Active Learning of (small) Quantile Sets

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SUR methods for Quantile Set Inversion

Estimation of small Quantile Sets

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Consider an **expensive-to-evaluate** numerical simulator f, with inputs in a set $\mathbb{U} = \mathbb{X} \times \mathbb{S}$:

- $x \in \mathbb{X}$ (deterministic design choices).
- $s \in \mathbb{S}$ (stochastic factors).



For simplicity we assume a deterministic simulator $f : \mathbb{U} = \mathbb{X} \times \mathbb{S} \mapsto \mathbb{R}^q$.

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- ▶ $s \in S$ (stochastic factors).



For simplicity we assume a deterministic simulator $f : \mathbb{U} = \mathbb{X} \times \mathbb{S} \mapsto \mathbb{R}^{q}$.

Given:

- $C \subset \mathbb{R}^q$ a subset of the outputs space \mathbb{R}^q .
- $\alpha \in (0,1)$ a threshold.
- \mathbb{P}_S a known distribution on \mathbb{S} .

We focus on the quantile set inversion (QSI) problem:

Estimate the set of all $x \in \mathbb{X}$ such that

 $\mathbb{P}(f(x,S) \in C) \leq \alpha, \qquad S \sim \mathbb{P}_S.$

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An example: the ROTOR37 compressor model

Function $f : \mathbb{X} \times \mathbb{S} \mapsto \mathbb{R}^3$ with two kind of inputs:

• $x \in \mathbb{X}$: design choice for the compressor

• $s \in \mathbb{S}$: manufacturing uncertainties, with $\mathbb{P}_{S} = \mathcal{U}(\mathbb{S})$.



Simulator return three outputs:

- f_1 : mass flow
- ► f₂: pressure ratio
- ► *f*₃: isentropic efficiency

We can set, for example, $\alpha = 5\%$ and

$$C = \left\{ z \in \mathbb{R}^3 : rac{|z_1 - b_1|}{|b_1|} > 0.175 \quad ext{or} \quad rac{|z_2 - b_2|}{|b_2|} > 0.175
ight\},$$

where b_1 and b_2 are baseline values for the mass flow and pressure ratio of the compressor.

For simplicity, we now assume $f : \mathbb{U} = \mathbb{X} \times \mathbb{S} \mapsto \mathbb{R}$, with $C = (-\infty, T]$.

The problem becomes

Estimate the quantile set:

$$\Gamma(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \leq T) \leq \alpha\}.$$

Remark: With $C = (-\infty, T]$, the problem can be seen in term of quantile of f(x, S). Indeed

$$x \in \Gamma(f) \qquad \Longleftrightarrow \qquad q_{\alpha}(f(x,S)) > T,$$

with $q_{\alpha}(f(x, S))$ the quantile of order α of f(x, S) (with $S \sim \mathbb{P}_{S}$).

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Estimate the quantile set:

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Example of function and associated quantile set, with T = 7.5 and $\alpha = 5\%$.



Figure: Representation of the function.

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Figure: Representation of the function (right), the density of \mathbb{P}_{S} (left)

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Figure: Representation of the function (middle), the density of \mathbb{P}_{S} (left) and associated quantile set (right).

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Figure: Representation of the function (middle), the density of \mathbb{P}_{S} (left) and associated quantile set (right).

Given the expensive-to-evaluate nature of the underlying function, it is necessary to evaluate the function at points chosen with attention.

Active learning (or sequential design of experiments) approach:

Consider

- ▶ $\mathcal{I}_n = \{(u_1, f(u_1)), ..., (u_n, f(u_n))\}$ the current information,
- $a_n(u)$ a sampling criterion dependent on \mathcal{I}_n .

Until satisfied:

• Choose $u \in \mathbb{U}$ as the minimizer (or maximizer) of $a_n(u)$

Evaluate *f* at *u*

• Update information $\mathcal{I}_n \mapsto \mathcal{I}_{n+1}$.

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In the following, we focus on Gaussian processes-based strategies.

Bayesian framework & notations:

 $f \sim \text{GP}$ prior ξ on $\mathbb{U} = \mathbb{X} \times \mathbb{S}$, with constant mean μ and covariance k.



Figure: Illustration of a GP on an interval.

We denote:

▶ \mathbb{P}_n and \mathbb{E}_n : conditional distribution and expectation given \mathcal{I}_n .

