Convergence analysis

Theorem [Migliorati-Nobile-von Schwerin-Tempone '11]

• 
$$\delta \to 0$$
 almost surely when  $M \to \infty$ 

$$a ||u - P^{M,\omega}_{\Lambda}u||_{L^2_{\rho}(\Gamma,V)} \leq (1 + \sqrt{\frac{1}{1-\delta}}) \inf_{v \in \mathbb{P}_{\Lambda}(\Gamma) \otimes V} ||u - v||_{L^{\infty}(\Gamma,V)}$$

Proof: for any  $v \in \mathbb{P}_{\Lambda} \otimes V$ :

$$\begin{aligned} \|u - P_{\Lambda}^{M,\omega} u\|_{L^{2}_{\rho}(\Gamma,V)} &\leq \|u - v\|_{L^{2}_{\rho}(\Gamma,V)} + \|v - P_{\Lambda}^{M,\omega} u\|_{L^{2}_{\rho}(\Gamma,V)} \\ &\leq \|u - v\|_{L^{2}_{\rho}\otimes V} + \sqrt{\frac{1}{1 - \delta}} \|v - P_{\Lambda}^{M,\omega} u\|_{M,V} \\ &\leq \|u - v\|_{L^{2}_{\rho}(\Gamma,V)} + \sqrt{\frac{1}{1 - \delta}} \|u - v\|_{M,V} \end{aligned}$$

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[Migliorati-Nobile-von Schwerin-Tempone '11] in the case of 1 uniform random variable  $y \sim \mathcal{U}([-1,1])$  using order statistics:  $\forall \alpha \in (0,1)$ , if  $M \propto \#\Lambda^2$ , then  $C_{\delta} \leq 3 \log \frac{M+1}{\alpha}$  with probability larger than  $1 - \alpha$ . Discrete least squares approx. using random evaluations

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## A general result

[Cohen-Davenport-Leviatan '12], [Chkifa-Cohen-Migliorati-Nobile-Tempone '13] Let  $\{\psi_{\mathbf{p}}\}$  be any orthonormal basis of  $L^2_{\rho}(\Gamma)$  and define

$$\mathcal{K}(\Lambda) := \sup_{\mathbf{y} \in \Gamma} \left( \sum_{\mathbf{p} \in \Lambda} |\psi_{\mathbf{p}}(\mathbf{y})|^2 \right) = \sup_{\mathbf{v} \in \mathbb{P}_{\Lambda}} \frac{\|\mathbf{v}\|_{L^{\infty}(\Gamma)}^2}{\|\mathbf{v}\|_{L^2_{\rho}(\Gamma)}^2}$$

Theorem [Cohen-Davenport-Leviatan '13]

For any  $\gamma > 0$ , and  $0 < \delta < 1$ , and  $\beta_{\delta} = \delta + (1 - \delta) \log(1 - \delta)$ , if

$$\frac{M}{\log M} \ge \frac{1+\gamma}{\beta_{\delta}} \mathcal{K}(\Lambda), \tag{2}$$

Then 
$$P\left((1-\delta)\|v\|_{L^2_{\rho}(\Gamma;V)}^2 \le \|v\|_{M,V}^2 \le (1+\delta)\|v\|_{L^2_{\rho}(\Gamma;V)}^2\right) \ge 1 - 2M^{-\gamma}$$

The result is based on properties of random matrices.



#### Implications

Convergence in probability: with probability greater than  $1-2M^{-\gamma}$ 

$$\|u-P^{M,\omega}_{\Lambda}u\|_{L^2_{\rho}(\Gamma;V)} \leq (1+\sqrt{\frac{1}{1-\delta}})\inf_{v\in\mathbb{P}_{\Lambda}\otimes V}\|u-v\|_{L^{\infty}(\Gamma,V)}$$

Convergence in expectation: assume  $||u||_{L^{\infty}(\Gamma,V)} \leq \tau$  and define the truncation operator

$$T_{\tau}: V \to V, \qquad T_{\tau}(v) = \begin{cases} v & \text{if } \|v\|_{V} \leq \tau \\ \frac{\tau}{\|v\|_{V}}v, & \text{if } \|v\|_{V} > \tau \end{cases}$$

Then  $\mathbb{E}^{\omega}(\|u - T_{\tau}P^{M,\omega}_{\Lambda}u\|^{2}_{L^{2}_{\rho}(\Gamma;V)}) \leq C\|u - P_{\Lambda}u\|^{2}_{L^{2}_{\rho}(\Gamma,V)} + 8\tau^{2}M^{-\gamma}$ Stability of discrete least squares:  $cond(D^{T}D) \leq \frac{1+\delta}{1-\delta}$ .

