

Sequential sensitivity analysis for computer experiments with

functional inputs

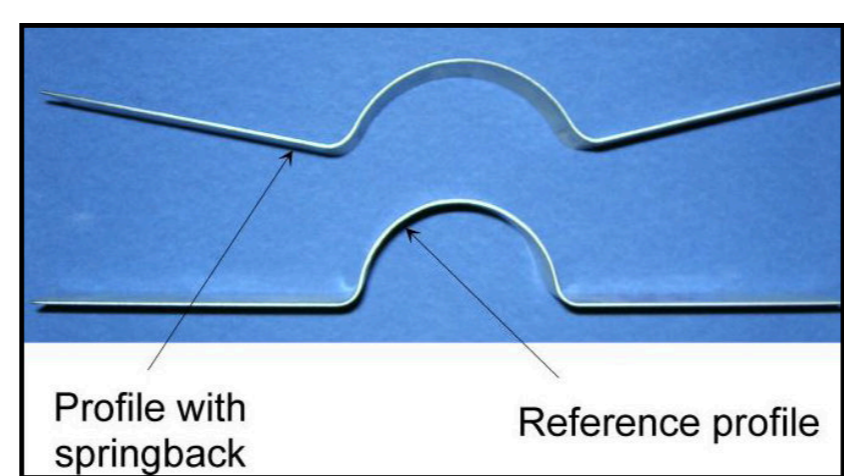
1. Application

Sheet metal forming: Standard industrial process in the forming of car parts



Occuring problems

- Springback: elastic recovery after forming, measured as mean shape deviation
- Tearing
- Wrinkling