• μ_n , σ_n and k_n : posterior mean, st. deviation and covariance of ξ .

▶ $p_n(u) = \mathbb{P}_n(\xi(u) \le T)$: posterior probability that $\{\xi(u) \le T\}$

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First approach: joint-space estimation

The QSI problem is related to the estimation of the excursion set

$$\Lambda(f) = \{u \in \mathbb{U} : f(u) \le T\}$$



Figure: Example function. The black line delimits the set $\Lambda(f)$. $x \in \Gamma(f) \iff \mathbb{P}((x, S) \in \Lambda(f)) \le \alpha$, fixed approximation of $\Lambda(f) \implies$ good approximation of $\Gamma(f)$ SUR methods for Quantile Set Inversion

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Figure: Example function. The black line delimits the set $\Lambda(f)$. $x \in \Gamma(f) \iff \mathbb{P}((x, S) \in \Lambda(f)) \leq \alpha$,

Good approximation of $\Lambda(f) \implies$ good approximation of $\Gamma(f)$

Several Bayesian methods focus on **estimating** $\Lambda(f)$. For example:

- Maximal uncertainty sampling methods:
 - Maximum misclassification probability [Bryan et al. (2005)]:

$$U_{n+1} \in rgmax_{u \in \mathbb{U}} \min(p_n(u), 1 - p_n(u))$$

- ▶ [Ranjan et al. (2008); Echard et al. (2011), ...]
- Stepwise uncertainty reduction (SUR) methods:
 - For instance [Chevalier et al. (2014)] (Joint-SUR):

 $U_{n+1} \in \underset{u \in \mathbb{U}}{\operatorname{argmin}} \mathbb{E}_n(\mathcal{H}_{n+1} \mid U_{n+1} = u)$

with $\mathcal{H}_n = \int_{\mathbb{T}} \min(p_n(u), 1 - p_n(u)) \, \mathrm{d}u$.

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Figure: Examples of designs (red dots) obtained after n = 30 steps with the maximum misclassification and the 'joint-SUR' criteria.

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Figure: Representation of the function (middle), the density of \mathbb{P}_{S} (left) and associated quantile set (right).

Second approach: Focusing directly on $\Gamma(f)$

To estimate $\Gamma(f)$, one only needs to focus on **'interesting parts'** of $\Lambda(f)$.

We denote:

• $\Gamma(\xi)$ the random quantile set associated to ξ .

• $\pi_n(x) = \mathbb{P}_n(x \in \Gamma(\xi))$, the posterior probability that x belongs to the (random) quantile set generated by ξ .

•
$$\mathcal{Q}_n = \int_{\mathbb{X}} \min(\pi_n(x), 1 - \pi_n(x)) \, \mathrm{d}x.$$

QSI-SUR sampling criterion [Ait Abdelmalek-Lomenech et al. (2024)]:

$$(X_{n+1}, S_{n+1}) \in \underset{(x,s)\in\mathbb{X}\times\mathbb{S}}{\operatorname{argmin}} \mathbb{E}_n(\mathcal{Q}_{n+1} \mid (X_{n+1}, S_{n+1}) = (x, s)),$$

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The implementation proposed in [Ait Abdelmalek-Lomenech et al. (2024)] produces good results on moderately difficult examples.



Figure: Median of the proportion of misclassified points vs. number of steps on several examples.

The QSI-SUR criterion focus on part of $\Lambda(f)$ that gives relevant information on $\Gamma(f)$.



Figure: Example of design obtained with the QSI-SUR criterion and the Joint-SUR criterion.

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The QSI-SUR criterion is based on

$$\mathcal{Q}_n = \int_{\mathbb{X}} \min(\pi_n(x), 1 - \pi_n(x)) \, \mathrm{d}x.$$

Two main issues in the implementation:

► First issue: Computational complexity.

- π_n approximated using conditional sample paths of $\xi(x, \cdot)$.
- Complexity is O(m³), where m is the number of points used for the approximation. Due to the Cholesky factorization of the covariance matrix.
- Criterion too expensive for continuous optimization and batch design.

Second issue: Not adapted to "small" $\Gamma(f)$.

- lntegral over X in Q_n is discretized.
- Necessity of points (in \mathbb{X}) close to the boundary of $\Gamma(f)$
- When $\Gamma(f)$ is small, importance sampling can prove insufficient.
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To resolve the issues listed previously, we use a two part solution:

► First issue: Computational complexity

- We introduce a new type of method called "Maximum Expected Estimator Modification" (MEEM).
- We derive a MEEM criterion with complexity $O(m^2)$.
- This criterion allows continuous optimization and batch design of experiments.