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MascotNum 2014, Zurich

## Uniform random vector in $[-1, 1]^N$

Let  $y_1, \ldots, y_N$  be i.i.d. uniform random variables in [-1, 1].

Theorem [Chkifa-Cohen-Migliorati-Nobile-Tempone '13]

For any N and any downward closed set  $\Lambda \subset \mathbb{N}^N$  it holds

 $K(\Lambda) \leq (\#\Lambda)^2.$ 

Therefore, the discrete  $L^2$  projection is stable and optimally convergent under the condition

$$\frac{M}{\log M} \geq \frac{1+\gamma}{\beta_{\delta}} (\#\Lambda)^2$$

The result uses expansion on Legendre polynomials for which

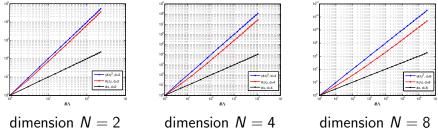
$$|\psi_{\mathbf{p}}(\mathbf{y})| \leq \prod_{n=1}^{N} \sqrt{2p_n + 1}, \quad \forall \mathbf{y} \in [-1, 1]^N.$$

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## Uniform random vector in $[-1, 1]^N$

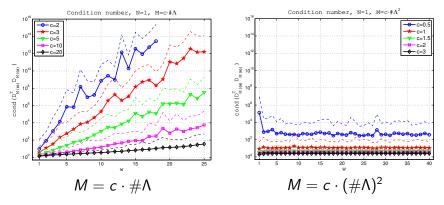
- For specific sets  $\Lambda$  the condition can be improved.
- For instance for the Total Degree polynomial space of degree w the bound K(Λ) ≤ (#Λ)<sup>2</sup> is very conservative





## Some numerical examples - 1D function

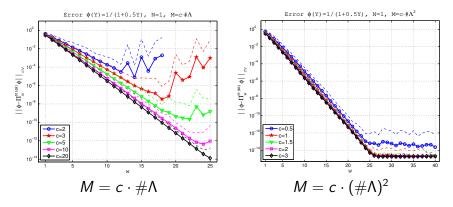
#### Condition number of $D^T D$





#### Some numerical examples - 1D function

Approximation of the meromorphic function  $\phi(y) = \frac{1}{1+0.5y}$ 

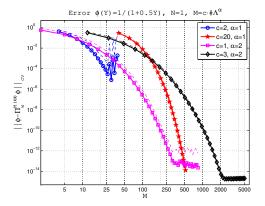


error with respect to polynomial degree.



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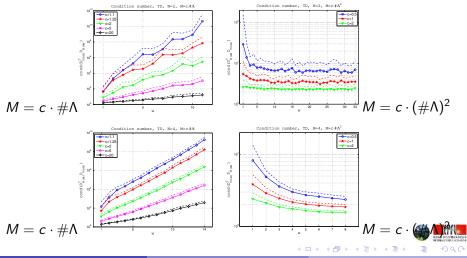


error with respect to total number of sampling points.



#### Some numerical examples

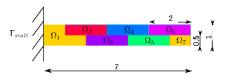
#### Condition number of $D^T D$ – multiD – Total Degree poly. space



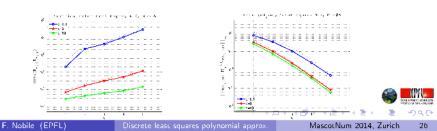
## Cantilever beam

- linear elasticity equations
- Young modulus uncertain in each brick:

$$egin{aligned} & E_i = e^{7+Y_i}, & ext{in } \Omega_i, \ & Y_i \sim \mathcal{U}([-1,1]), \ & iid \end{aligned}$$

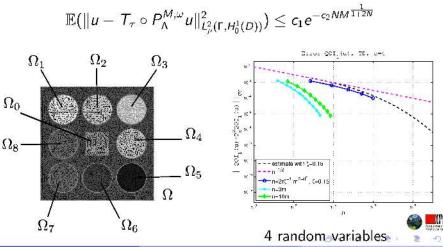


 Uncertainty analysis on maximum vertical displacement.