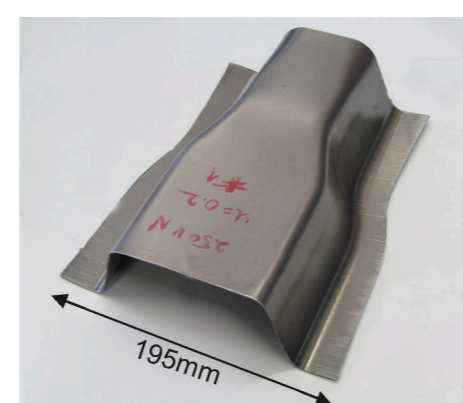


Computer experiment analysis by Finite Element simulations, e.g. by LS-DYNA

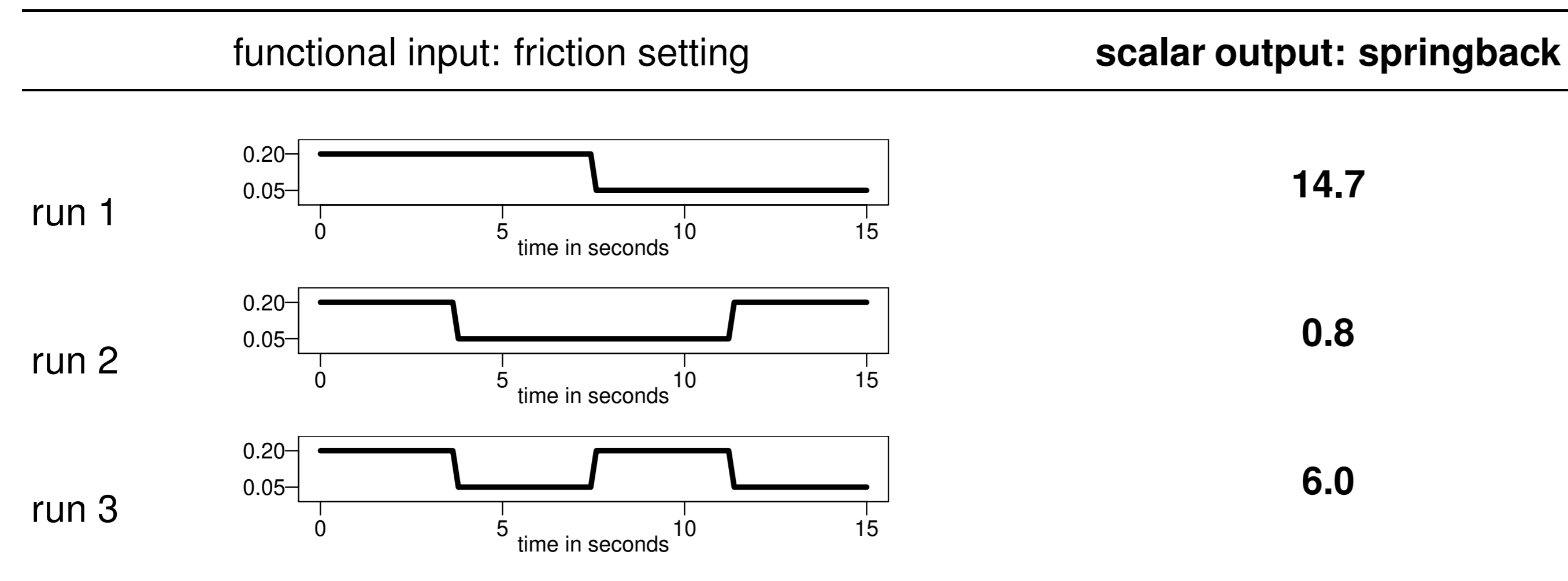
2. Extension to functional input

New possibility: **Variation of two inputs** – blankholder force and friction – during the forming process

- New insights on functional influence on springback, sensitivity analysis
- Improvements in forming, springback optimization



Test runs with different functional behaviour but equal overall mean friction show potential of functional approach