Second issue: Not adapted to "small" $\Gamma(f)$.

- ▶ We introduce a sequential Monte Carlo (SMC) framework.
- We estimate a sequence of decreasing quantile sets, converging towards the set of interest.

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Maximum Expected Estimator Modification (MEEM)

Let us consider a sequence of estimators $(\widehat{\Gamma}_n)_n$ such that

 $\widehat{\Gamma}_n$: $\mathcal{I}_n \mapsto \mathcal{P}(\mathbb{X})$,

and a "distance"

 $d : \mathcal{P}(\mathbb{X})^2 \mapsto \mathbb{R}^+.$

MEEM principle: Choose the point that maximize the expected change in the estimation, i.e.

$$U_{n+1} \in \underset{u \in \mathbb{U}}{\operatorname{arg\,max}} \mathbb{E}_n(d(\widehat{\Gamma}_{n+1},\widehat{\Gamma}_n) | U_{n+1} = u)$$

NB: For convenience, we assume a batch size of 1.

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"Duality" SUR / MEEM

Several SUR strategies in the litterature are equivalent to MEEM strategies.

For example:

- Optimization:
 - ► Expected Improvement
 ► MEEM method with d(a, b) = |a b| and estimator f_n^{*} = min{U₁,..., U_n}
- **Function** approximation:
 - ▶ SUR method : $U_{n+1} \in \arg\min \mathbb{E}_n \left(\int_U \sigma_n^2(u) \, \mathrm{d}u \, | \, U_{n+1} = u \right)$.
 - MEEM method with $d(h,g) = \int_{\mathbb{U}} (h(u) g(u))^2 du$ and estimator $f_n = \mu_n$

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MEEM method for QSI

We choose the divergence $d(\widehat{\Gamma}_{n+1},\widehat{\Gamma}_n) = \lambda(\widehat{\Gamma}_{n+1}\Delta\widehat{\Gamma}_n)$ we have

$$d(\widehat{\Gamma}_{n+1},\widehat{\Gamma}_n) = \int_{\mathbb{X}} |\mathbb{1}_{\widehat{\Gamma}_{n+1}}(x) - \mathbb{1}_{\widehat{\Gamma}_n}(x)| \, \mathrm{d}x,$$

coupled with the sequence of plug-in estimators

$$\widehat{\Gamma}_n = \{x \in \mathbb{X} : \mathbb{P}(\mu_n(x, S) \leq T) \leq \alpha\},\$$

We obtain the **QSI-MEEM** strategy:

$$U_{n+1} \in \underset{u \in \mathbb{U}}{\arg\max} \int_{\mathbb{X}} \mathbb{E}_n \left(\left| \mathbb{1}_{\widehat{\Gamma}_{n+1}}(x) - \mathbb{1}_{\widehat{\Gamma}_n}(x) \right| \ \Big| \ U_{n+1} = u \right) \, \mathrm{d}x.$$

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ight) \, \mathrm{d}x.$$

Criterion does not need to be approximated using conditional sample paths of $\boldsymbol{\xi}.$

As a consequence of the kriging update formula, we have:

Proposition

Given \mathcal{I}_n and U_{n+1} , $\widehat{\Gamma}_{n+1}$ is a function of a standard Gaussian variable Z: $\widehat{\Gamma}_{n+1}(z) = \{x \in \mathbb{X} : P(\mu_n(x, S) + \kappa_n(x, S)z \leq T) \leq \alpha\},$ with $\pi_n(x, s) = k(U_{n-1}(x, s))/\pi_n(U_{n-1})$

 \implies Computational complexity of the criterion: O(m^2), with m the number of points (in $X \times S$) used for the approximation.

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Sanity check

We observe that the QSI-MEEM method produces results similar (or better) than the QSI-SUR strategy on case with relatively large quantile sets.



Figure: Median (left) and quantile of order 0.9 of the proportion of misclassified points vs. number of steps, for 100 repetitions of the algorithms on the introductory example.

Second issue: Estimation of small quantile sets

Idea: Multilevel splitting/subset simulation [Kahn and Harris (1951); Au and Beck (2001)] to efficiently sample points in X.