#### Elliptic PDE with random inclusions

The following bound has been derived in [Chkifa-Cohen-Migliorati-Nobile-Tempone 13]



Improvements can be obtained by sampling from a different distribution  $\hat{\rho}$ . Let us consider the weighted least squares approx.

$$P^{M}_{\Lambda}u = \operatorname*{argmin}_{v \in \mathbb{P}_{\Lambda}(\Gamma) \otimes V} \frac{1}{M} \sum_{k=1}^{M} \frac{\rho(\mathbf{y}^{(k)})}{\hat{\rho}(\mathbf{y}^{(k)})} \|u^{(k)} - v(\mathbf{y}^{(k)})\|_{V}^{2}$$

where the sample  $\{\mathbf{y}^{(k)}\}_k$  is drawn from the distribution  $\hat{\rho}(\mathbf{y})d\mathbf{y}$ .

- $\rho(\mathbf{y}) = \hat{\rho}(\mathbf{y}) = \text{Chebyshev distribution in } [-1,1]^N$ , then the relation  $M \propto \min\{2^N \# \Lambda, (\# \Lambda)^{\frac{\log(3)}{\log(2)}}\}$  is enough to guarantee optimal convergence [Chkifa-Cohen-Migliorati-N.-Tempone '13]
- ρ(y)=uniform and ρ̂(y)=Chebyshev distribution in [-1, 1]<sup>N</sup>, then, the relation M ∝ 2<sup>N</sup>#Λ guarantees optimal convergence [Rauhut-Ward '12]. However, the constant depends on N [Yan-Guo-Xiu '12].
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- $\rho(\mathbf{y})=$ uniform and  $\hat{\rho}(\mathbf{y})=$ Chebyshev distribution in  $[-1,1]^N$ , then, the relation  $M \propto 2^N \# \Lambda$  guarantees optimal convergence [Rauhut-Ward '12]. However, the constant depends on N [Yan-Guo-Xiu '12].
- ρ(y)=Gaussian: still unclear. Numerically, the situation seems to be worse. Improvements suggest din [Tang-Zhou '14];

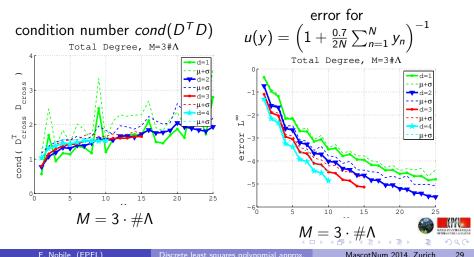
F. Nobile (EPFL)

Discrete least squares polynomial approx



## Numerical example with Chebyshev preconditioning

Expansion in Legendre polynomials ( $\rho(\mathbf{y})$ =uniform) and samples from Chebyshev distribution ( $\hat{\rho}(\mathbf{y}) = \text{Chebyshev}$ )



#### Outline

- Introduction parametric / stochastic equations
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#### Adaptive construction of polynomial spaces

 $\{\Lambda_k\}_{k\geq 0}$  sequence of downward closed multi-index sets, with  $\Lambda_0 = \{\mathbf{0}\}$ . The sequence is adaptively computed by means of greedy algorithms based on the random discrete  $L^2$  projection.

**Definitions:** 

• Margin  $\mathcal{M}(\Lambda)$  associated to a multi-index set  $\Lambda$ :

 $\mathcal{M}(\Lambda) = \{\mathbf{p} : \mathbf{p} \notin \Lambda \text{ and } \exists j > 0 : \mathbf{p} - \mathbf{e}_j \in \Lambda\}$ 

• Reduced margin  $\mathcal{R}(\Lambda)$  associated to a multi-index set  $\Lambda$ :

 $\mathcal{R}(\Lambda) = \{\mathbf{p} \ : \ \mathbf{p} \notin \Lambda \text{ and } \forall j = 1, \dots, d \ : \ p_j \neq 0 \Rightarrow \mathbf{p} - \mathbf{e}_j \in \Lambda \}$ 

set  $\Lambda$  and its Margin set  $\Lambda$  and its Reduced margin



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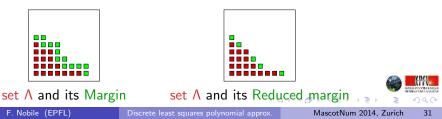
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The Dörfler marking Idea proposed by W. Dörfler in 1996 for Adaptive Finite Elements.