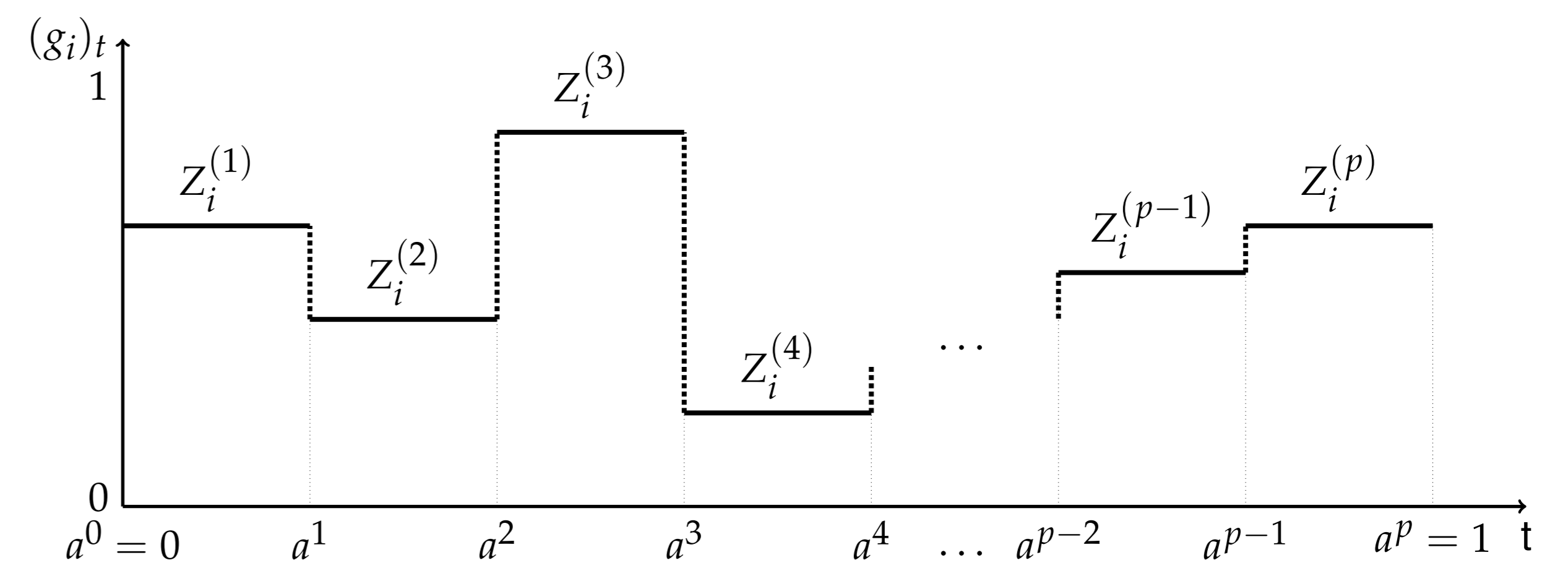
3. Assumptions

- $Y \in \mathbb{R}$ scalar response,
- $g_j : D_j \mapsto [0, 1], j = 1, \dots, d$ functional input variables
- $D_j = [0, 1]$ for each $j = 1, \dots, d$
- Connected by a black box function $\mathcal{F}_{[0,1]}^d \mapsto \mathbb{R}, Y = f(g_1, \dots, g_d)$
- All input variables can be controlled
- Scalar inputs can be considered as constant functional inputs
- Function evaluations very time consuming

4. Functional representation

Functional input via space of **piecewise constant functions**

$$V_0^{a_j} = \left\{ Z_j^{(1)} \mathbb{1}_{[0, a_1]}(t) + \dots + Z_j^{(p_j)} \mathbb{1}_{[a_{j-1}, 1]}(t), \text{ with } Z_j^{(k)} \in [0, 1], 1 \leq k \leq p_j \right\}$$



5. Sensitivity analysis

Input space transformed from functional to scalar

$$Y = f(g_1, \dots, g_d) = \tilde{f}_{a_1, \dots, a_{p_d}}(Z_1^{(1)}, \dots, Z_1^{(p_1)}, \dots, Z_d^{(1)}, \dots, Z_d^{(p_d)})$$

Perform sensitivity analysis on input space $Z_1^{(1)}, \dots, Z_1^{(p_1)}, \dots, Z_d^{(1)}, \dots, Z_d^{(p_d)}$

Sensitivity analysis method: Regression coefficients, normalized to be independent of the particular partition

Definition 1. Consider a set of splitting points a_1, \dots, a_{p_d} and assume that $g_j \in V_{a_j}, j = 1, \dots, d$: $g_j(t) = \sum Z_j^{(k)} \mathbb{1}_{[a_j^{k-1}, a_j^k]}(t)$. Denote by $\hat{\beta}_j^k$ and $\hat{\beta}_j^{(kk')}$ the estimated first-order and second-order regression coefficients, then we define by

$$\hat{H}_j^k = \frac{\hat{\beta}_j^k}{a_j^k - a_j^{k-1}} \text{ and } \hat{H}_j^{kk'} = \frac{\hat{\beta}_j^{(kk')}}{(a_j^k - a_j^{k-1})(a_j^{k'} - a_j^{k'-1})}$$

the so-called **normalized regression index** of $Z_j^{(k)}$ and the **normalized interaction regression index** of $Z_j^{(k)}$ and $Z_j^{(k')}$ resp. for $j \in \{1, \dots, d\}, 1 \leq k < k' \leq p_j$.