Sequentially estimate a sequence of decreasing quantile sets

$$\Gamma^{0}(f)\supset\Gamma^{1}(f)\supset...\supset\Gamma^{K}(f)=\Gamma(f),$$

using the MEEM strategy described previously.

Such sets can be defined by setting

 $\Gamma^{k}(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \leq T_{k}) \leq \alpha\},\$

with $T_k \leq T_{k+1}$.

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We propose a SMC-based algorithm inspired by BSS [Li (2012); Bect et al. (2017)]

It alternates two distinct phases:

Estimation phase

- Define a new intermediary quantile set to estimate.
- Sample points $U_n, ..., U_{n+r}$ using the MEEM criterion.

Move phase

Concentrate the particles towards the previously estimated set.

For simplicity, we still assume $C = (-\infty, T]$ and a batch size of 1.

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Move phase

Concentrate the particles towards the previously estimated set.

For simplicity, we still assume $C = (-\infty, T]$ and a batch size of 1.

Quantile Set Inversion 00000000

Let
$$q_{n,k}$$
 a density targeting $\Gamma^k(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \in C_k) \le \alpha\}$ at step n .

Estimation phase:

• Set T_{k+1} such that

$$\mathsf{ESS}\left(\frac{\mathbbm{1}_{\widehat{\Gamma}_n^{k+1}}(x)}{\mathbbm{1}_{\widehat{\Gamma}_n^k}(x)}\right) \cong 30\%.$$

Sample point

 $U_{n+1} \in \operatorname{argmax} J_n(u),$

with J_n the MEEM criterion targeting $\Gamma^{k+1}(f)$.



Figure: Temporary quantile set (blue line), final quantile set (green line), particles (blue dots). - n = 0.

Quantile Set Inversion 00000000

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Figure: Temporary quantile set (blue line), final quantile set (green line), particles (blue dots) and projection of the sequential design (red dots). - n = 4.

Let $q_{n,k}$ a density targeting $\Gamma^k(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \leq T_k) \leq \alpha\}$ at step n.

Move phase:

When stopping condition is met:

- Residual resampling.
- Move particles in Γ^{k+1}(f) using MHRW with target density q_{n,k+1}.
- Adapt walk's variance to target acceptation rate 25%.



Figure: Temporary quantile set (blue line), final quantile set (green line), particles (blue dots) and projection of the sequential design (red dots). - n = 5.

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To evaluate the performances of the proposed strategy, we focus on the relative error

 $\frac{\lambda_{\mathbb{X}}(\Gamma(f)\Delta\widehat{\Gamma}_n)}{\lambda_{\mathbb{X}}(\Gamma(f))}$

obtained at the end of the strategy, and the number of steps required to obtain these results.

The functions considered are modeled by a GP with constant mean and Matern covariance kernel (with $\nu \in \{1/2, 3/2, 5/2, +\infty\}$).

Covariance parameters are estimated at each step using ReML.

Each strategy is repeated 50 times, with different maximin LHS initial designs.

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1st example: 5-Trid function [Adorio and U.P. (2005)]

$$\blacktriangleright~\mathbb{U}=\mathbb{X}\times\mathbb{S}$$
 with $\mathbb{X}=[-25,25]^3$ and $\mathbb{S}=[-25,25]^2$,

$$\blacktriangleright \mathbb{P}_{S} = \mathcal{U}(\mathbb{S})$$

•
$$\alpha = 5\%$$
 and $C = [1098.5, +\infty)$

• Relative size of $\Gamma(f)$: $\lambda_{\mathbb{X}}(\Gamma(f)) \sim 10^{-6}$.

$$f(u) = \sum_{i=1}^{5} (u_i - 1)^2 - \sum_{i=2}^{5} u_i u_{i-1}$$

Size of the initial design: 50.

Conclusion 00



Figure: Distribution of the relative error (top) and the number of steps (bottom), for different batch size (left to right: 1, 2, 3). - (50 runs)

2nd example: OTL circuit function [E. N. and D. M. (2007)]

- $\blacktriangleright \ \mathbb{U} = \mathbb{X} \times \mathbb{S}$
- $\blacktriangleright \ \mathbb{X} = [-50, 150] \times [25, 70] \times [0.5, 3] \times [1.2, 2.5] \times [0.25, 1.2]$
- ▶ \$ = [-50, 300],
- $\blacktriangleright \mathbb{P}_{S} = trunc\mathcal{N}(175, 50)$
- $\alpha = 5\%$ and $C = [2.65, +\infty)$
- ► Relative size of Γ(f): λ_X(Γ(f)) ~ 10⁻⁷.

f(x, s) represents the midpoint voltage of a circuit given the choice of resistances designs x and the current gain s.