Given a multi-index set  $\Lambda$ , a subset  $R \subseteq \mathcal{R}(\Lambda)$ , a (continuous) function  $e: R \to \mathbb{R}$  and a parameter  $\theta \in (0, 1]$ , we define a procedure

 $D\ddot{o}rfler = D\ddot{o}rfler(R, e, \theta)$ 

that computes a set  $F \subseteq R \subseteq \mathcal{R}(\Lambda)$  of minimal cardinality such that

 $\sum_{\mathbf{p}\in F} e(\mathbf{p})^2 \ge \theta \sum_{\mathbf{p}\in R} e(\mathbf{p})^2.$ 

with the (estimates of the) coefficients in the set  $R_{1,1}$ 



## The Dörfler marking

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In practice, for any  $\mathbf{p} \in R$ , the error indicator  $e(\mathbf{p})$  will be either an estimator of the coefficient  $c_{\mathbf{p}}$  of the function u expanded over the Legendre basis or the projected residual on the  $\mathbf{p}$ -th Legendre basis function.

This corresponds to choose a fraction  $\theta$  of the energy associated with the (estimates of the) coefficients in the set R,



F. Nobile (EPFL)

Discrete least squares polynomial approx

## Orthogonal Matching Pursuit with Dörfler marking

Algorithm 1 Orthogonal Matching Pursuit with Dörfler marking

Set 
$$r_0 = u(\mathbf{y}), u_0 \equiv 0$$
 and  $\Lambda_0 = \{\mathbf{0}\}$ ,  
for  $k = 1, ..., k_{max}$  do  
 $F_1 = \text{Dörfler}(\mathcal{R}(\Lambda_{k-1}), \{|(r_{k-1}, \psi_{\mathbf{p}})_{M, V}|\}_{\mathbf{p}}, \theta_1)$   
 $\widetilde{\Lambda}_k = \Lambda_{k-1} \cup F_1$   
 $u_k = \operatorname{argmin}_{v \in \mathbb{P}_{\widetilde{\Lambda}_k}} ||u - v||_{M, V}, \quad u_k = \sum_{\mathbf{p} \in \widetilde{\Lambda}_k} c_{\mathbf{p}}^{(k)} \psi_{\mathbf{p}}$   
 $F_2 = \text{Dörfler}(F_1, \{c_{\mathbf{p}}^{(k)}\}_{\mathbf{p}}, \theta_2)$   
 $\Lambda_k = \Lambda_{k-1} \cup F_2$   
 $r_k = u - u_k|_{\Lambda_k}$   
end for

 $\theta_1 \in (0,1)$  and  $\theta_2 = 1$ : Dörfler marking only with the correlations.

 $\theta_1 = 1$  and  $\theta_2 \in (0, 1)$ : Dörfler marking only with the random discrete projection on  $\Lambda_{k-1} \cup \mathcal{R}(\Lambda_k)$ .

#### Some remarks and open issues

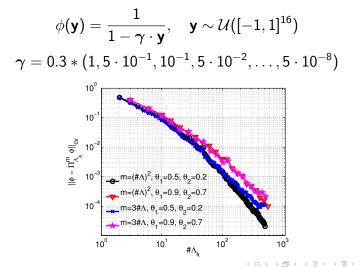
- The first Dörfler marking performs a screening of the reduced margin, to avoid an *L*<sup>2</sup> discrete minimization over a too large polynomial space.
- At each step the correlations {|(r<sub>k-1</sub>, ψ<sub>p</sub>)<sub>M,V</sub>| : p ∈ R(Λ<sub>k</sub>)} are mutually uncoupled and cheap to compute, but might provide only a rough estimate of the coefficients (depending on the choice of M<sub>k</sub>).
- The second Dörfler marking performs a selection based on the more accurate estimates of the coefficients coming from the L<sup>2</sup> projection.
- At each step the adaptive algorithm remains stable and accurate by choosing  $M_k \propto (\#\Lambda_k)^2$  (consequence of the theory in the first part).
- The adaptive algorithm generates a sequence {Λ<sub>k</sub>}<sub>k≥0</sub> of only quasi best *N*-term sets.
- Rate of convergence? Choice of  $\theta_1, \theta_2$ ? What if  $M_k \propto \# \Lambda_k$ ?



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#### A numerical test

Approximation of a meromorphic function (16-variables)



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- We have derived conditions under which the random discrete least squares approximation is stable and optimally convergent.
- The condition M ≥ C(#Λ)<sup>2</sup> for uniform random variables holds in any dimension and for any "shape" of the polynomial space, opening the possibility for adaptive algorithms.
- The condition  $M \sim (\#\Lambda)^2$  seems to be too stringent in high dimension and a linear scaling is often enough, making this technique more attractive for high dimensional problems.
- Still open questions on preconditioned least squares or unbounded random variables.
- We have proposed an adaptive algorithm based on a double Dörfler marking that performs very well. The analysis is still ongoing.



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# Thank you for your attention!



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