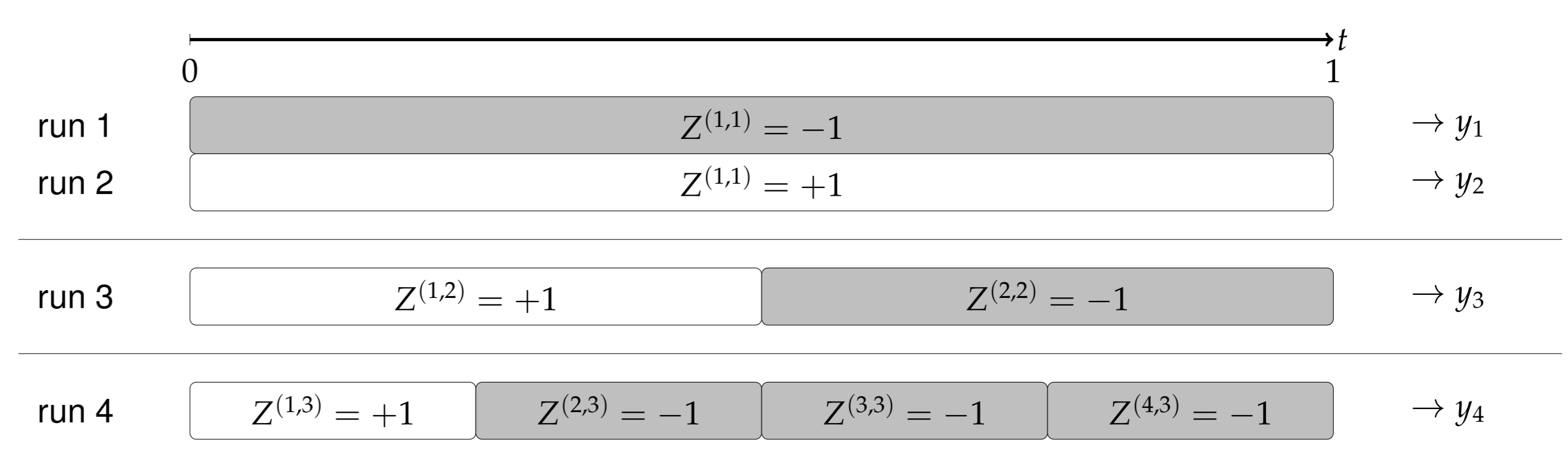
Theoretical result: When f is an integral of an input g weighted by an integrable function $w : [0, 1] \mapsto \mathbb{R}$ the indices return the weights

$$f(g) = \alpha + \int_0^1 w(t)g(t) dt \Rightarrow \hat{H}^k = \frac{\int_{a^{k-1}}^{a^k} w(t) dt}{a^k - a^{k-1}}, \lim_{a^k - a^{k-1} \rightarrow 0} \hat{H}^k = w(t)$$

6. Design based on sequential bifurcation

Sequential bifurcation: Very economical screening method that saves runs by grouping factors

Implementation in functional design: Start with one interval and then split interesting intervals in sequential steps