Size of the initial design: 60.

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Figure: Distribution of the relative error (top) and the number of steps (bottom), for different batch size (left to right: 1, 2, 3). - (50 runs).

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3rd example: ROTOR37 model [Reid and Moore (1978)]

Gaussian metamodel (provided by S. Da Veiga and SafranTech) of the ROTOR37 compressor model.

The function $f : \mathbb{X} \times \mathbb{S} \mapsto \mathbb{R}^3$ takes two kind of inputs:

- $x \in \mathbb{X} = [0, 1]^{13}$: design choice for the compressor
- $s \in \mathbb{S} = [0,1]^5$: manufacturing uncertainties $(\mathbb{P}_S = \mathcal{U}(\mathbb{S}))$



Simulator returns three outputs:

- f_1 : the mass flow
- f_2 : the pressure ratio
- ► *f*₃: the isentropic efficiency

Goal: finding the set of determinisitic design choice leading to values of the mass flow and pressure ratio being close to baselines values (b_1, b_2) with sufficiently high probability.

We consider:

•
$$C = \left\{ z \in \mathbb{R}^3 : \frac{|z_1 - b_1|}{|b_1|} > 0.175 \text{ or } \frac{|z_2 - b_2|}{|b_2|} > 0.175 \right\}$$

• $\alpha = 5\%$

Relative size of $\Gamma(f)$: $\lambda_{\mathbb{X}}(\Gamma(f)) \sim 10^{-8}$

We model the different outputs using independant GPs.

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Relative size of $\Gamma(f)$: $\lambda_{\mathbb{X}}(\Gamma(f)) \sim 10^{-8}$

We model the different outputs using independant GPs.

We start the strategy from an initial design of size 90. A batch size of 5 is used.



Figure: Distribution of the relative error (left) and the number of steps (right), for a batch size of 5. - (50 runs).

Conclusion:

- Introducing the concept of MEEM allows to reproduce (or improve) the results obtained by using the QSI-SUR criterion on moderately difficult examples.
- The MEEM criterion permits a welcomed gain regarding the computational complexity, due to the absence of conditional Gaussian sample paths
- Coupled with a SMC framework, the criterion allows to accurately estimate small quantile sets (size of order $10^{-6} 10^{-8}$).

Future research might be dedicated to treating cases where $\alpha \sim 0$.

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Thank you for your attention!

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The second part (QSI-MEEM criterion) is based on:

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Choice of the target densities:

Natural idea (in the spirit of [Dubourg et al. (2013); Bect et al. (2017)]):

$$q_{n,k}(x) \propto \pi_n^k(x) = \mathbb{P}_n(x \in \Gamma^k(\xi))$$

Does not admit a closed-form expression.

Expensive to estimate.

Idea: Replace $\pi_n^k(x)$ by $\mathbb{1}(x \in \Gamma_{n,k}^+)$. How to define $\Gamma_{n,k}^+$?

Given $x_0 \in \mathbb{X}$, μ_n and σ_n the posterior mean and standard deviation of ξ and $\beta \in (1/2, 1)$, consider the **quantile function**:

$$\xi_n^+(x_0,\cdot) = \mu_n(x_0,\cdot) + \Phi^{-1}(\beta)\sigma_n(x_0,\cdot),$$

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 $\mathcal{C} = (-\infty, \mathcal{T}]$ and $\xi(x_0, \cdot)$ is a high quantile

▶ $\mathbb{P}(\xi_n^+(x_0, S) \in C_k)$ is an optimistic estimation of the probability of failure at point x_0 .



Figure: Example of quantile function $\xi_n^+(x_0, \cdot)$, with a fixed x_0 . Setting $\Gamma_{n,k}^+ = \Gamma_n^k(\xi_n^+)$ eliminates x_0 if $\{x_0 \in \Gamma^k(\xi)\}$ is very improbable. We define the target densities as

$$q_{n,k}(x) \propto \mathbb{1}(x \in \Gamma_n^k(\xi_n^+))$$

NB: The MHRW step becomes a constrained random walk.

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