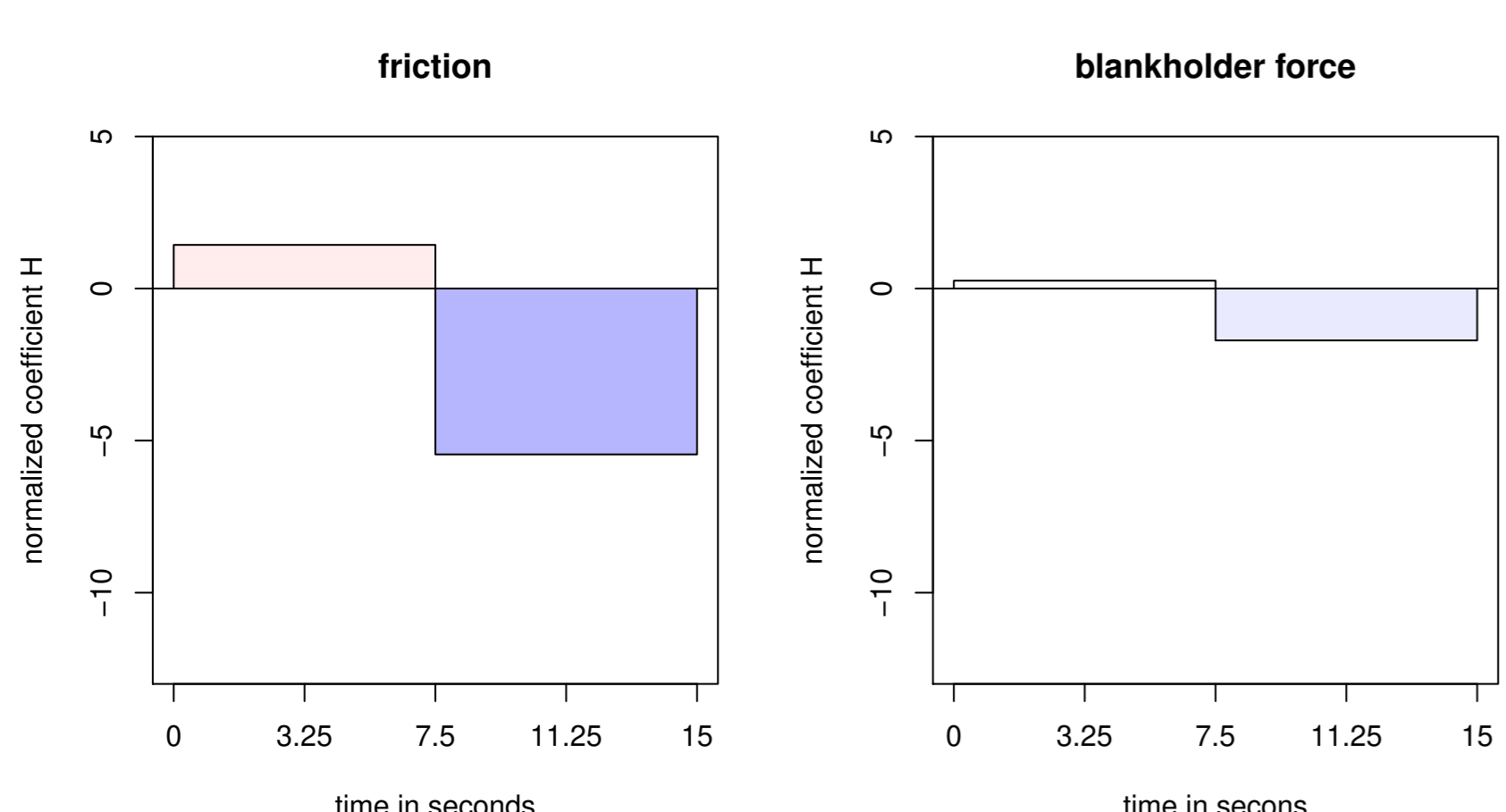
$$\hat{H}^{1,1} = \frac{0.5(y_2 - y_1)}{1}, \hat{H}^{1,2} = \frac{0.5(y_3 - y_1)}{0.5}, \hat{H}^{2,2} = \frac{0.5(y_2 - y_3)}{0.5}, \dots$$

Literature

- [1] Bettonvil, B. (1995): Factor screening by sequential bifurcation. Communications in Statistics-Simulation and Computation 24 (1), S. 165–185.
- [2] Fruth, J.; Roustant, O.; Kuhnt, S. (2014): Sequential designs for sensitivity analysis of functional inputs in computer experiments. Online on HAL: <http://hal.archives-ouvertes.fr/hal-00943509>.
- [3] Ramsay, J. O.; Silverman, B. W. (2005): Functional data analysis. 2nd ed. New York: Springer.
- [4] Saltelli, A.; Chan, K.; Scott, E. M. (Eds.) (2000): Sensitivity analysis. Chichester: Wiley.

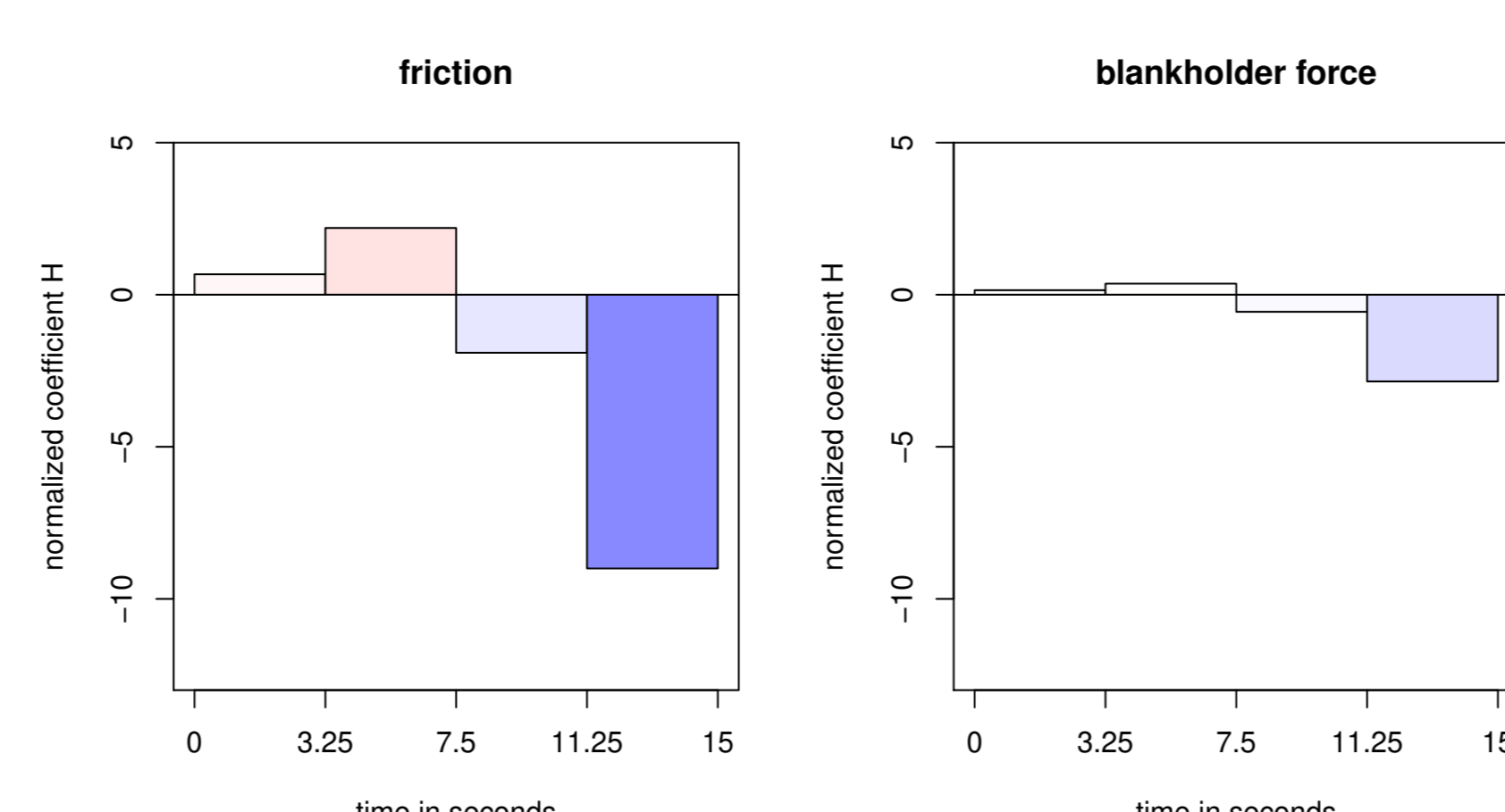
Application results: Sensitivity analysis of the functional influence of friction and blankholder force on springback in three sequential steps using 8 evaluation runs each

Step 1: Two intervals for both inputs



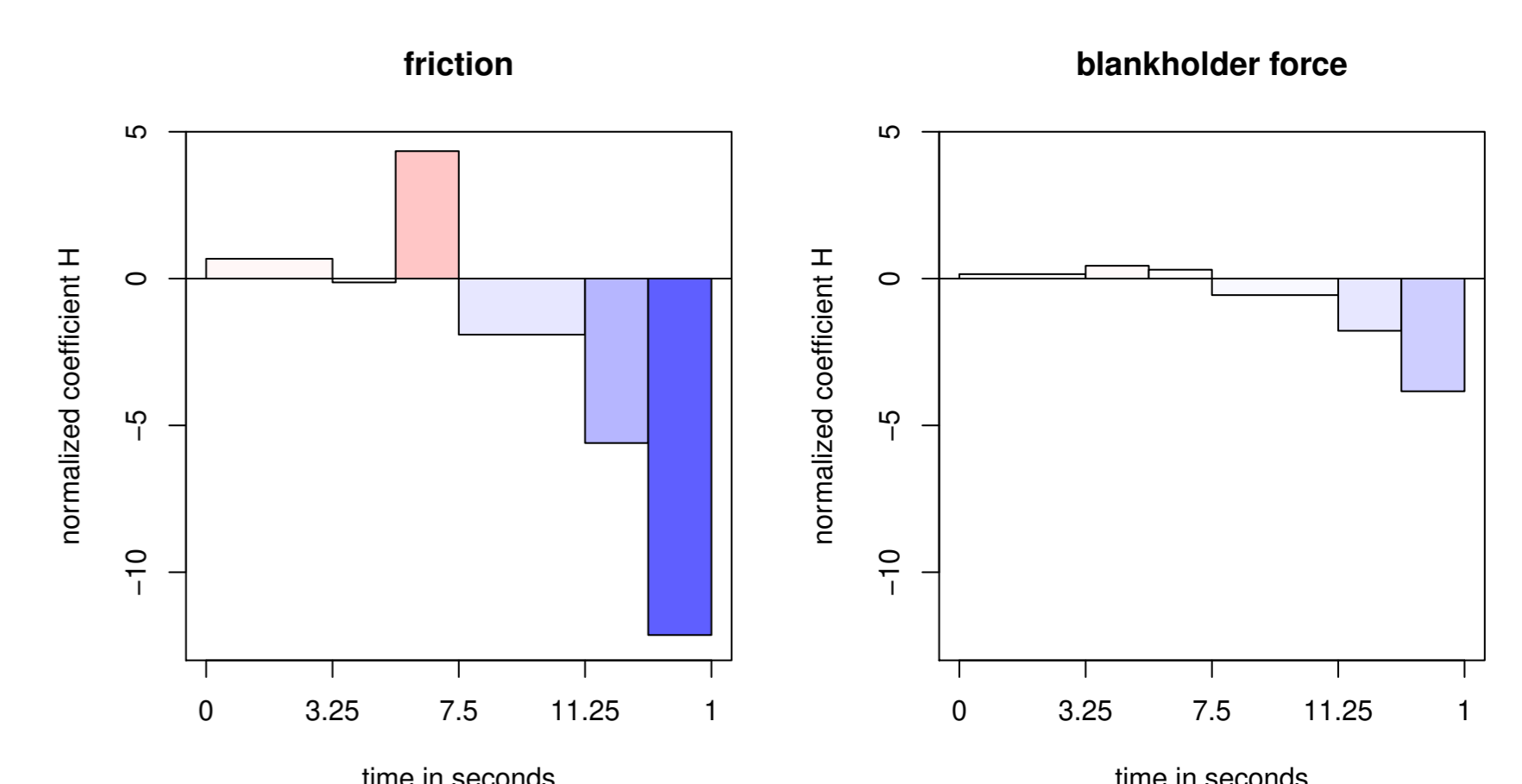
- Stronger influence of friction than of blankholder force
- General: positive influence in first, negative in second half

Step 2: Split all intervals for both inputs



- Last interval has greatest impact
- First and third intervals have small influence

Step 3: Split each second and fourth interval



- Overall for both factors: clear change after half of the time
- Magnitude increases towards the end of both halves